

# **Shallow Water Hydrographic Survey Project in the Baltic Sea Using a Combination of MBES and Bathymetric LiDAR**

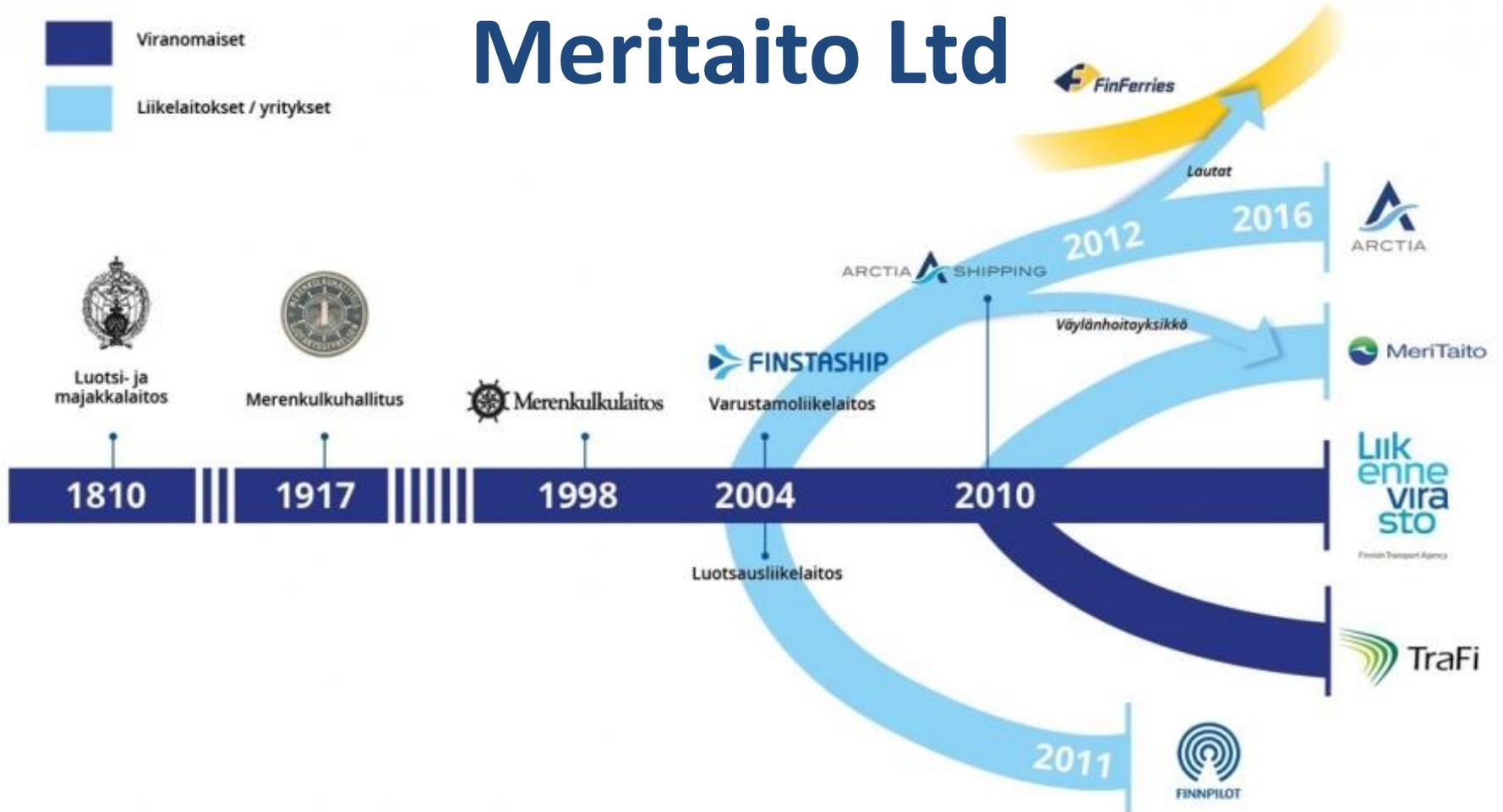
**Jani Pötrönen  
Survey Manager  
Meritaito Ltd**



# Agenda

- **Short introduction to Meritaito Ltd (part of Arctia Group since 12/2018)**
- **Combination of MBES and bathymetric lidar surveys**
- **Experience of bathymetric lidar data in the Baltic Sea**

# Meritaito Ltd



- Fairway Maintenance
- Marine Constructions
- Canals
- Marine Surveys

- Fairway Design
- Oil Spill Response
- Aids to Navigation

# Meritaito Ltd

- **Project experience with Hydrographic Offices**
  - Mareano2016 for NHS at the Barents Sea
  - ODIN No2 in 2017 and No5 in 2018 for SMA at the Baltic Sea
  - CHP Surveys for MCA in UK Waters started 2018
    - Up to three ASVs used for IHO Order 1A surveys in Scotland and East Coast of UK
  - **Several projects with current TrafiCom**
    - Three combined MBES and Bathymetry Lidar projects since 2017 in Finnish TW

# Combination of MBES and bathymetric lidar surveys

- Experience from three projects with FTA
- Important to combine two methods to gain best end results for the Client
  - Push contractor to pay attention to lidar survey achievement with overall responsibility of data coverage

# Survey Overview

- **Flight Altitude 450m**
- **Flight speed 65m/s or 126knots**
- **200% coverage**
  - 60% overlap
    - Including 10% safety factor for roll/off track errors
- **System used HawkEye 4X**
  - Topo, Shallow and Deep sensors

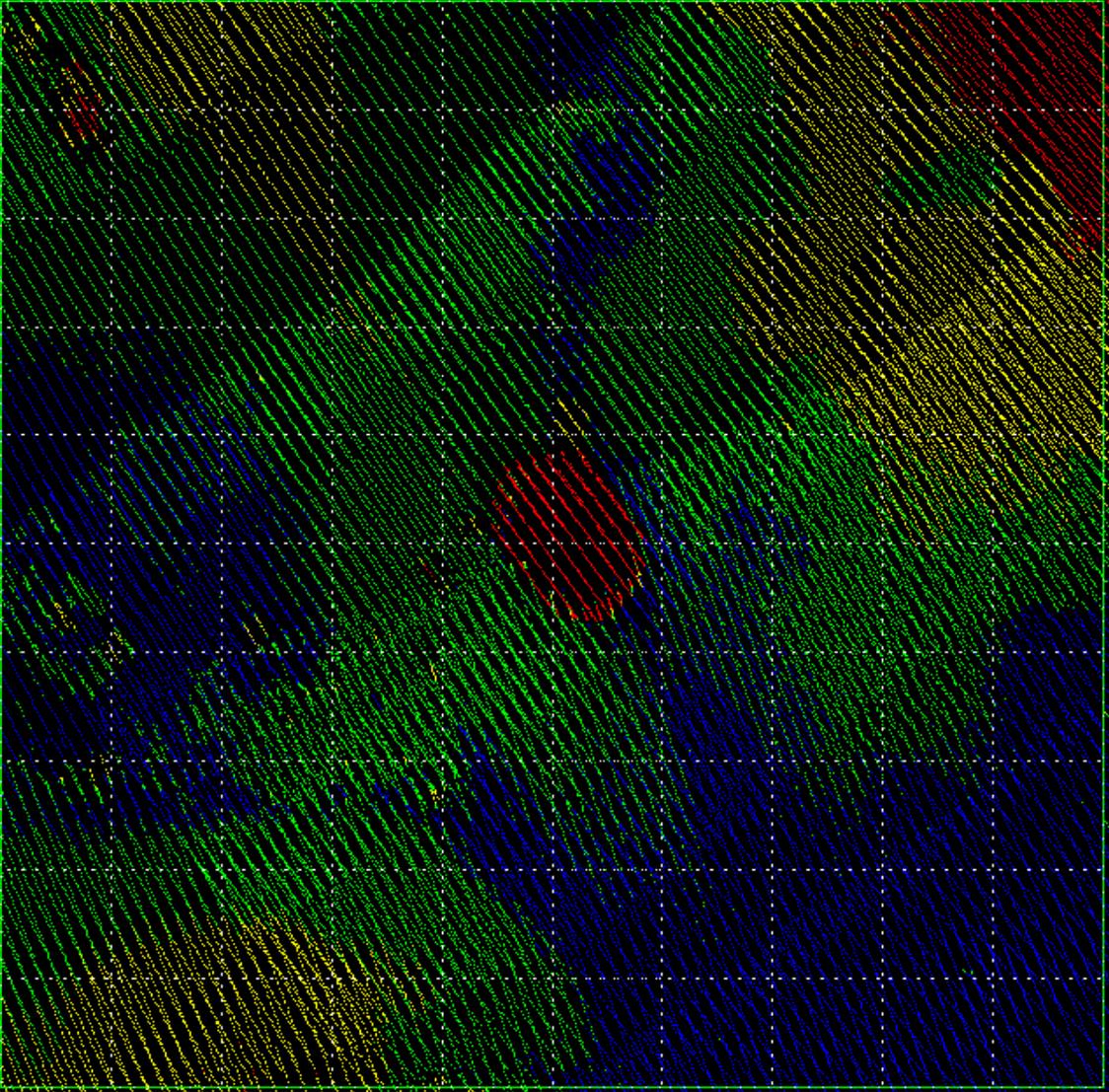


- **Secchi depths in the project area varies from 3 to 6 meters**
  - Lidar penetration down to 11m

