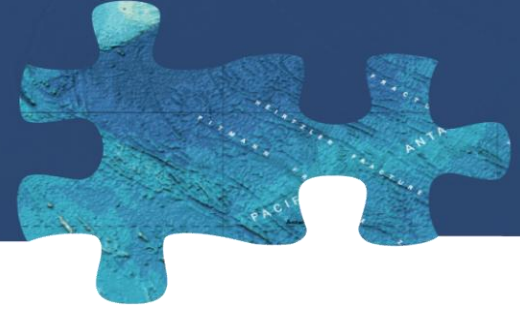


# Seabed 2030



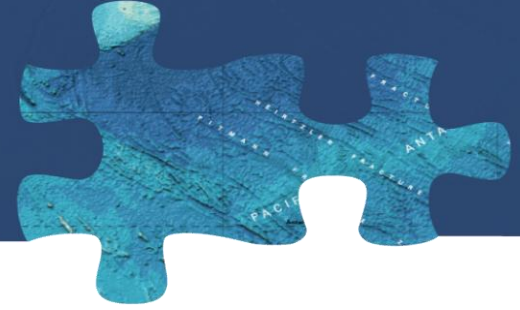
## The Seabed 2030 Base Line

*“The mapped portion of the World Ocean in GEBCO\_2014 considering the Seabed 2030 mapping resolution target based on depths”*

