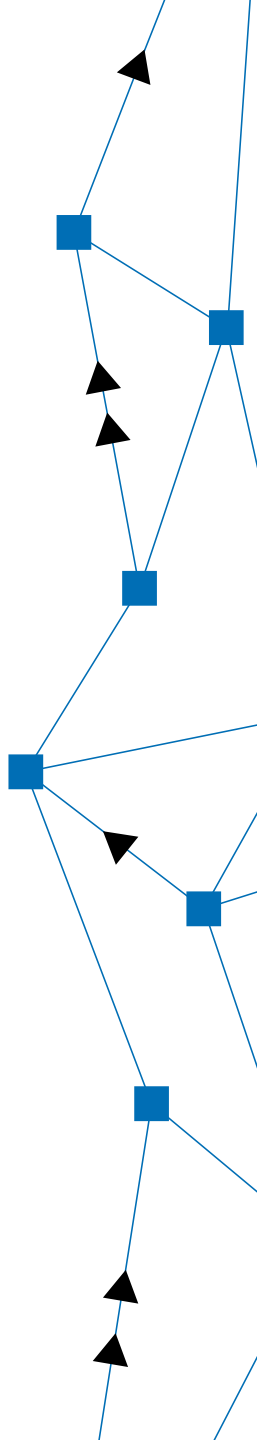


PHOTOGRAMMETRY AND LIDAR: COMPARISON OF TWO METHODS FOR VESSEL COORDINATE SURVEY (VCS)

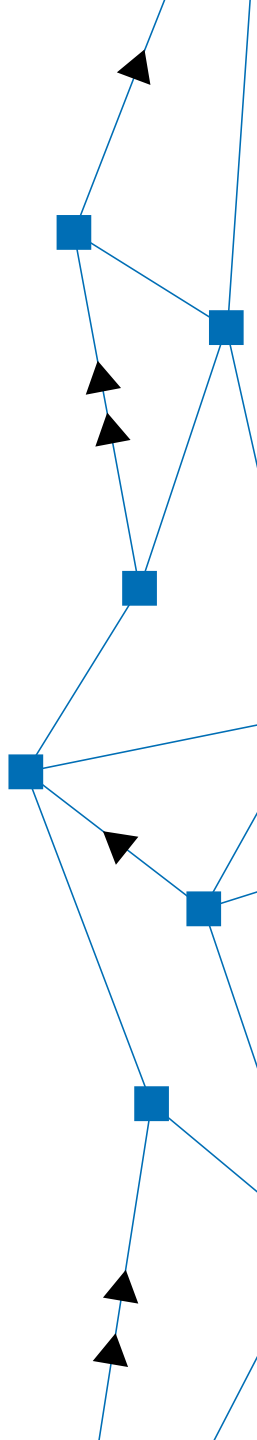
INTRODUCTION

- The goal of this work was to test two methods for vessel coordinate survey (VCS).
- Two vessels were surveyed, and results compared with each other and previous offsets.
- Conclusions were made about which method to prefer considering possible limitations



TOPICS

- Hydrographic survey error budget
- How to reduce errors
- Methods for VCS
- Performed tasks
 1. preparations
 2. survey
 3. data processing
- Results and conclusions




MULTIBEAM SURVEY ERROR BUDGET

Horizontal uncertainty

- GNSS horizontal accuracy
- Antenna lever arm
- Raytracing error
- HRP error
- VCS error

Vertical uncertainty

- GNSS vertical accuracy
 - Depth error
 - Raytracing error
 - HRP error
 - VCS error
 - Sound velocity error
 - Tide error
 - Vessel draft error
- 