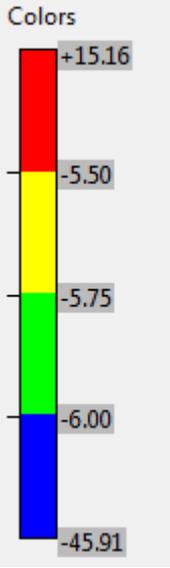
# POINT DENSITY

# MBES Area 1

20m



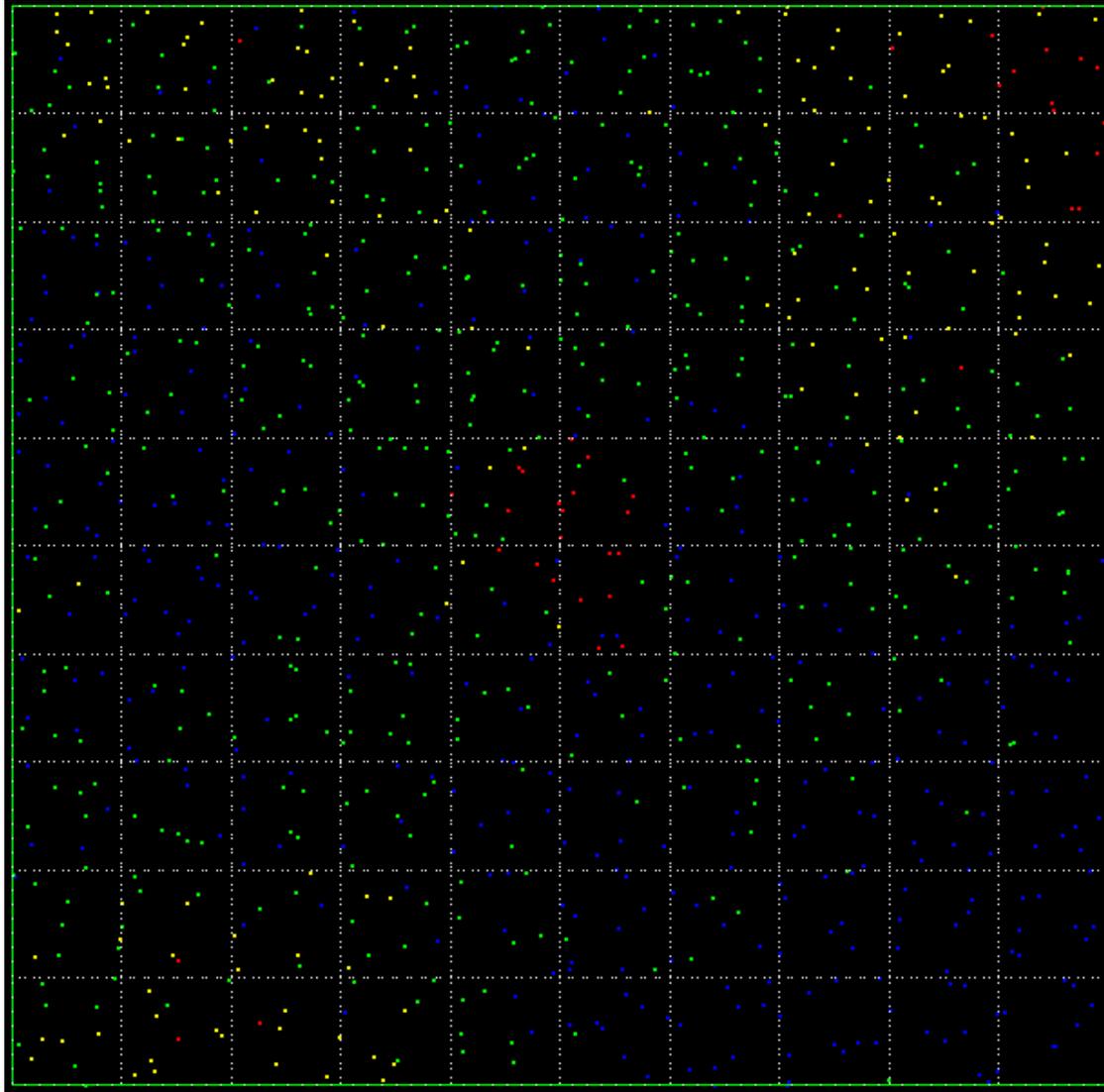
20m



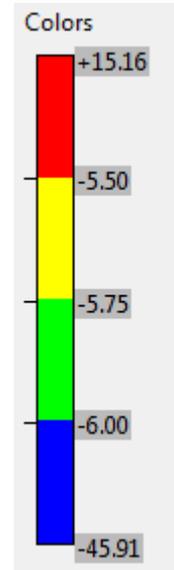
DEPTHS 4-10 m

# LiDAR standard 100% coverage

20m



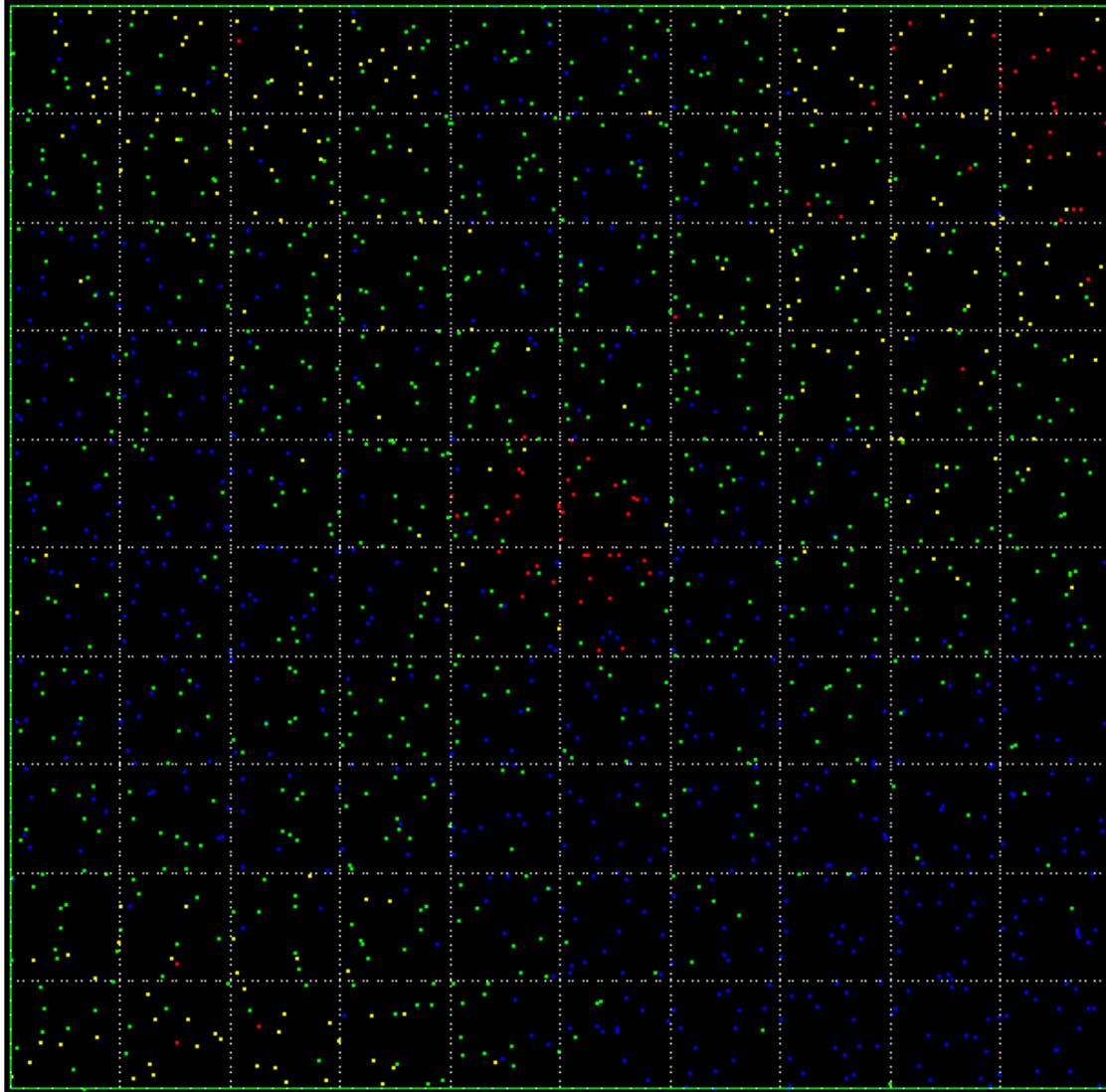
20m



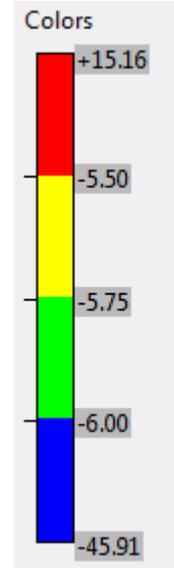
Average (20m\*20m area)  
point density  
2.490/m<sup>2</sup>

# LiDAR standard 200% coverage

20m



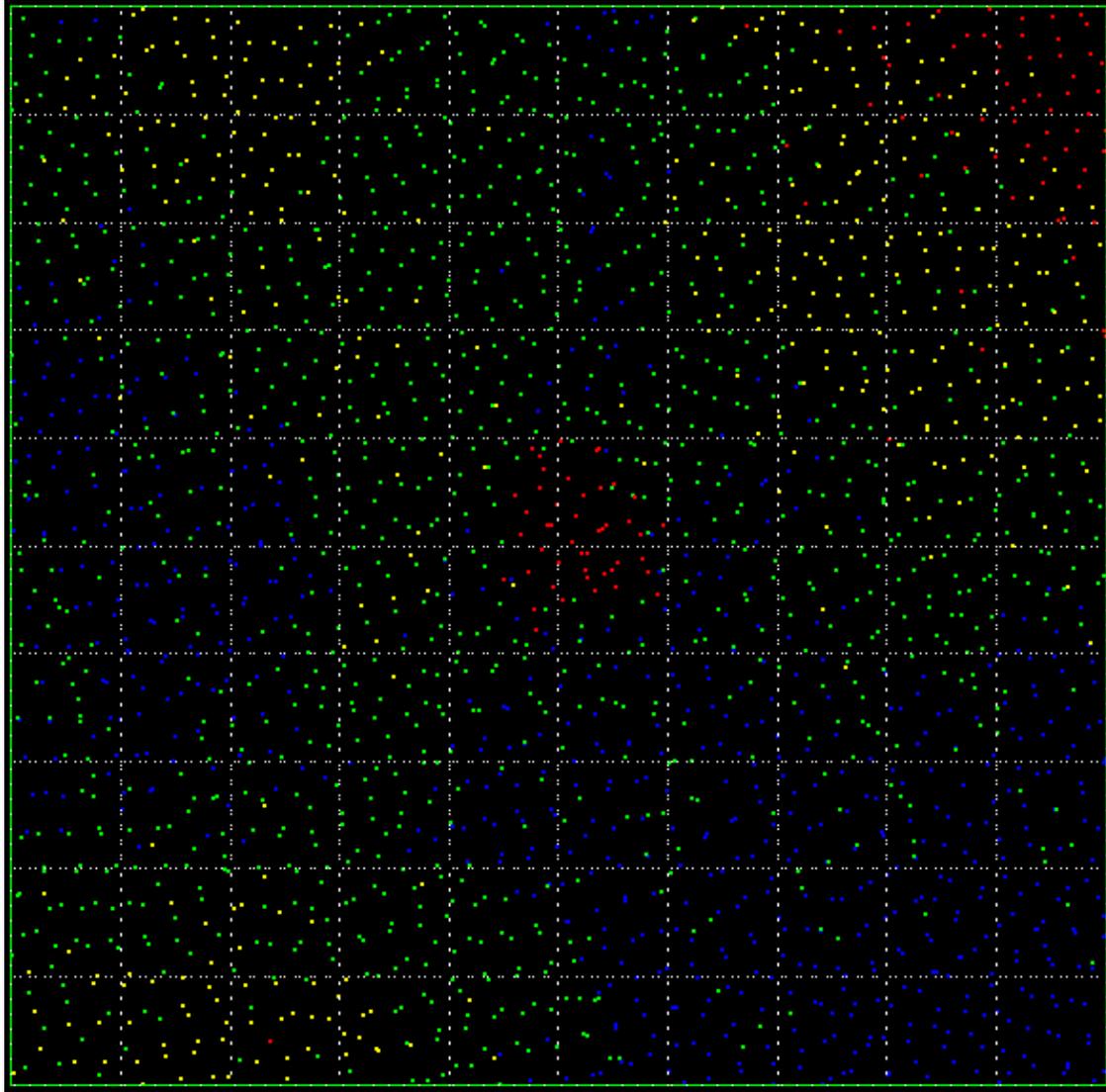
20m



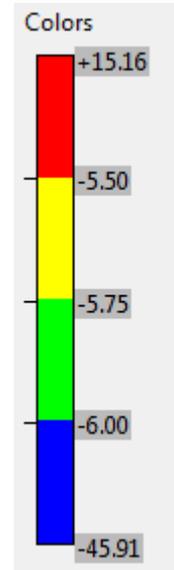
Average (20m\*20m area)  
point density  
 $3.942/m^2$

# LiDAR 4X 100% coverage

20m



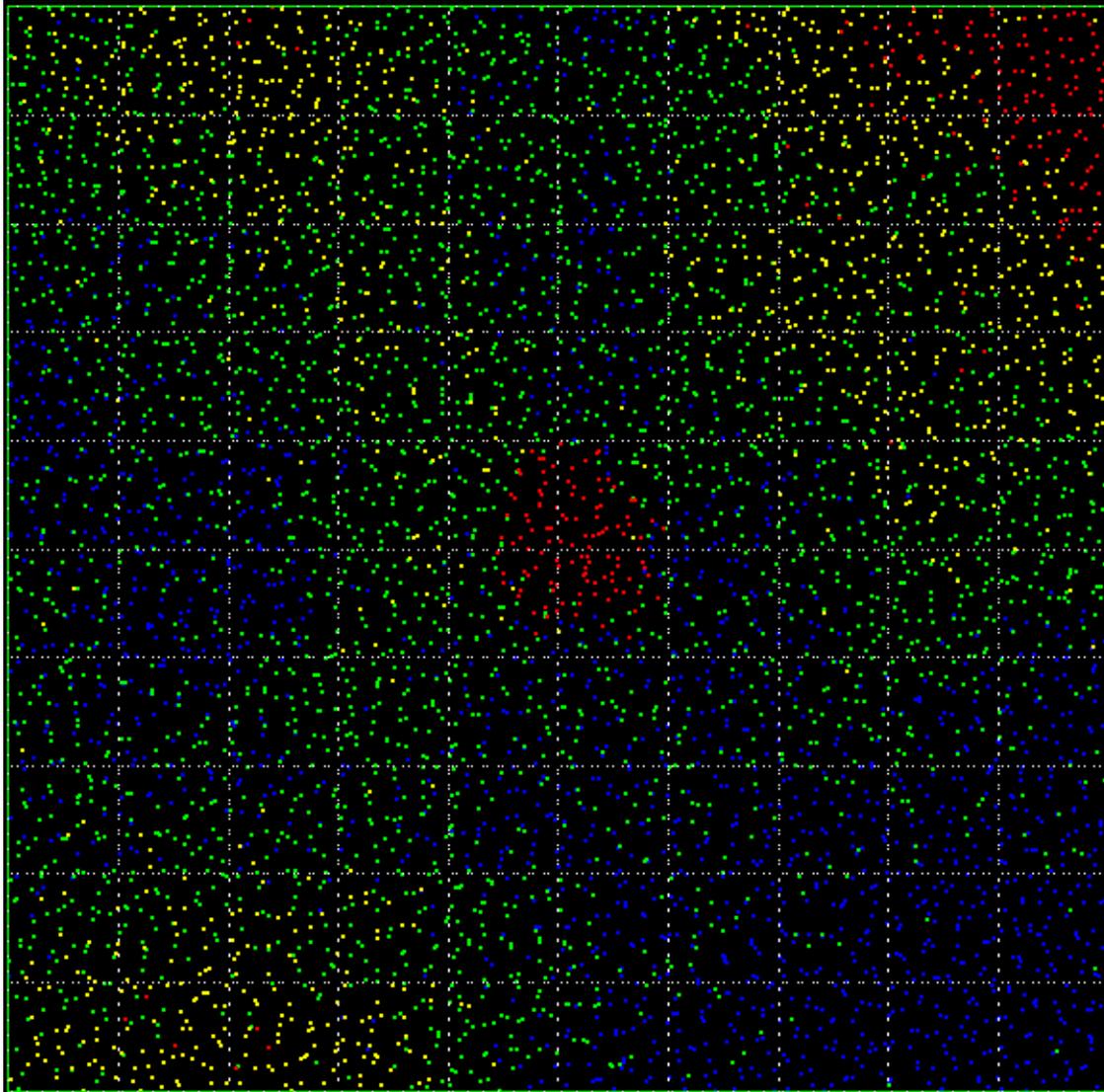
20m



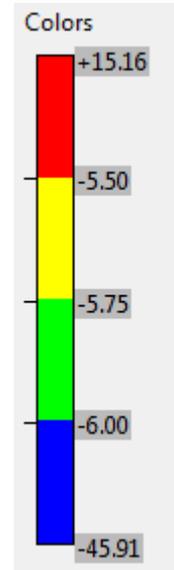
Average (20m\*20m area)  
point density  
 $8.595/m^2$