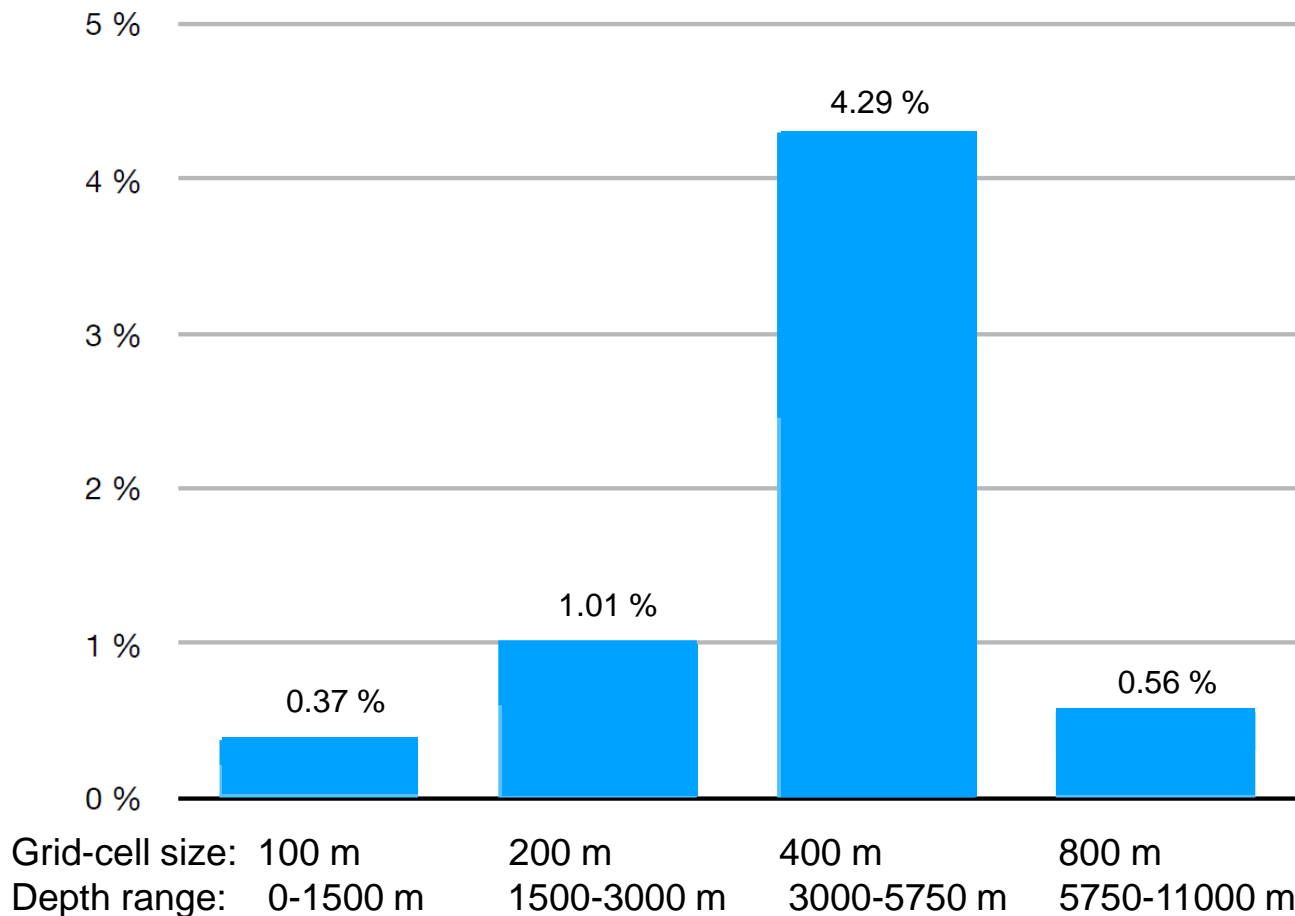
### *Presentation outline:*

1. **Summary statistics:** *Mapped portion of the World Ocean in GEBCO\_2014 at Seabed 2030 resolution targets*
2. **Methods:** *Calculation of the statistics*
3. **Background and explanations:**
  - Seabed 2030 depth-dependent mapping resolution target*
  - Calculation of the mapped portion in GEBCO\_2014*
  - Why the grid cell size resolution matters when calculating how much of the World Ocean is mapped*

# Summary statistics



**Summary:** ~6 % of the World Ocean was mapped in the GEBCO\_2014 grid considering the Seabed 2030 grid cell resolution target at different depth intervals