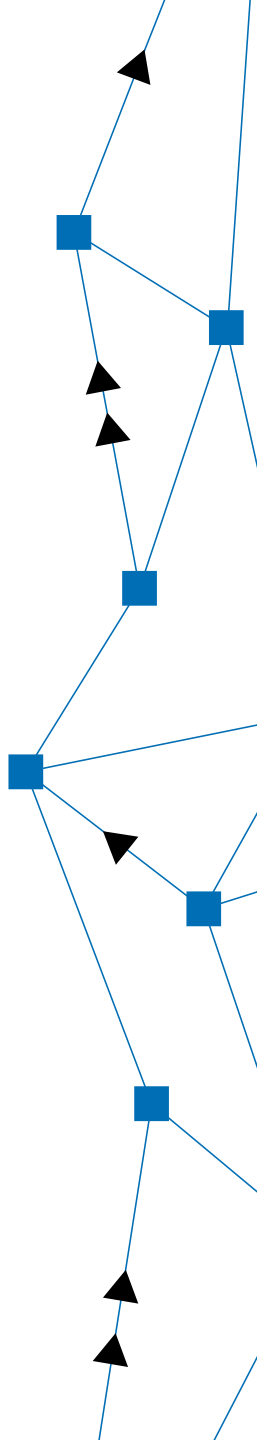
Modern methods for vessel coordinate survey