# LiDAR 4X 200% coverage

20m

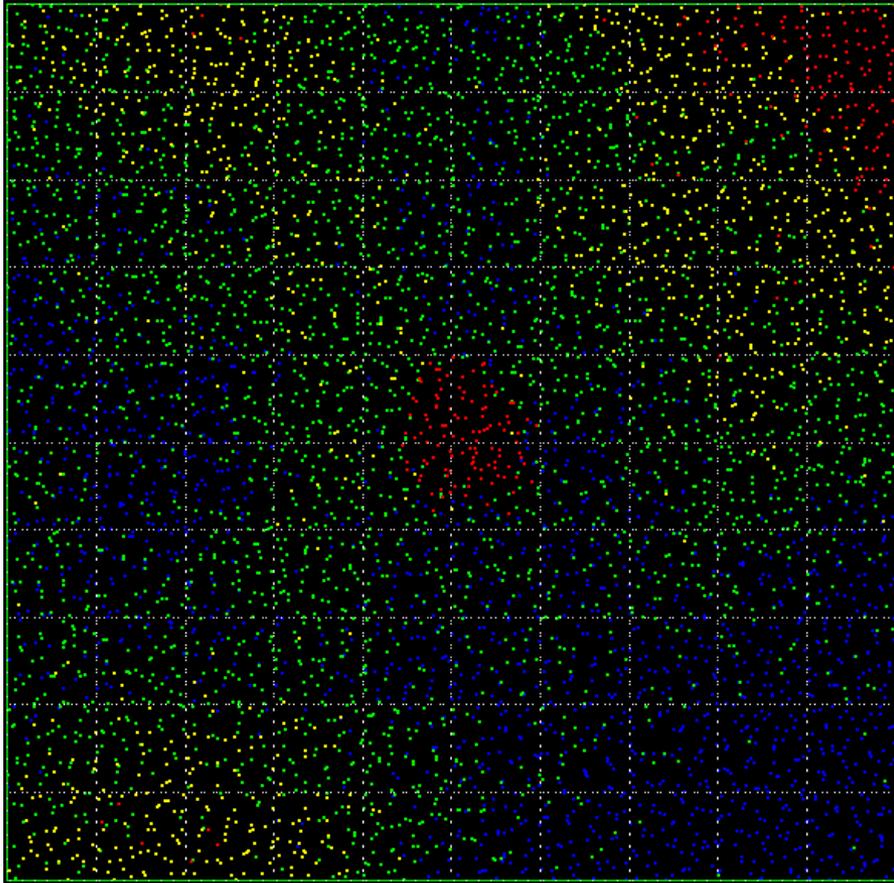


20m

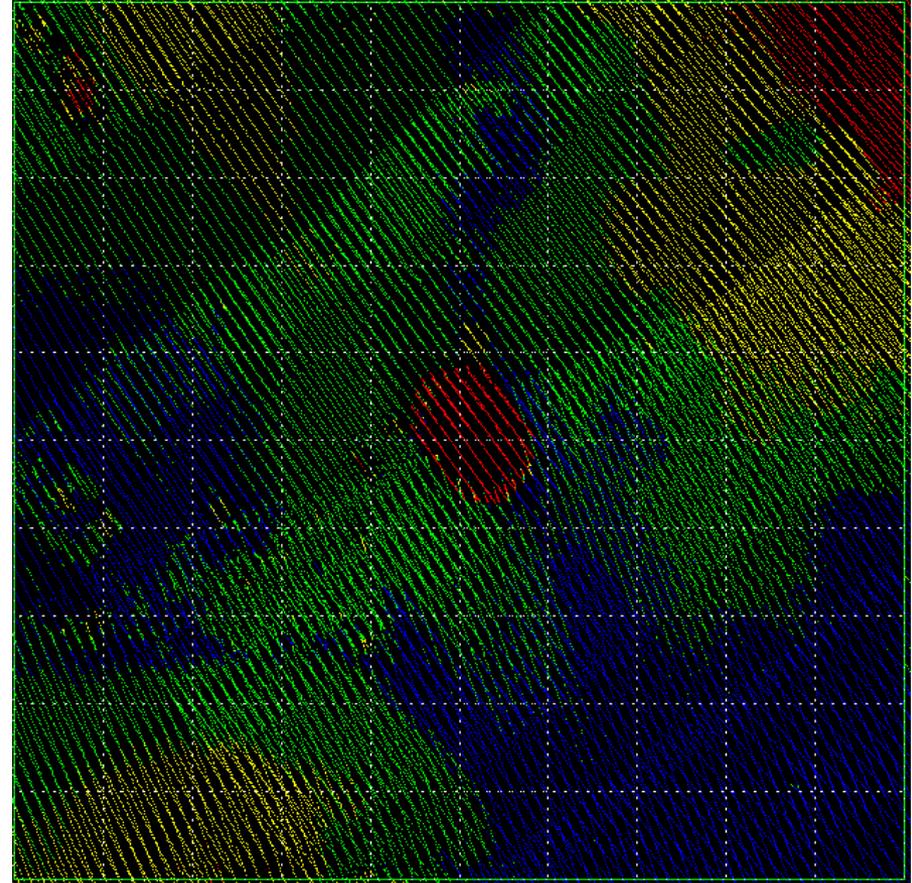


Average (20m\*20m area)  
point density  
13.935/m<sup>2</sup>

# LiDAR 4X 200% coverage VS. MBES



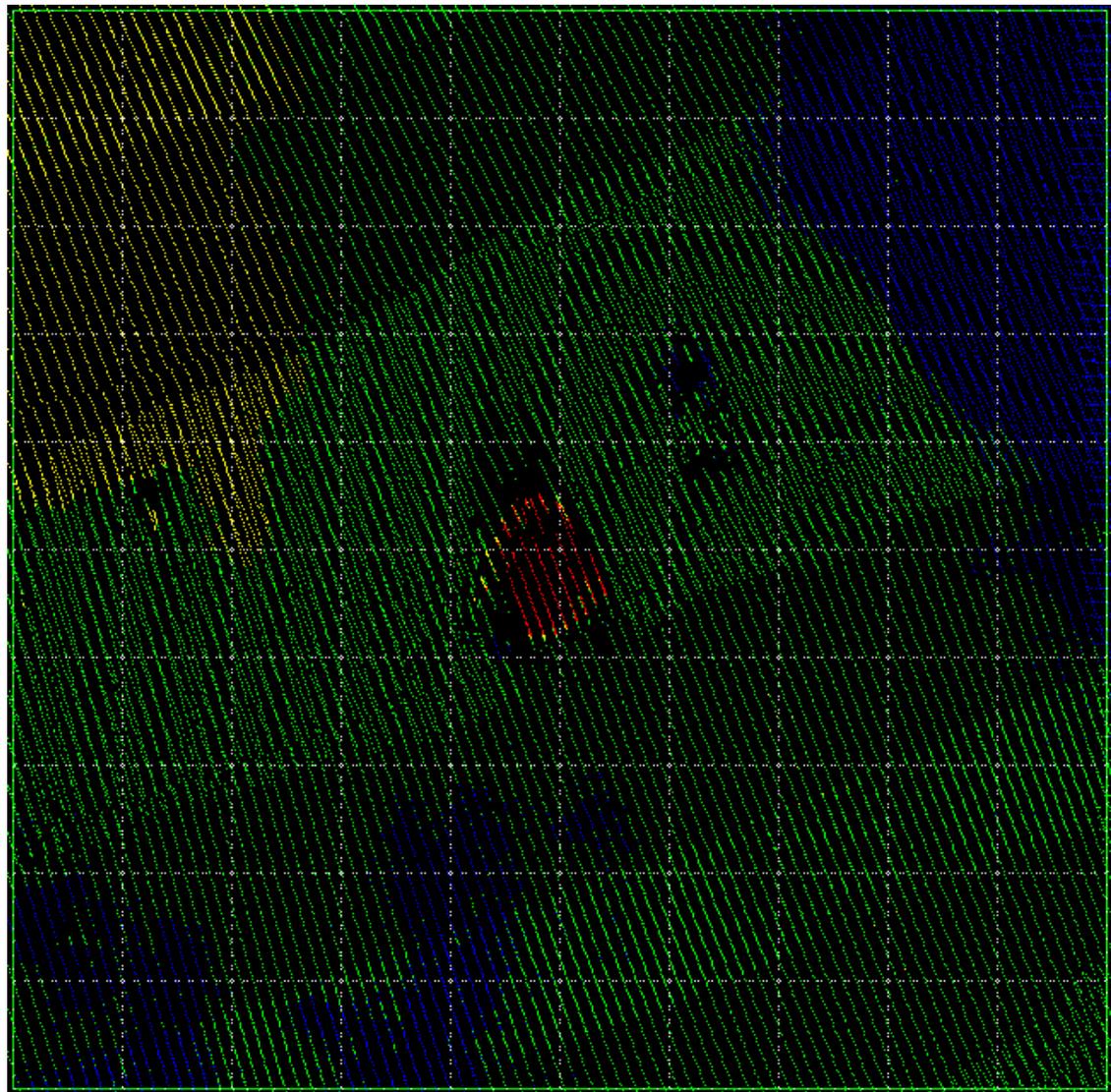
LiDAR UfourX 200% coverage



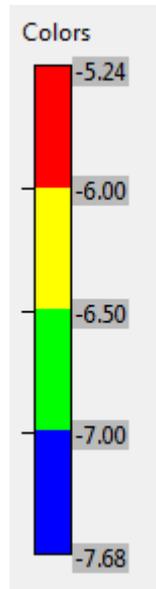
MBES

# MBES Area 2

20m

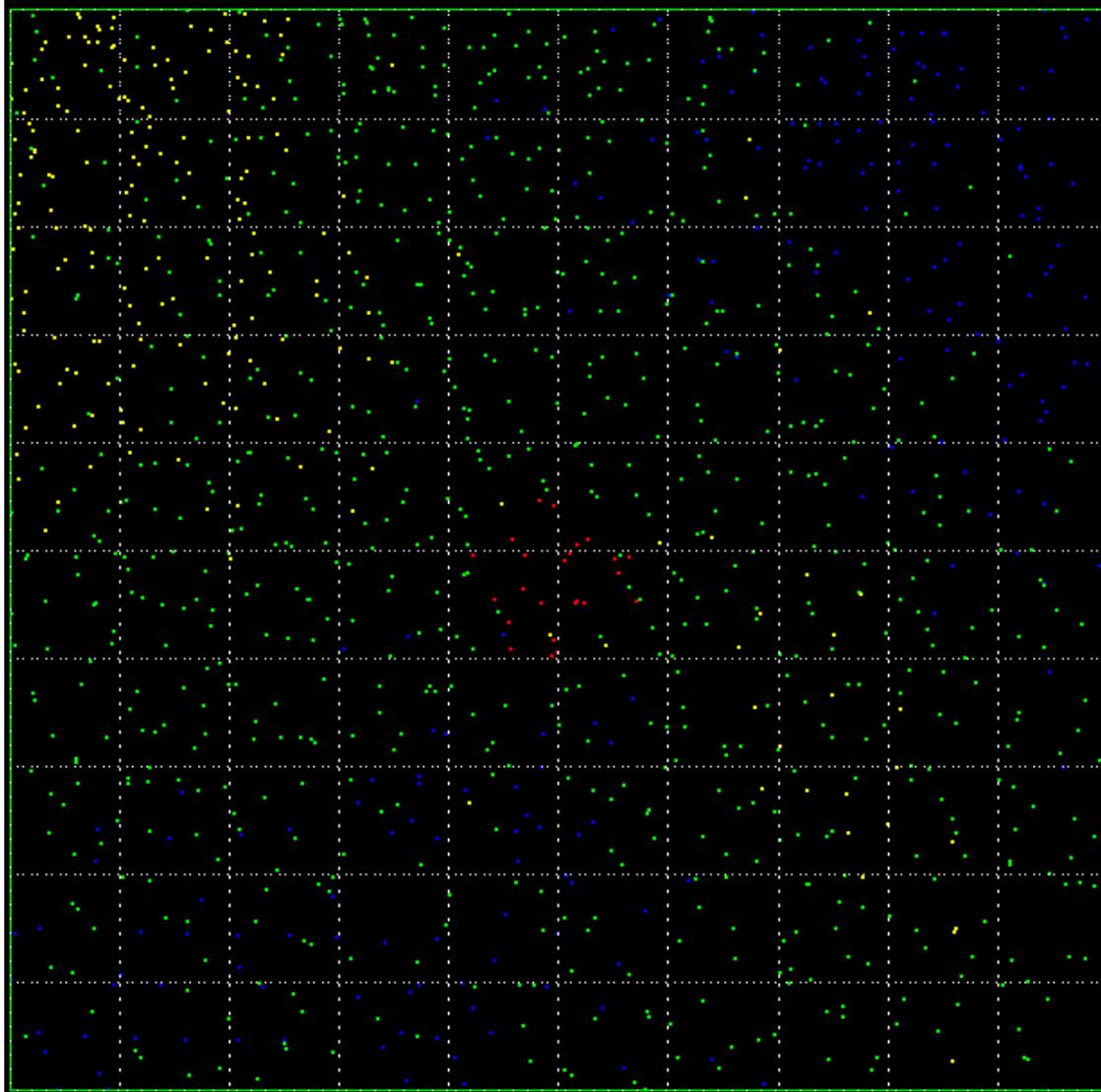


20m

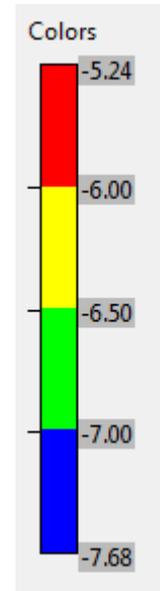


# LiDAR standard 100% coverage

20m