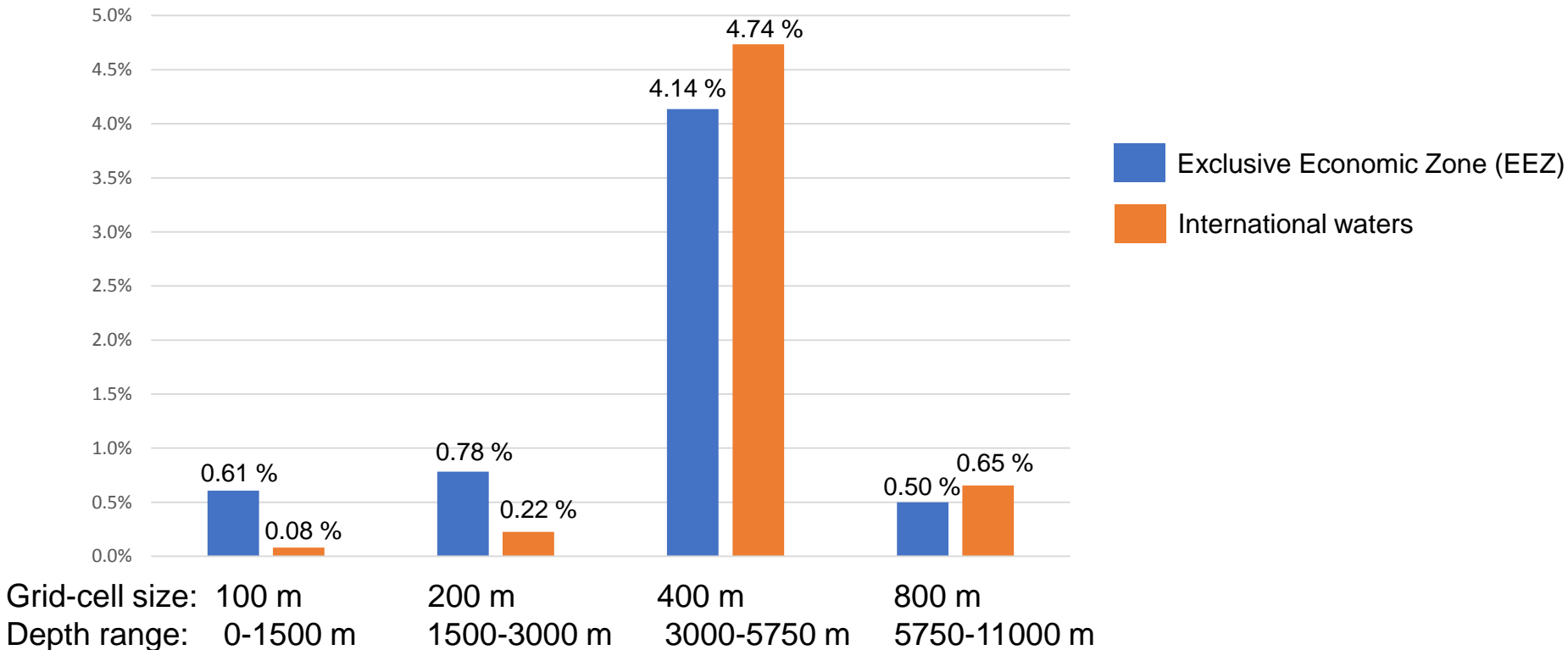
# Summary statistics

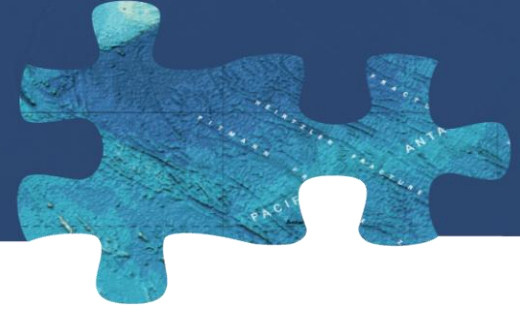


**Summary: 6.0/5.7 %** of the EEZ/International waters was mapped in the GEBCO\_2014 grid considering the Seabed 2030 grid cell resolution target at different depth intervals.

(This calculation does not make a distinction of an EEZ for Antarctic waters, all data in Antarctic waters are considered to be outside countries EEZs.)

Mapper portions of EEZ and International waters (%)