- Total station
- 3D LIDAR scanning
- Photogrammetry



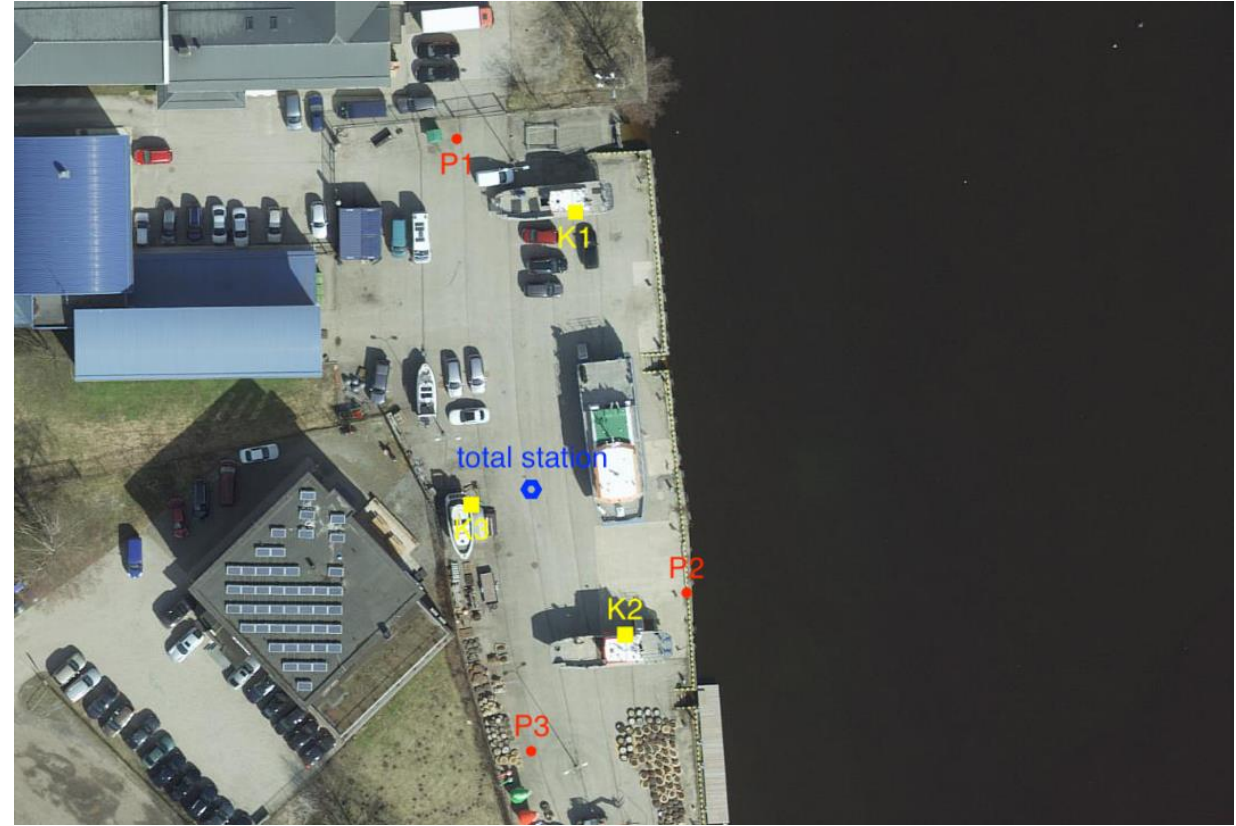
PERFORMED TASKS

1. Preparations
2. 3D scanning
3. Drone photogrammetry
4. Data processing





• EVA-320



• EVA-301

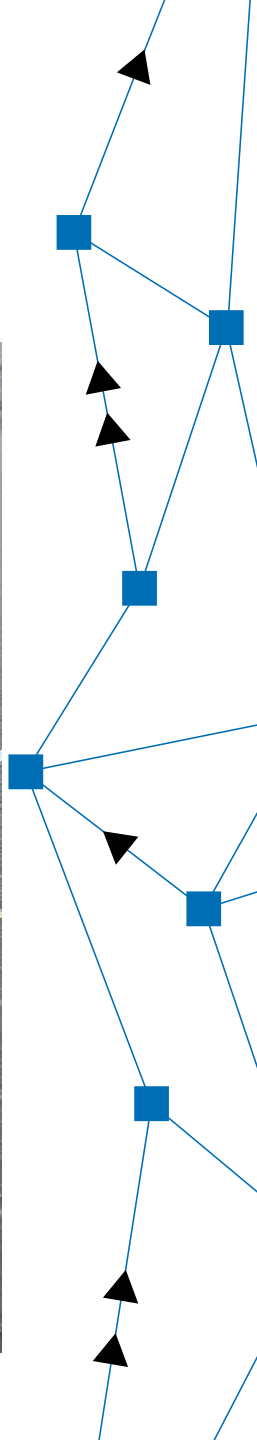