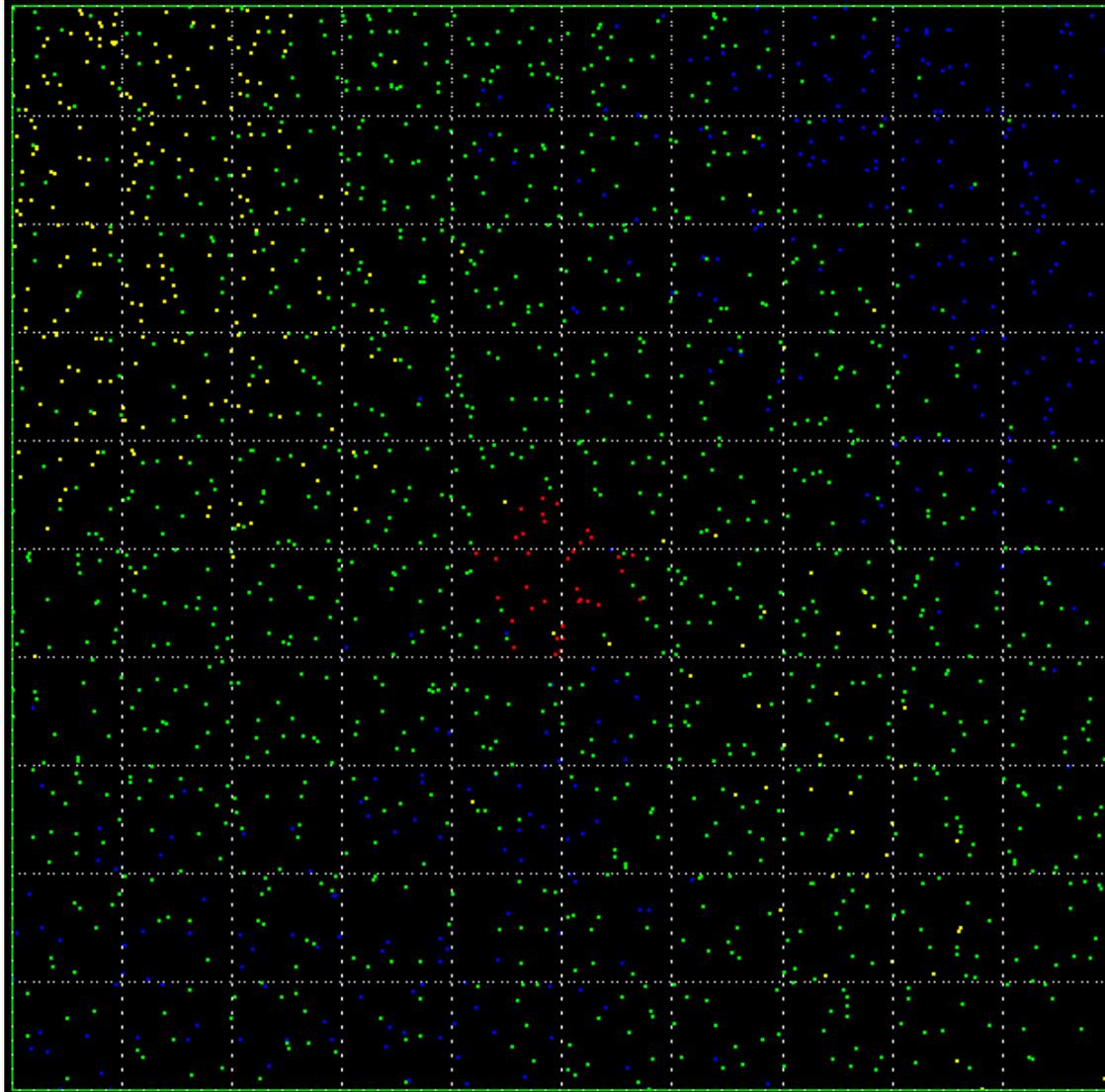
20m



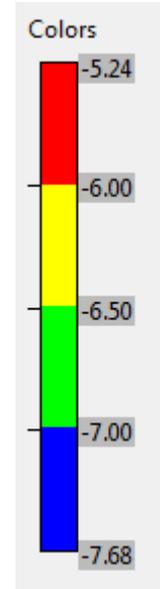
Average (20m\*20m area)  
point density  
 $3.313/\text{m}^2$

# LiDAR standard 200% coverage

20m



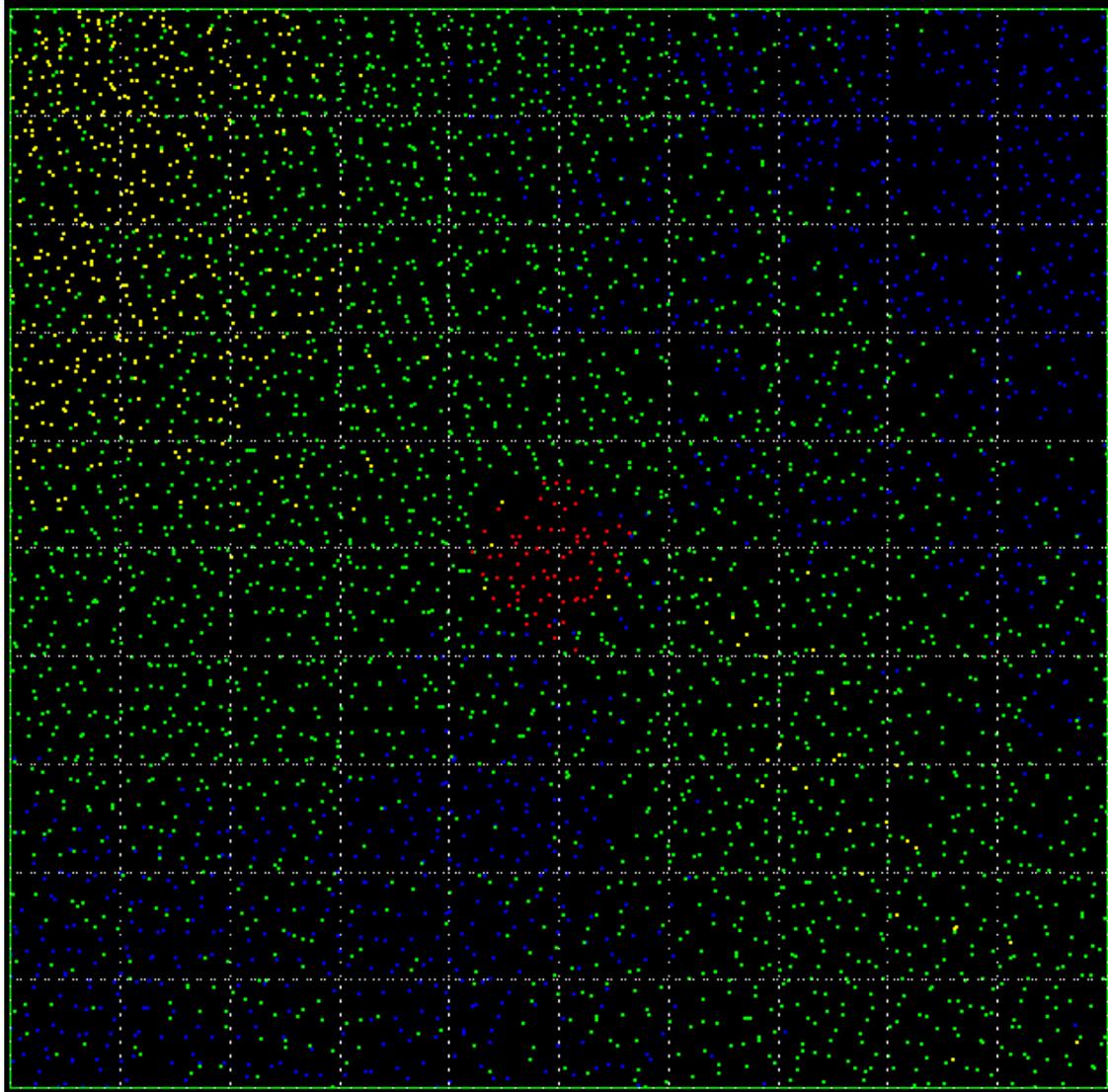
20m



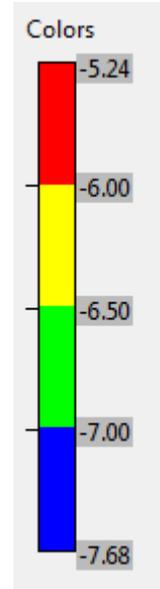
Average (20m\*20m area)  
point density  
 $4.825/m^2$

# LiDAR 4X 100% coverage

20m



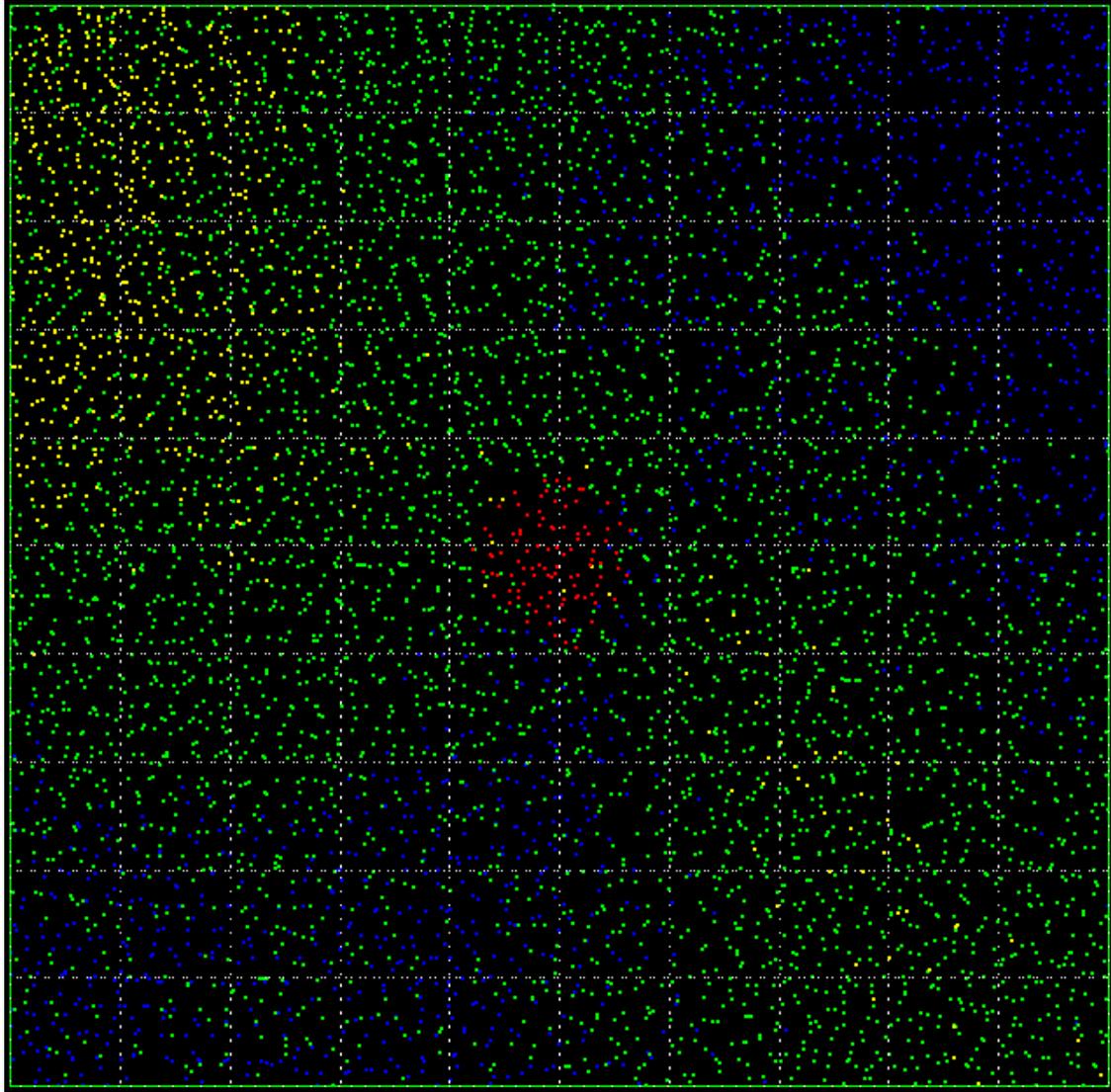
20m



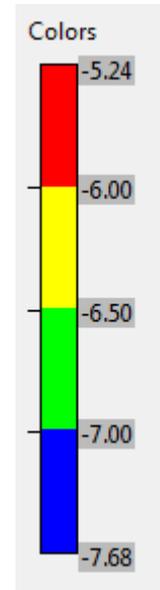
Average (20m\*20m area)  
point density  
10.338/m<sup>2</sup>