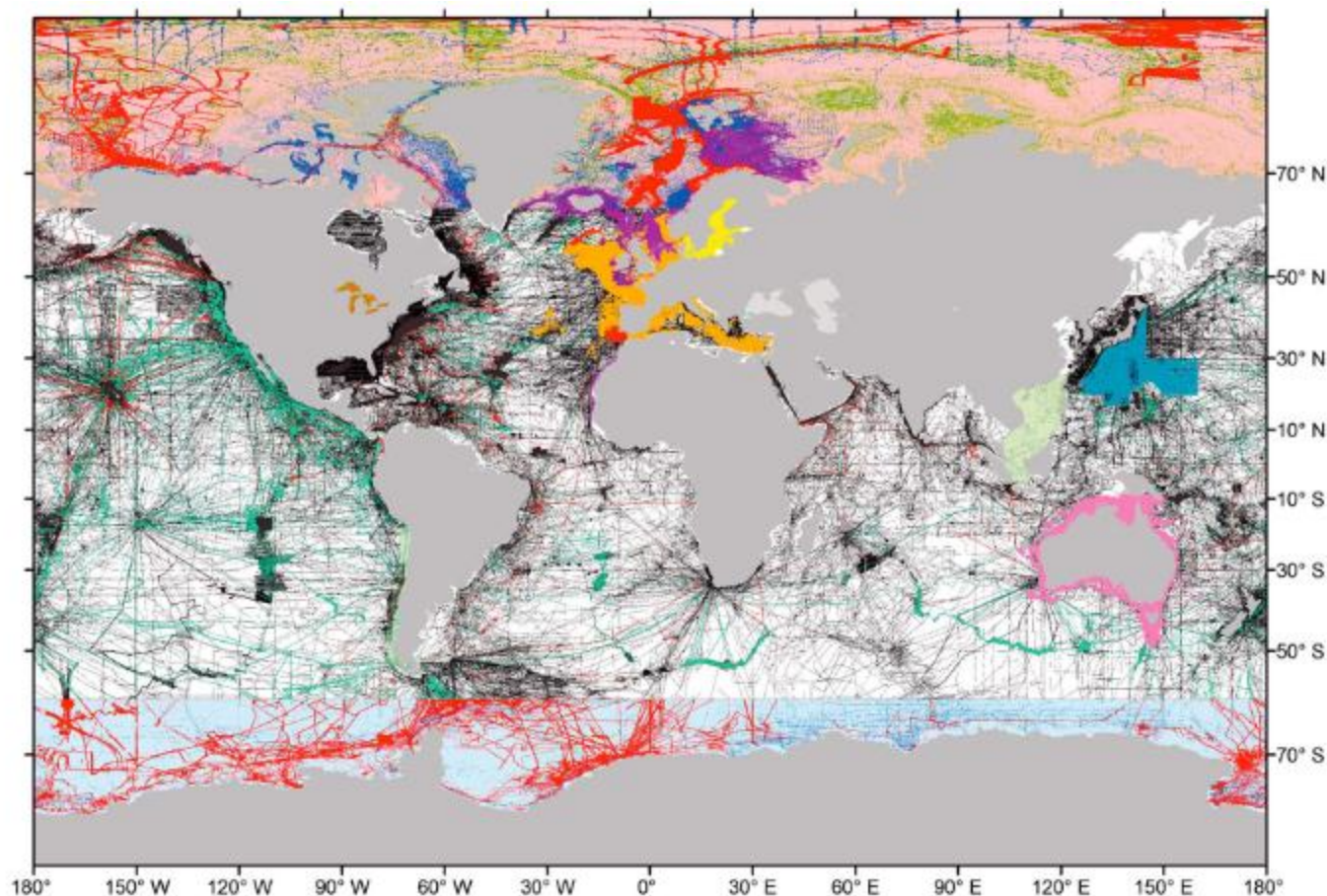


## Calculation of the statistics

# Calculation of the statistics



- All measured depths (multibeam, single beam, spot soundings) that were used to create GEBCO\_2014 were included in the statistics.
- Contributed grids were included in the statistics where the underlying data not is available. This will overestimate the mapped portion
- Digitized nodes from depth contour maps are excluded from the statistics
- International waters implies the area outside of countries' EEZ (Exclusive Economic Zone).
- Antarctica is not considered to have an EEZ in our calculations of mapped portion of EEZ respective International waters.
- All calculations are based on counting grid cells filled with data in proportion to the total amount of grid cells covering the World ocean. The size of the grid cells are varied depending on the Seabed 2030 resolution target.
- IBCAO (64-90 N) and IBCSO (60-90 S) were calculated on a Polar Stereographic projection while the in-between region was calculated directly on WGS 84.



- Region taken from IBCAO V3
- Region taken from IBCSO V1
- EMODNet 2013
- Baltic Sea Bathymetry Database
- Geoscience Australia Grid 2009
- JHOD grid
- Olex AS data

- LDEO Global Multi-Resolution Topography Synthesis
- Multibeam bathymetry
- Single beam bathymetry
- Bathymetric contours from charts
- North American Great Lakes bathymetry
- Coastal area updated using ENC soundings
- Regions based on pre-prepared grids, (first included in the GEBCO\_08 Grid)

- Trackline control information from the SRTM30\_plus (v5) base grid

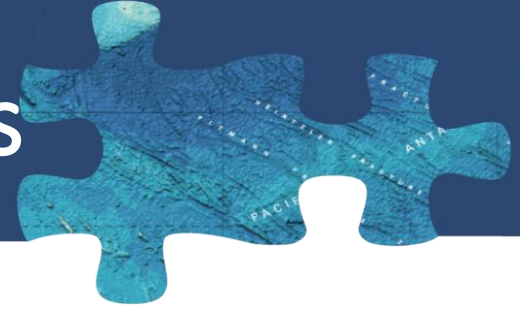
- Region based on interpolation guided by satellite-derived gravity data within the SRTM30\_plus (v5) base grid