PREPARATIONS



Photogrammetry

DJI Phantom 4 RTK

DJI Mini SE

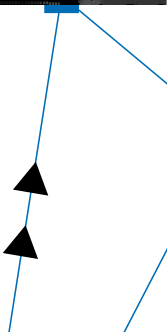
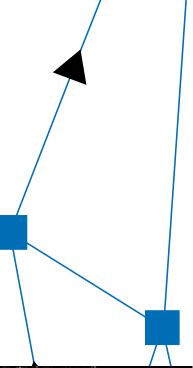
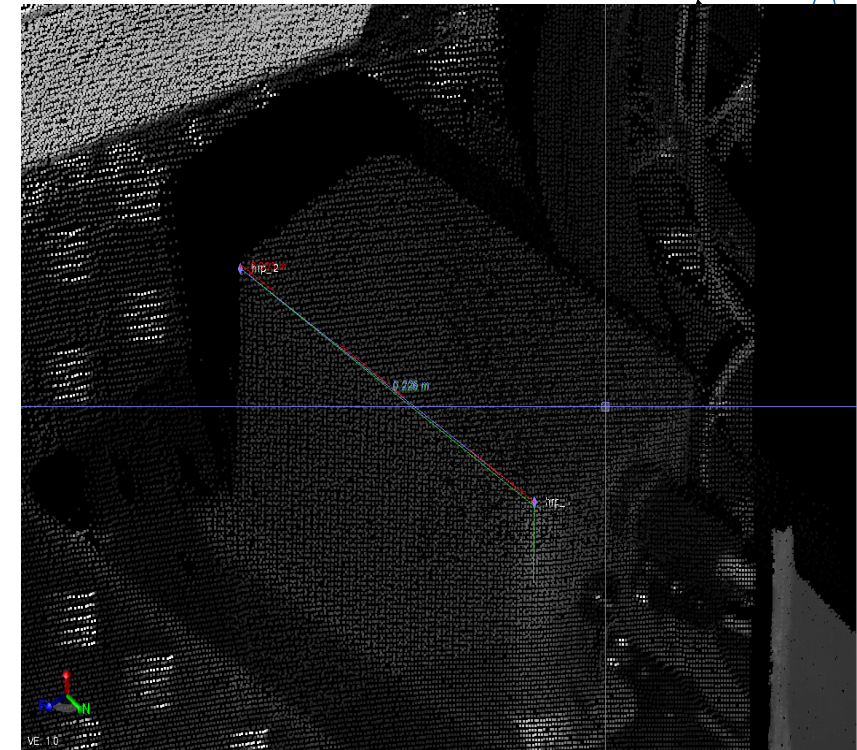
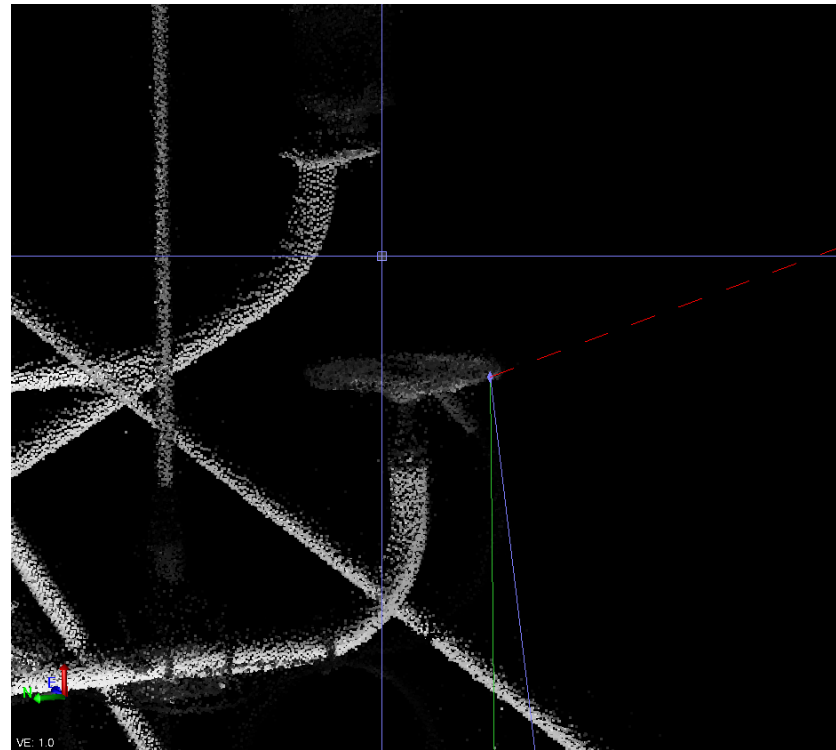
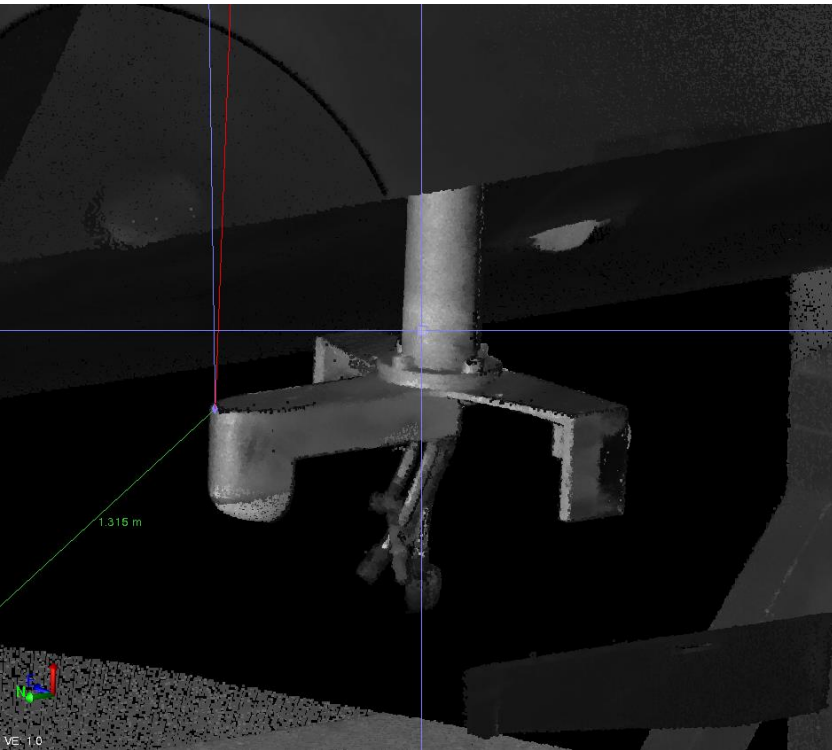