# LiDAR 4X 200% coverage

20m

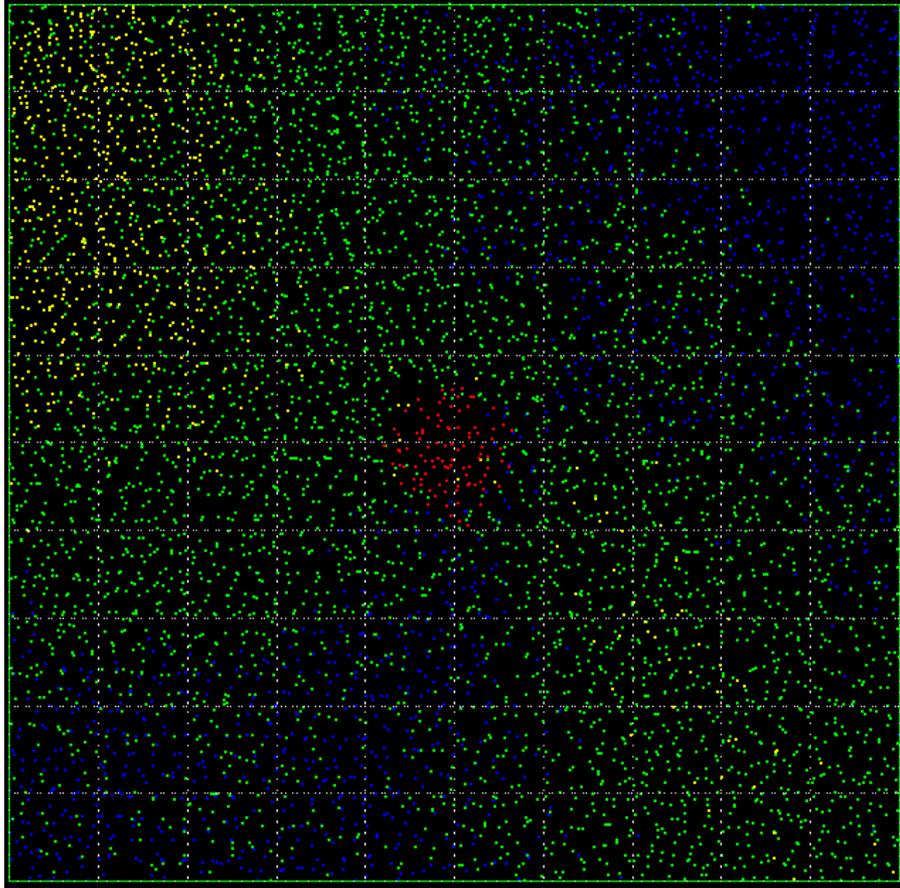


20m

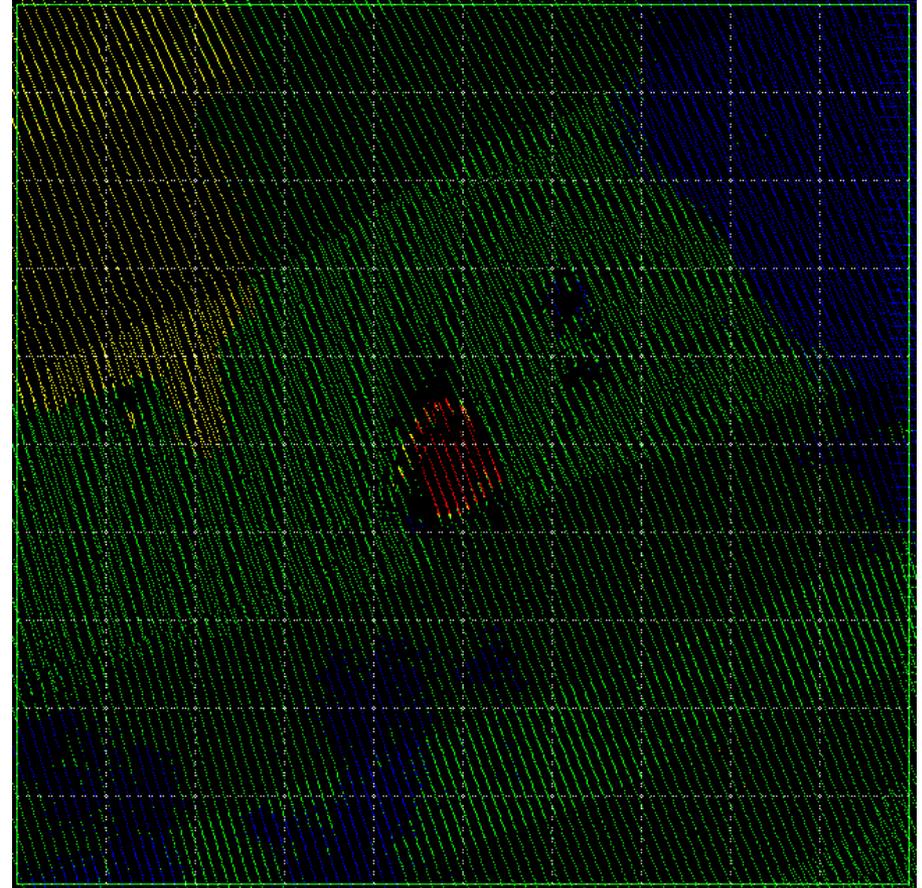


Average (20m\*20m area)  
point density  
15.300/m<sup>2</sup>

# LiDAR 4X 200% coverage VS. MBES



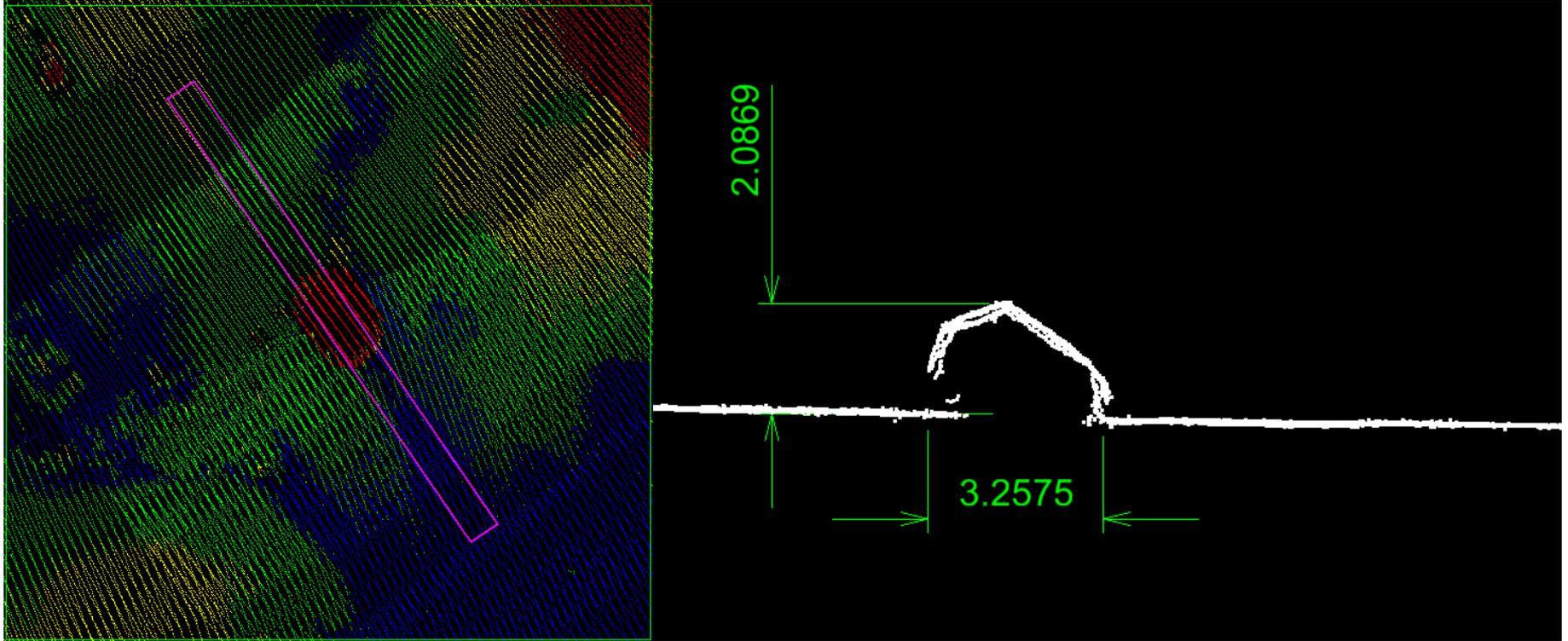
LiDAR UfourX 200% coverage



MBES

# Object Detection

# Object 1

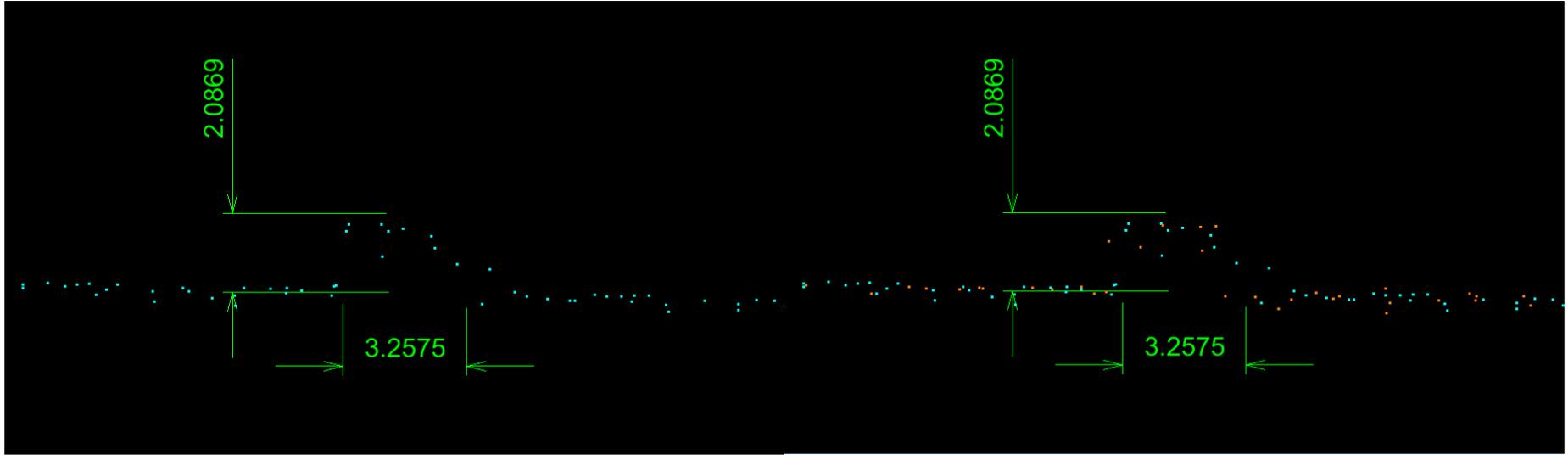


MBES reference

Depth: 5.9m

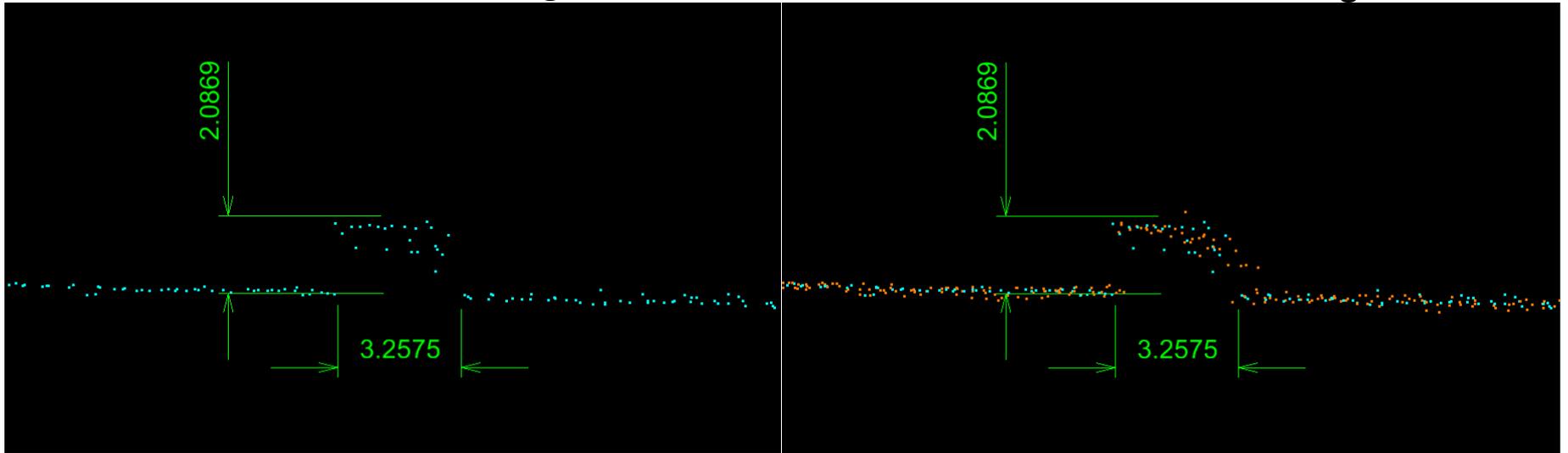
Cross section depth: 0.5m

# Object 1 Color By Flightlines



Standard LiDAR 100% coverage

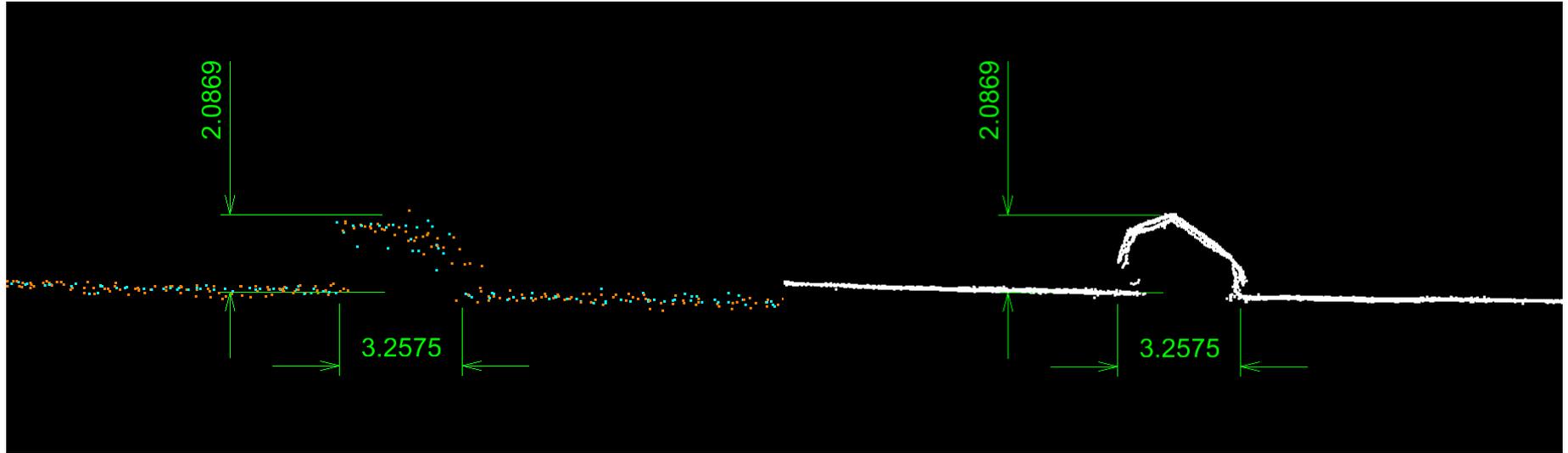
Standard LiDAR 200% coverage



4X LiDAR 100% coverage