Excluded from statistics

All interpolated depths are excluded from statistics

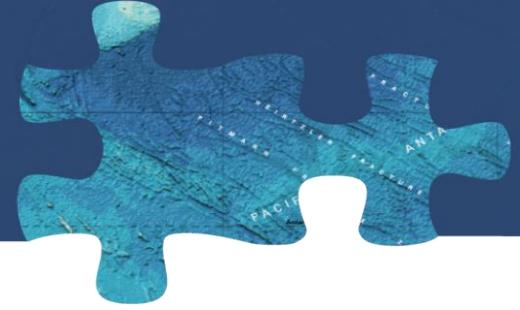


# Calculation of the statistics



## Technical procedure

1. Collate all input data in three columns (x-coordinate, y-coordinate and depth value)
2. Pick one depth value per grid cell that has values by choosing the median depth using GMT blockmedian for all input data and for four resolutions (100 m, 200 m, 400 m and 800 m)
3. Split all data into a number (9–25) of sub regions (in order to fit into the computer memory) and make grid files
4. Resample the coarser resolutions to the highest resolution 100 x 100 m/3.2'' x 3.2''
5. Filter all data to each Seabed depth range for corresponding resolution (Polar areas/mid latitudes)
  - 100 m/3.2'' 0–1500 m
  - 200 m/6.5'' m 1500–3000 m
  - 400 m/13'' 3000–5750 m
  - 800 m/26'' 5750– m
6. Make a composite grid with all depth ranges in order to avoid edge overlaps
7. Mask data inside EEZ
8. Count data points inside and outside of EEZ



# Background and explanations



# *Seabed 2030 depth-dependent mapping resolution target*

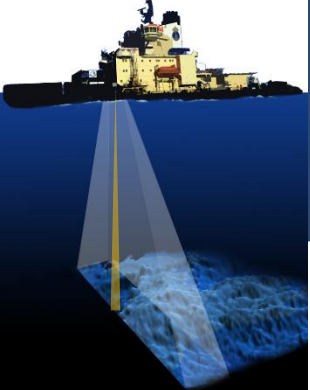


The diagram illustrates three different mapping scenarios for the Seabed 2030 project. In the upper left, a satellite in space emits a wide, yellow, cone-shaped beam of light down to the ocean surface. In the center, a large research vessel is shown on the water's surface, with a narrower yellow beam of light extending from its hull down to the seabed. In the lower right, a small autonomous underwater vehicle (AUV) is shown near the seabed, emitting a very narrow yellow beam of light. The seabed is depicted with a 3D topographic map showing various depths and features. The background consists of a blue sky with white clouds and a blue ocean surface.