Stationary 3D LIDAR scanner – Trimble X7



Data processing

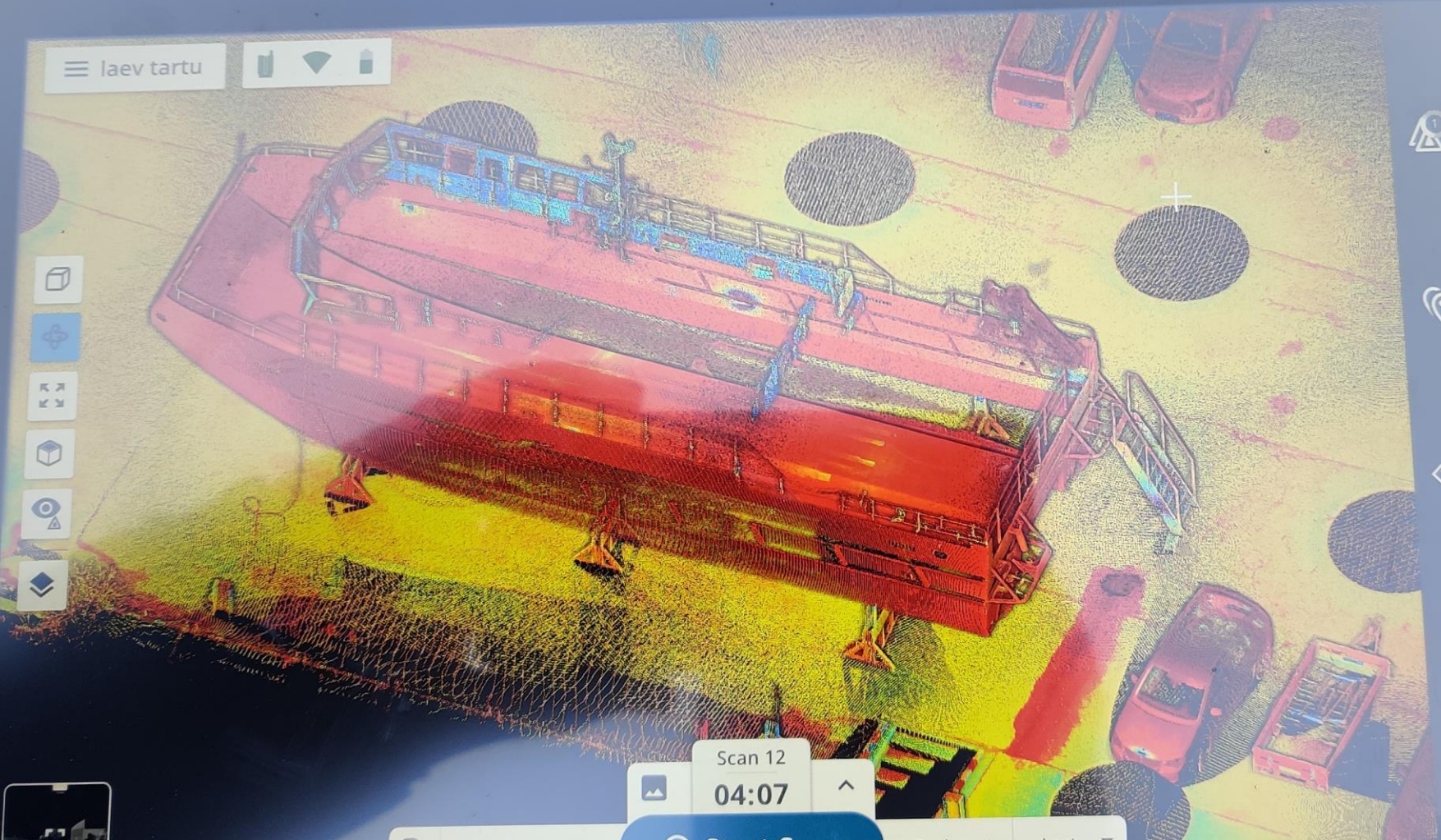


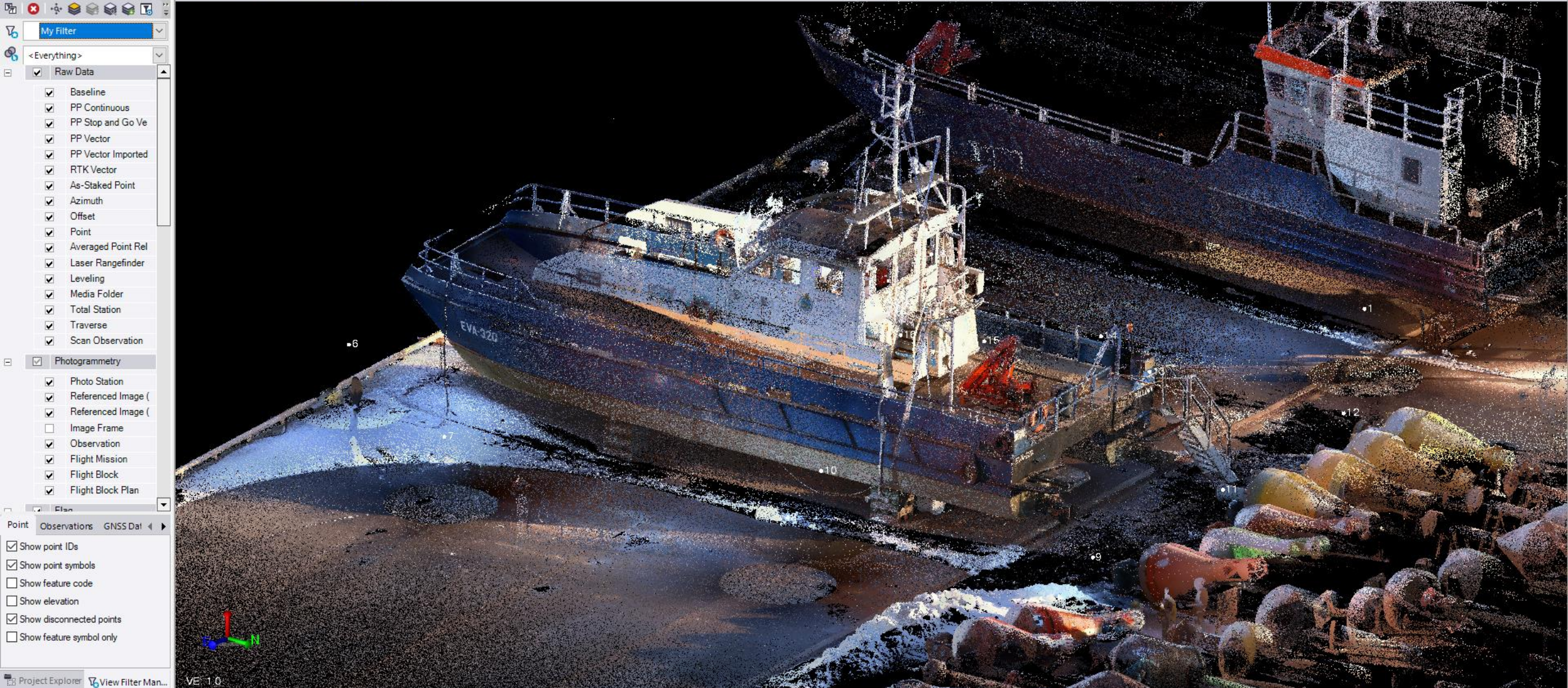
laev tartu



Scan 12

04:07





- My Filter
- <Everything>
- Raw Data
 - Baseline
 - PP Continuous
 - PP Stop and Go Ve
 - PP Vector
 - PP Vector Imported
 - RTK Vector
 - As-Staked Point
 - Azimuth
 - Offset
 - Point
 - Averaged Point Rel
 - Laser Rangefinder
 - Leveling
 - Media Folder
 - Total Station
 - Traverse
 - Scan Observation
 - Photogrammetry
 - Photo Station
 - Referenced Image (
 - Referenced Image (
 - Image Frame
 - Observation
 - Flight Mission
 - Flight Block
 - Flight Block Plan
- Point Observations GNSS Dal
- Show point IDs
 - Show point symbols
 - Show feature code
 - Show elevation
 - Show disconnected points
 - Show feature symbol only