4X LiDAR 200% coverage

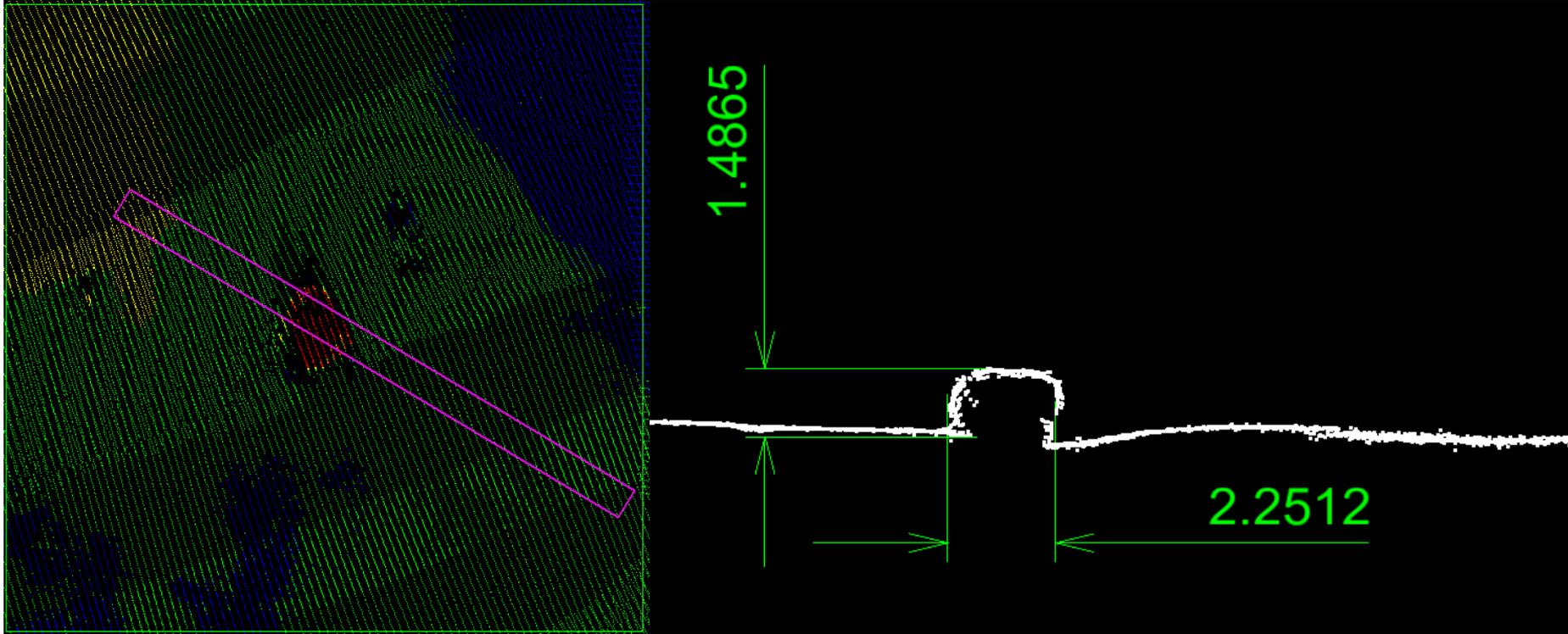
# LiDAR 4X 200% coverage VS. MBES, object 1



LiDAR UfourX 200% coverage

MBES

# Object 2

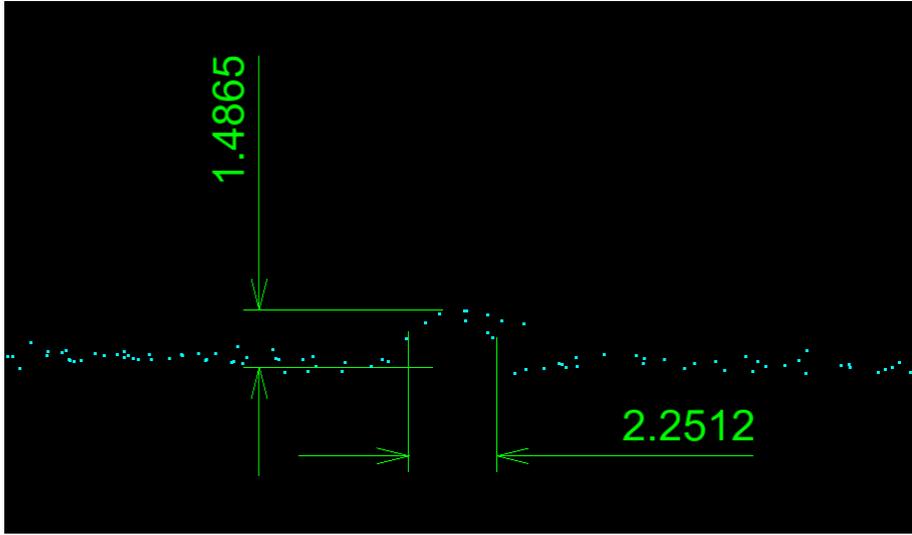


MBES reference

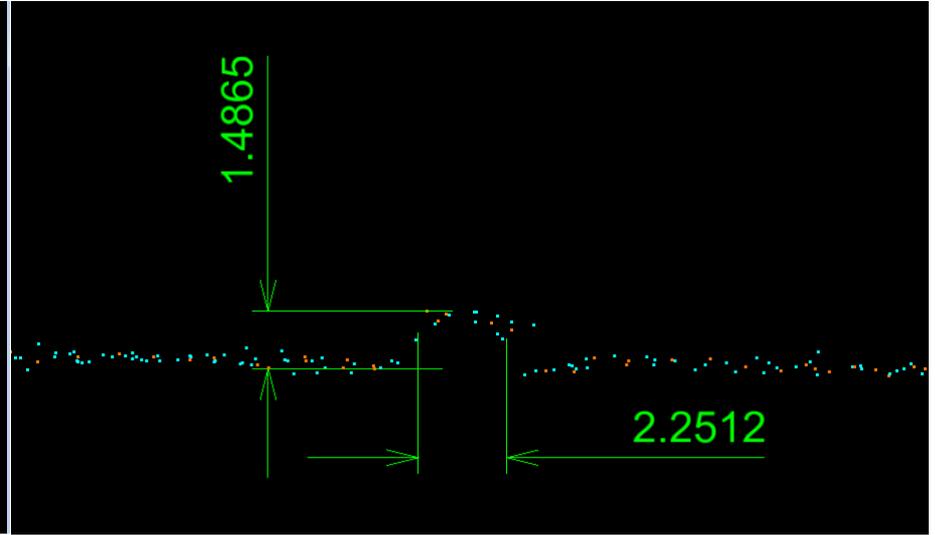
Depth:6.5m

Cross section depth: 0.5m

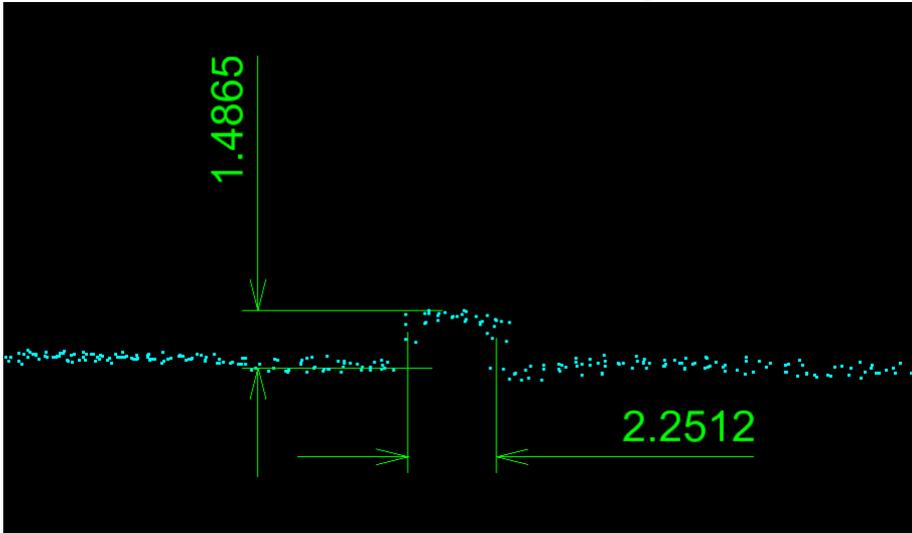
# Object 2 Color By Flightlines



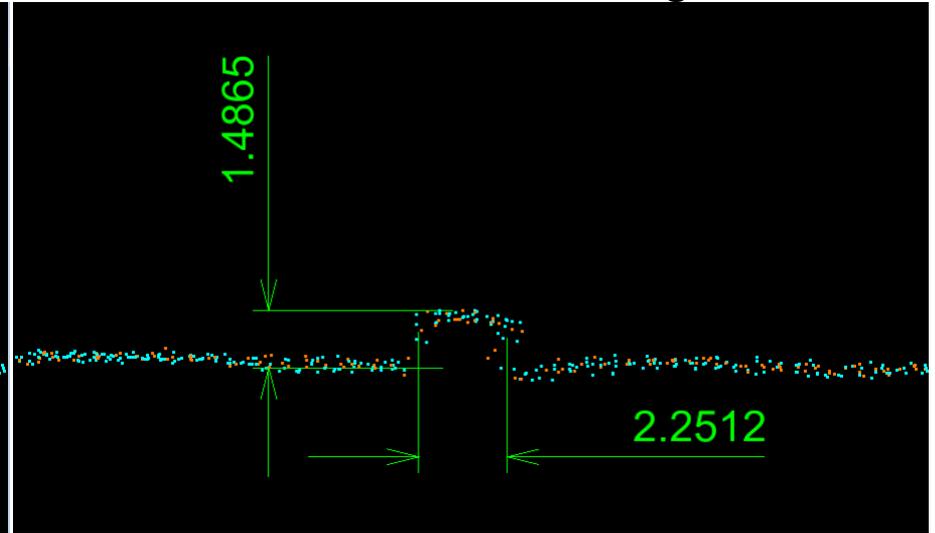
Standard LiDAR 100% coverage



Standard LiDAR 200% coverage

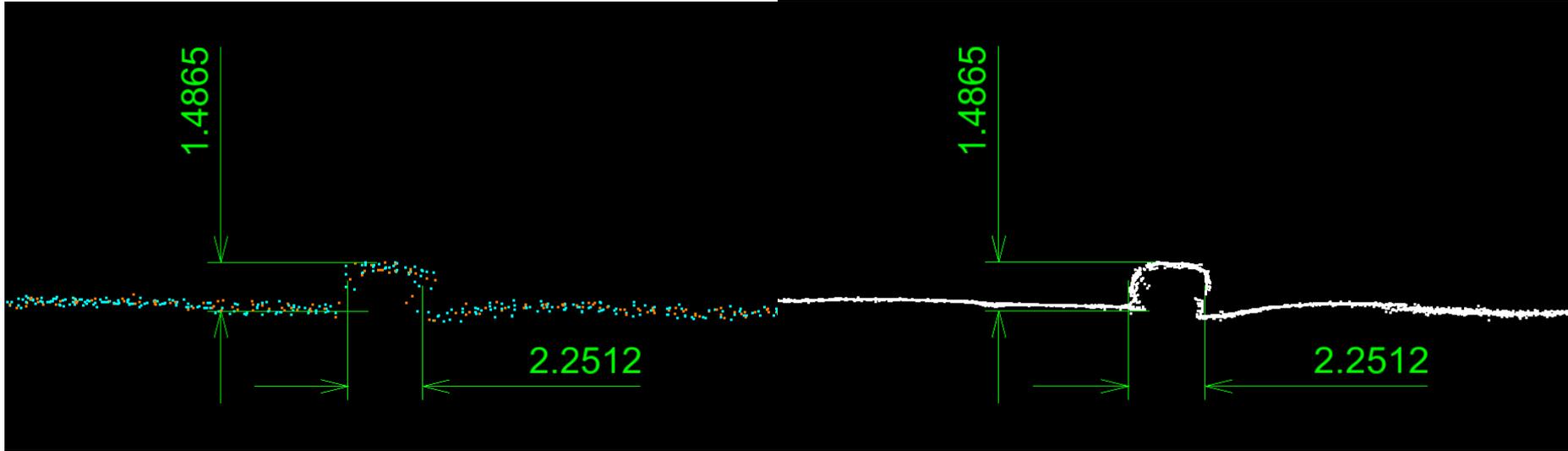


4X LiDAR 100% coverage



4X LiDAR 200% coverage

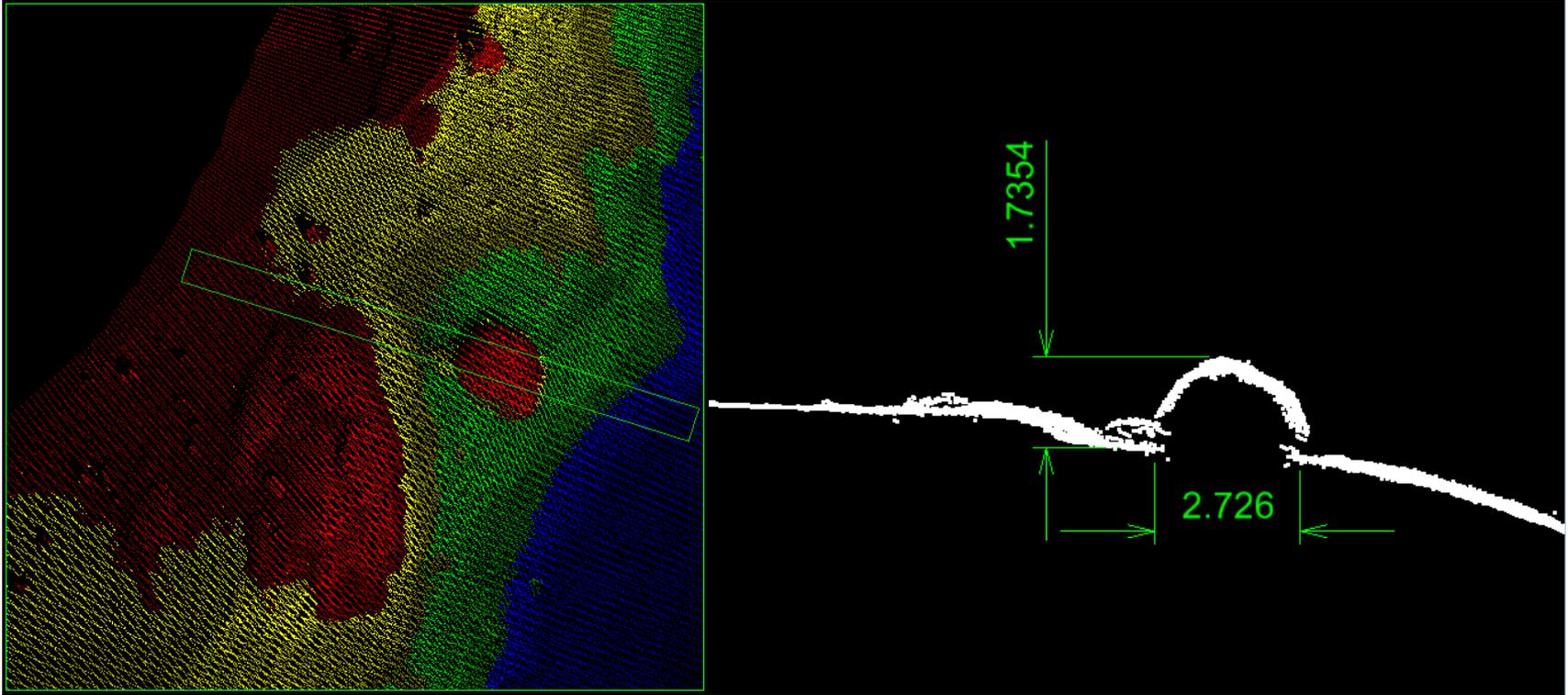
# LiDAR 4X 200% coverage VS. MBES, object 2