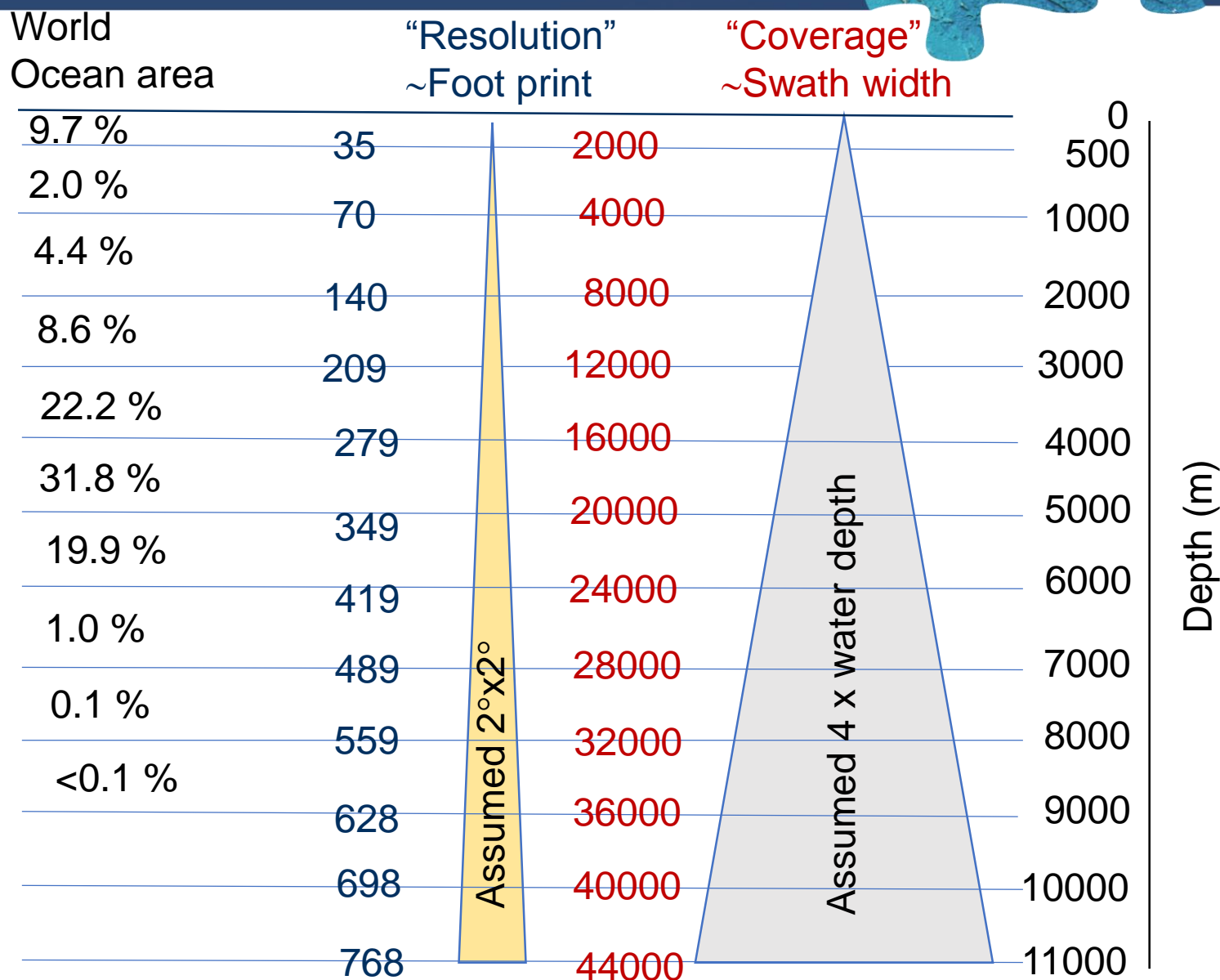
Horizontal resolution: ~1 km

(1°x1° deep-water multibeam)  
Horizontal resolution: ~60 m  
Swath width: 14-17 km

(1°x1° high-res multibeam)  
Horizontal resolution: < 5 m  
Swath width: <500 m

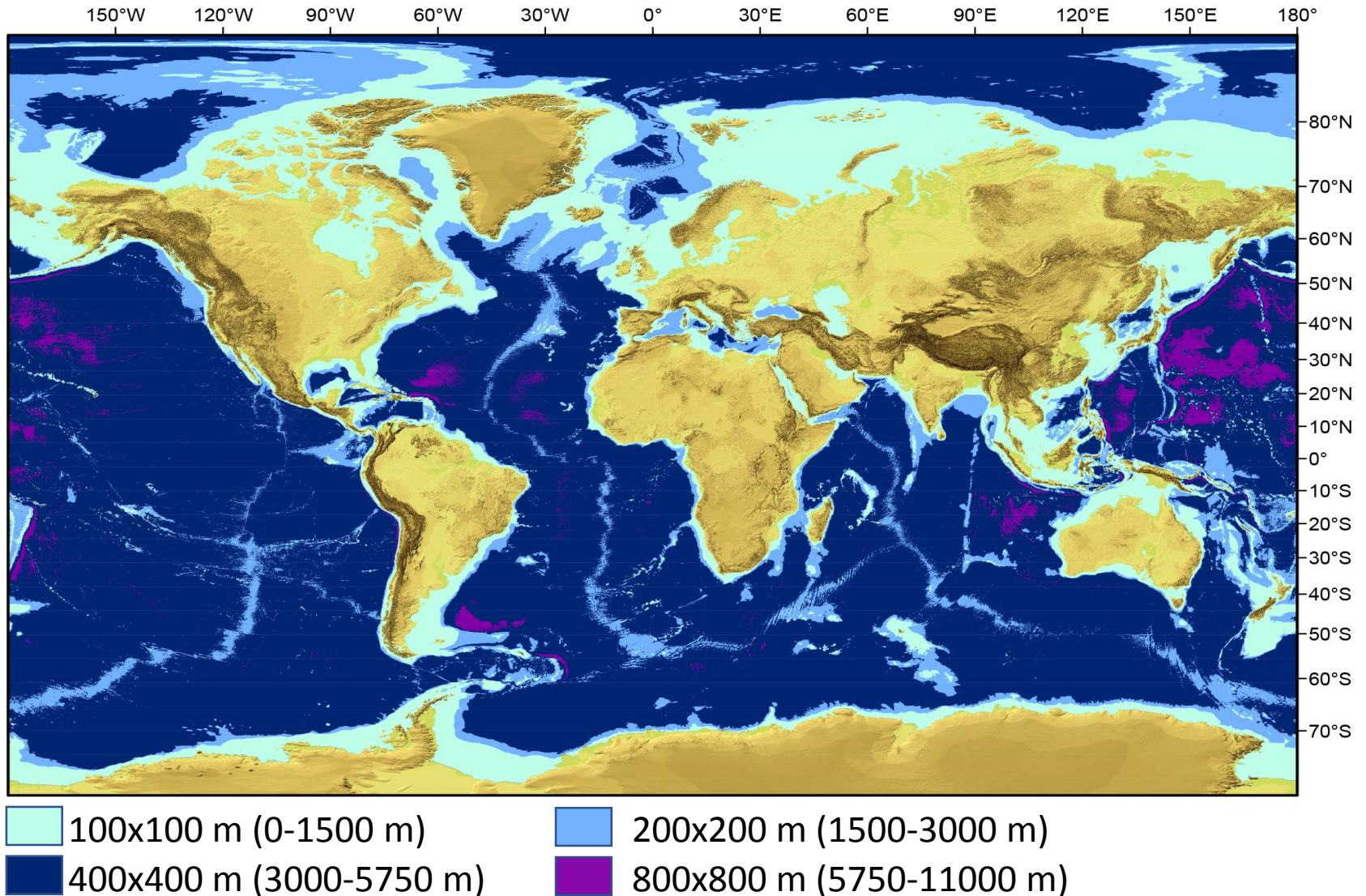
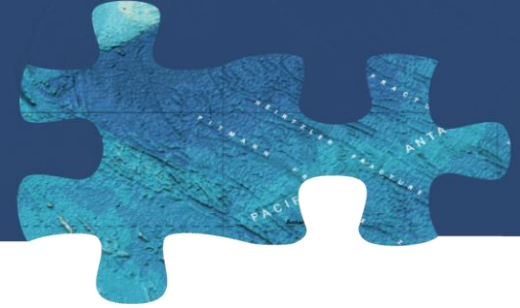