RESULTS

- 3D scanning

1. EVA-320

X offset – 3,795 m

Y offset – 0,903 m

Z offset – 9,395 m

HRP offset - 0° 45' 6"

2. EVA-301

X offset – 0,817 m

Y offset – 1,047 m

Z offset – 6,180 m

HRP offset – 0° 1' 24"

- Photogrammetry

1. EVA-320

X offset – 3,83 m

Y offset – 0,898 m

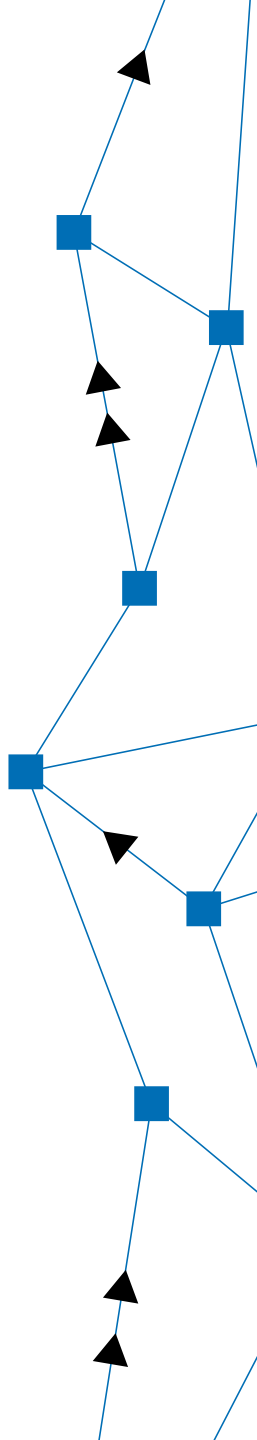
Z offset – 9,397 m

2. EVA-301

X offset – ...

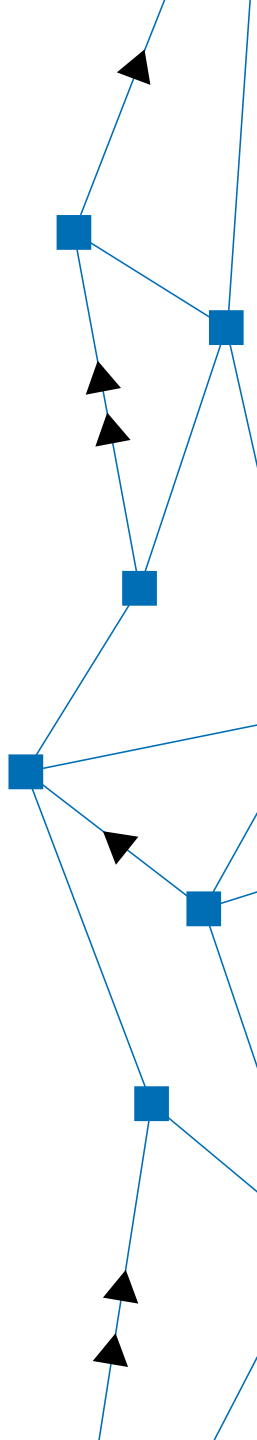
Y offset – ...

Z offset – ...



RESULTS

	3D scanning	Photogrammetry
Relative precision	✓	✓
Relative simplicity	✓	✗
Practical usability	✓	✗
Instruments cost	✗	✓
Survey time	✗	✓
Data processing time	✓	✗
Min required personnel	✓	✓
Dependence on the weather	✓	✗
Unexpected restrictions	✓	✗





THANK YOU FOR ATTENTION!