LiDAR UfourX 200% coverage

MBES

# Object 3

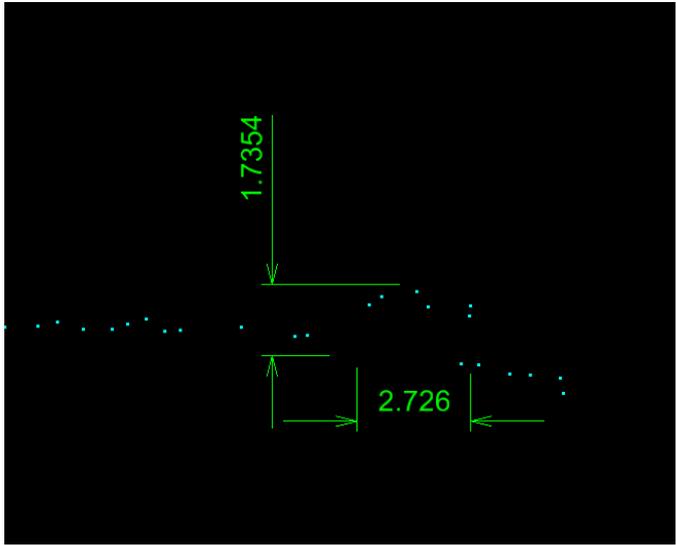


MBES reference

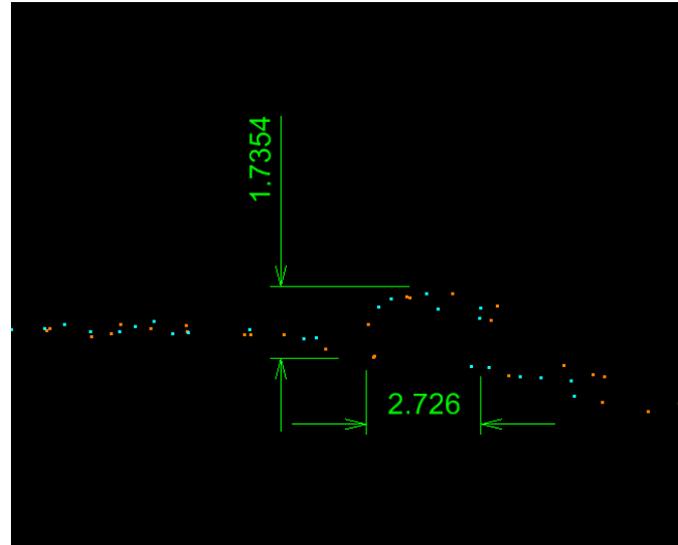
Depth:6.3m

Cross section depth: 0.5m

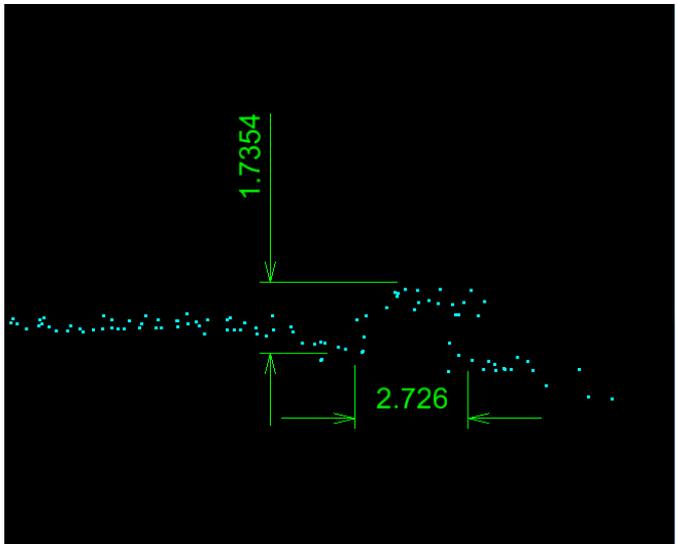
# Object 3 Color By Flightlines



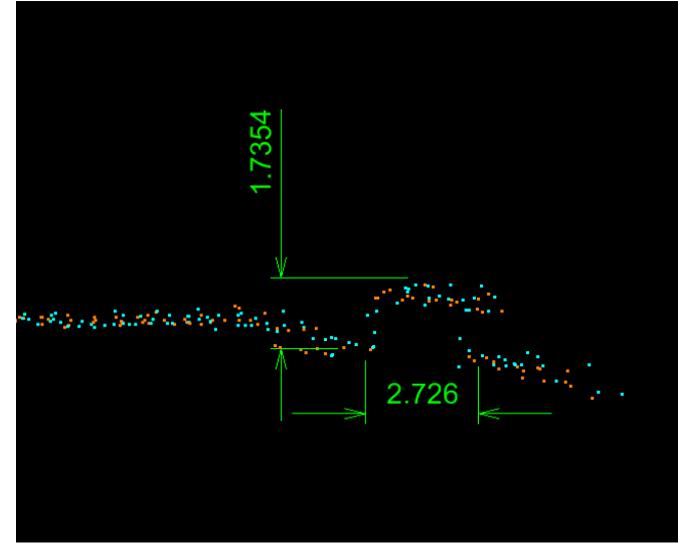
Standard LiDAR 100% coverage



Standard LiDAR 200% coverage

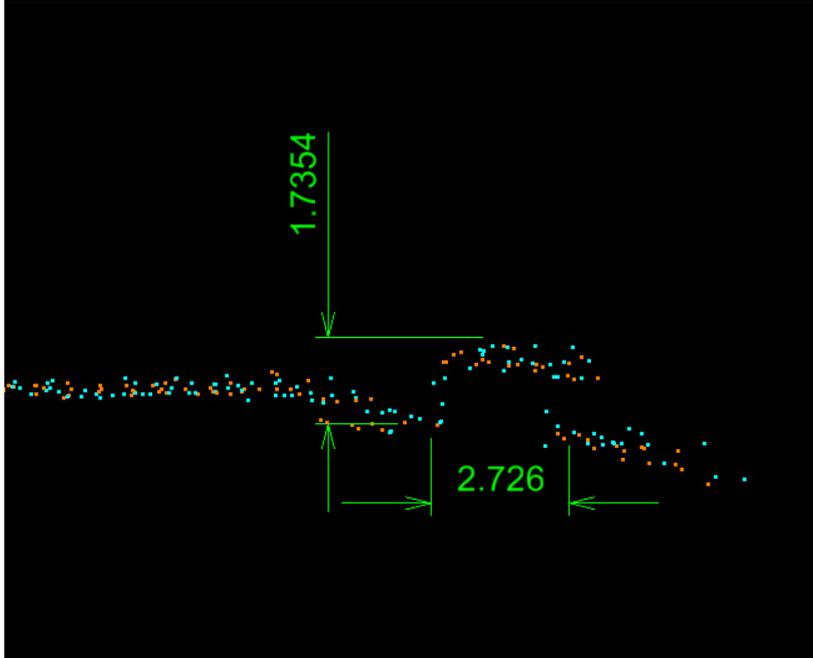


4X LiDAR 100% coverage

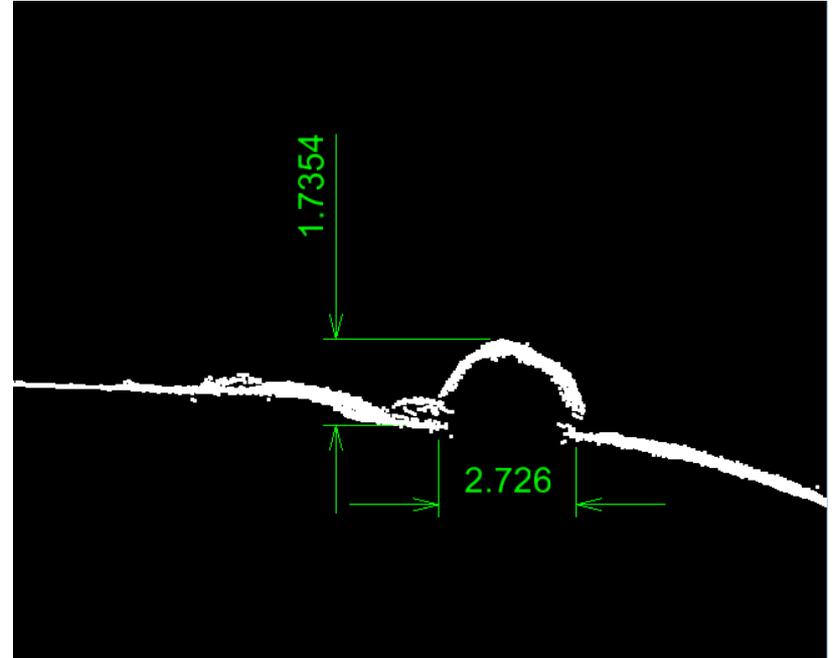


4X LiDAR 200% coverage

# LiDAR 4X 200% coverage VS. MBES, object 3

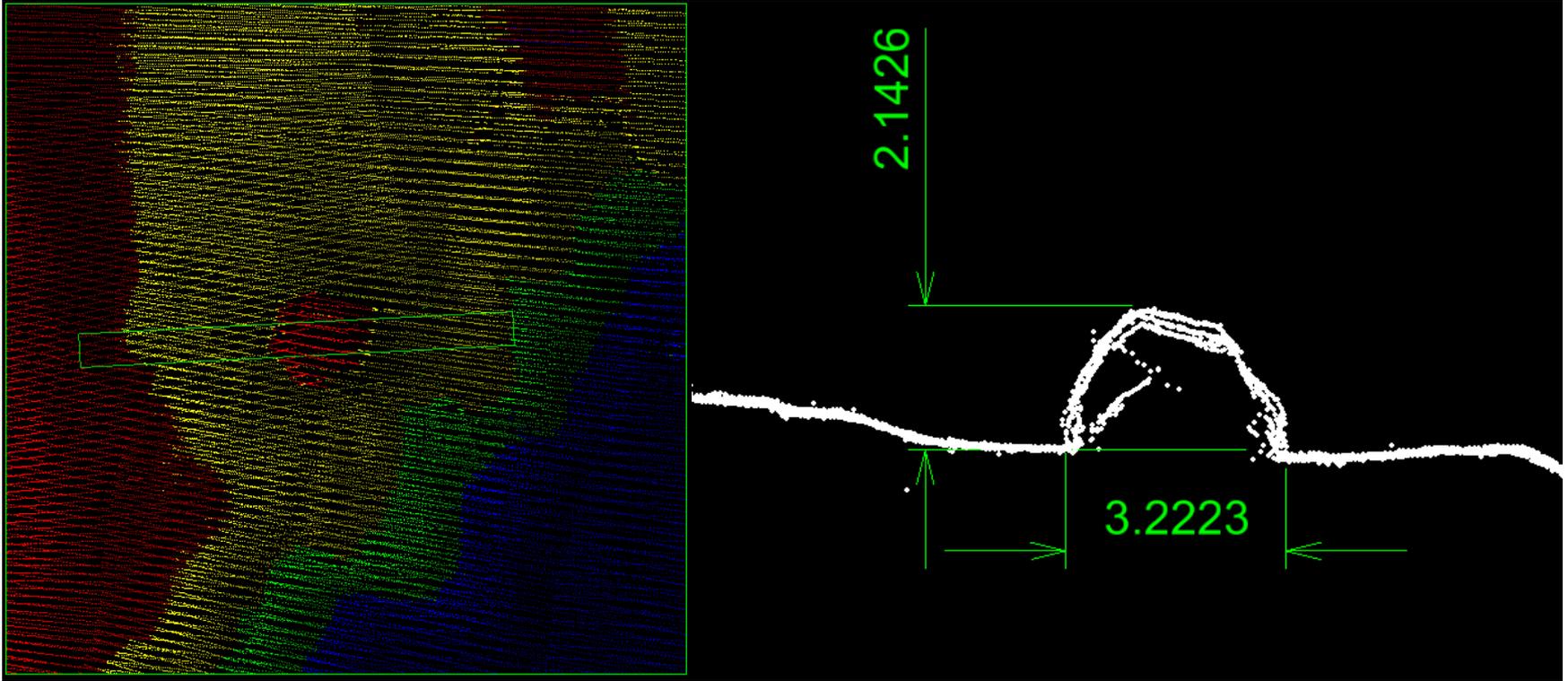


LiDAR UfourX 200% coverage



MBES