# Mapping with surface vessel, deep water multibeam (12 kHz 2°x 2°, 60 ° from nadir)





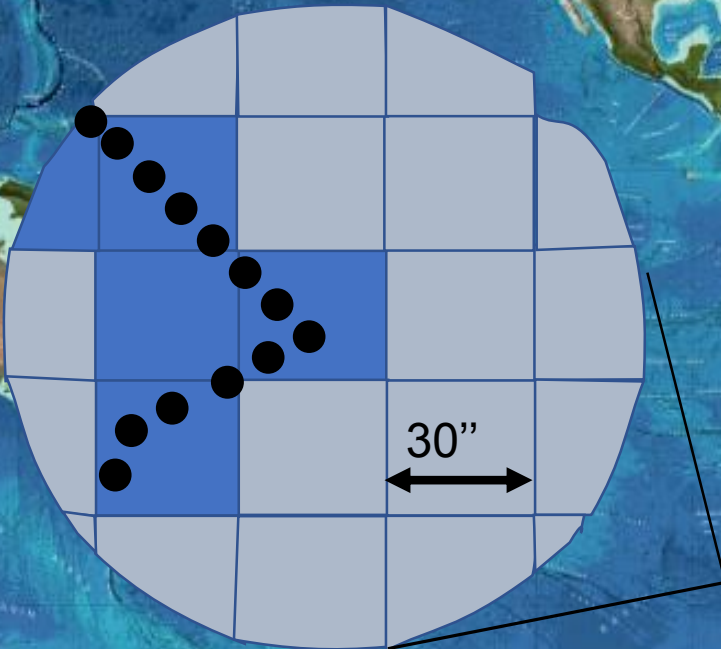
# Seabed 2030 grid-cell size at different depths





# How was the calculation of the mapped portion in GEBCO\_2014 originally done?

Of the GEBCO\_2014 grid cells, sized 30"x30" arc seconds (ca 1x1 km), 18 % of them have depth values.



# Estimates of the mapped portion of the world ocean vary based on the grid resolution used



***The higher grid resolution we aim for, the smaller portion of the World Ocean have been mapped!***

18 % mapped

GEBCO\_2014 (grid cell size 30"x30", ca 1000x1000 m)

6 % mapped

Seabed 2030 variable grid resolution