# Object 4

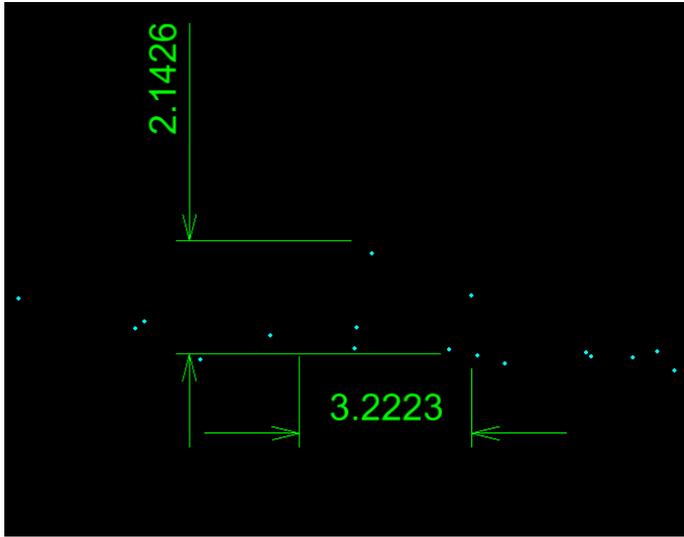


MBES reference

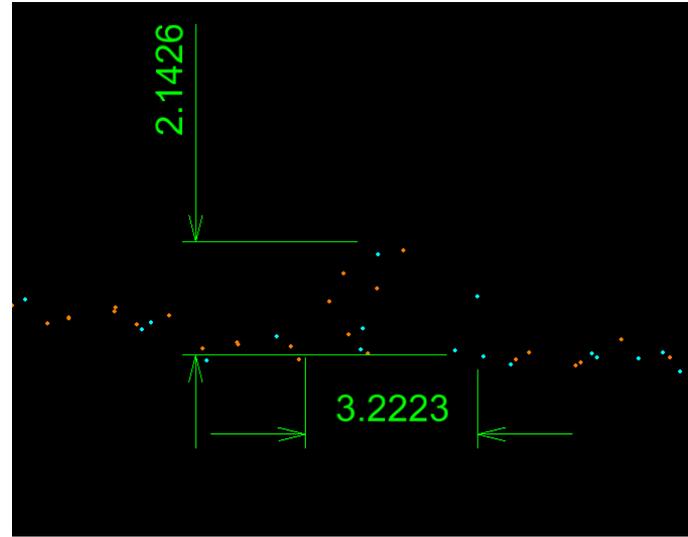
Depth:6.5m

Cross section depth: 0.5m

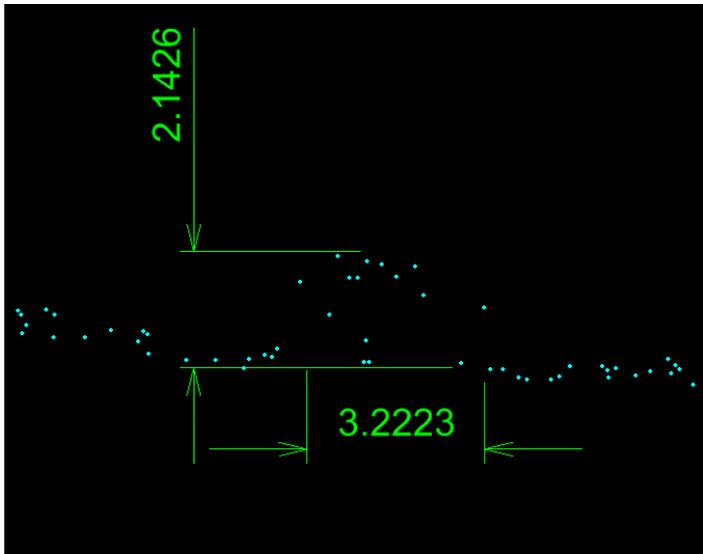
# Object 4 Color By Flightlines



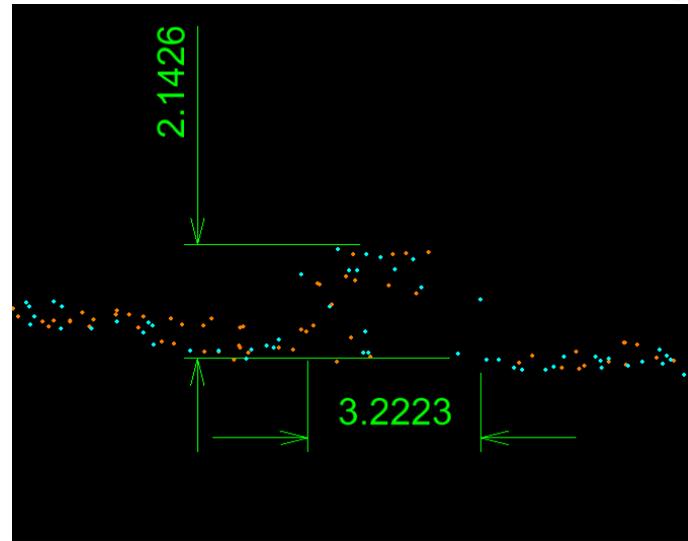
Standard LiDAR 100% coverage



Standard LiDAR 200% coverage

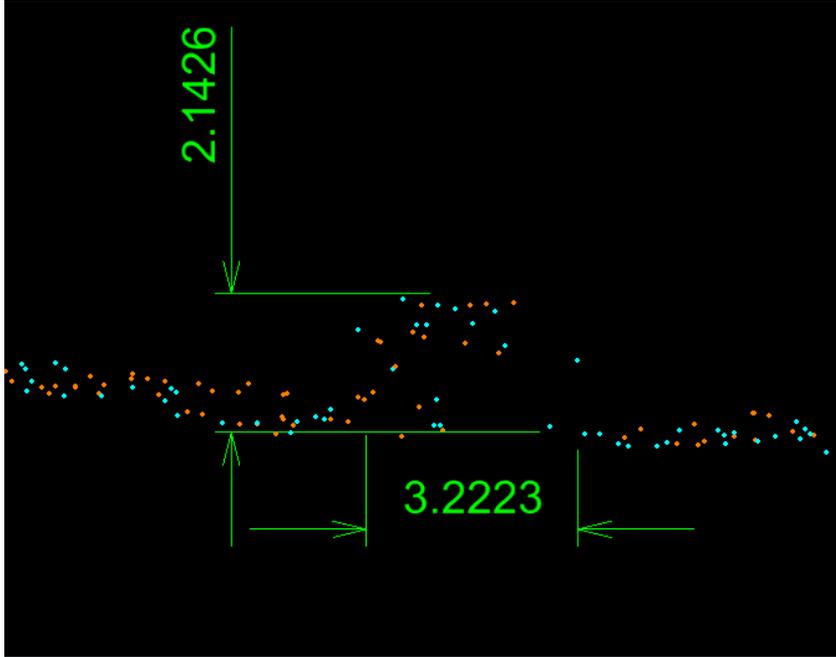


4X LiDAR 100% coverage

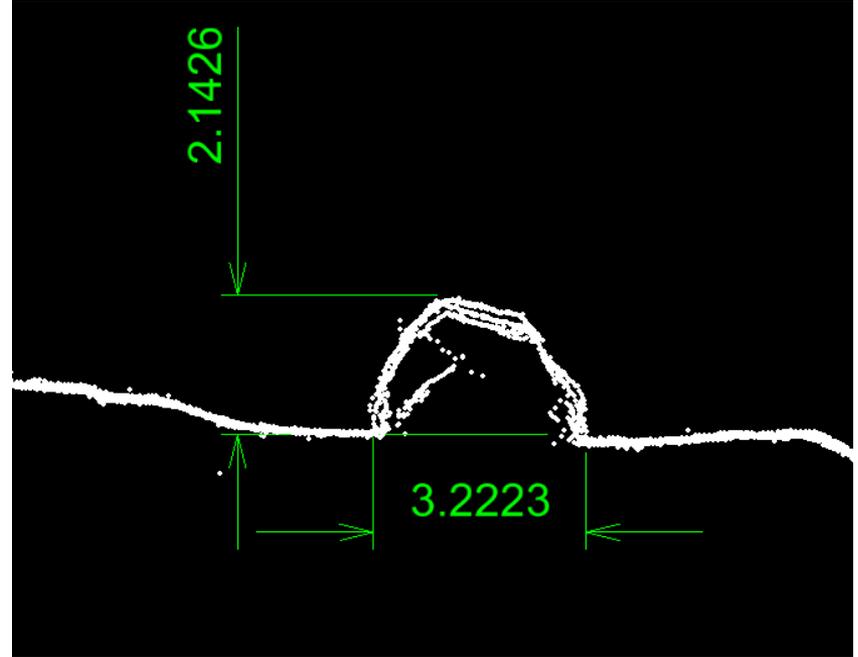


4X LiDAR 200% coverage

# LiDAR 4X 200% coverage VS. MBES, object 4



LiDAR UfourX 200% coverage

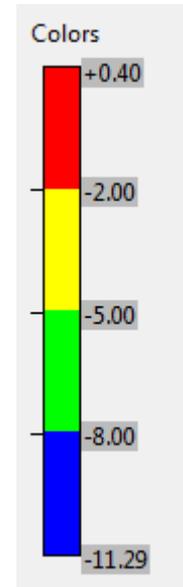
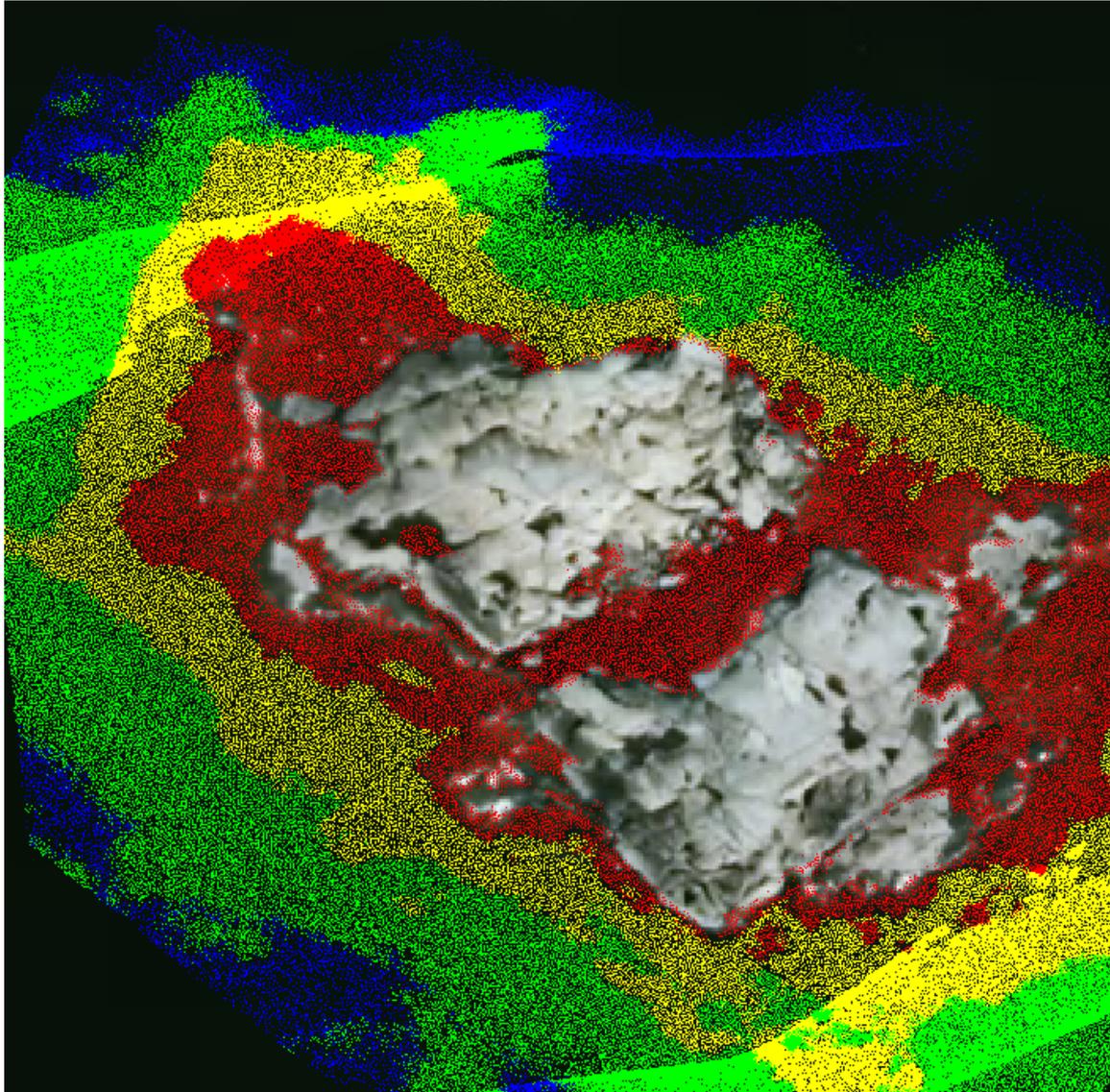


MBES

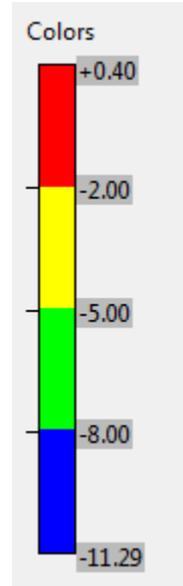
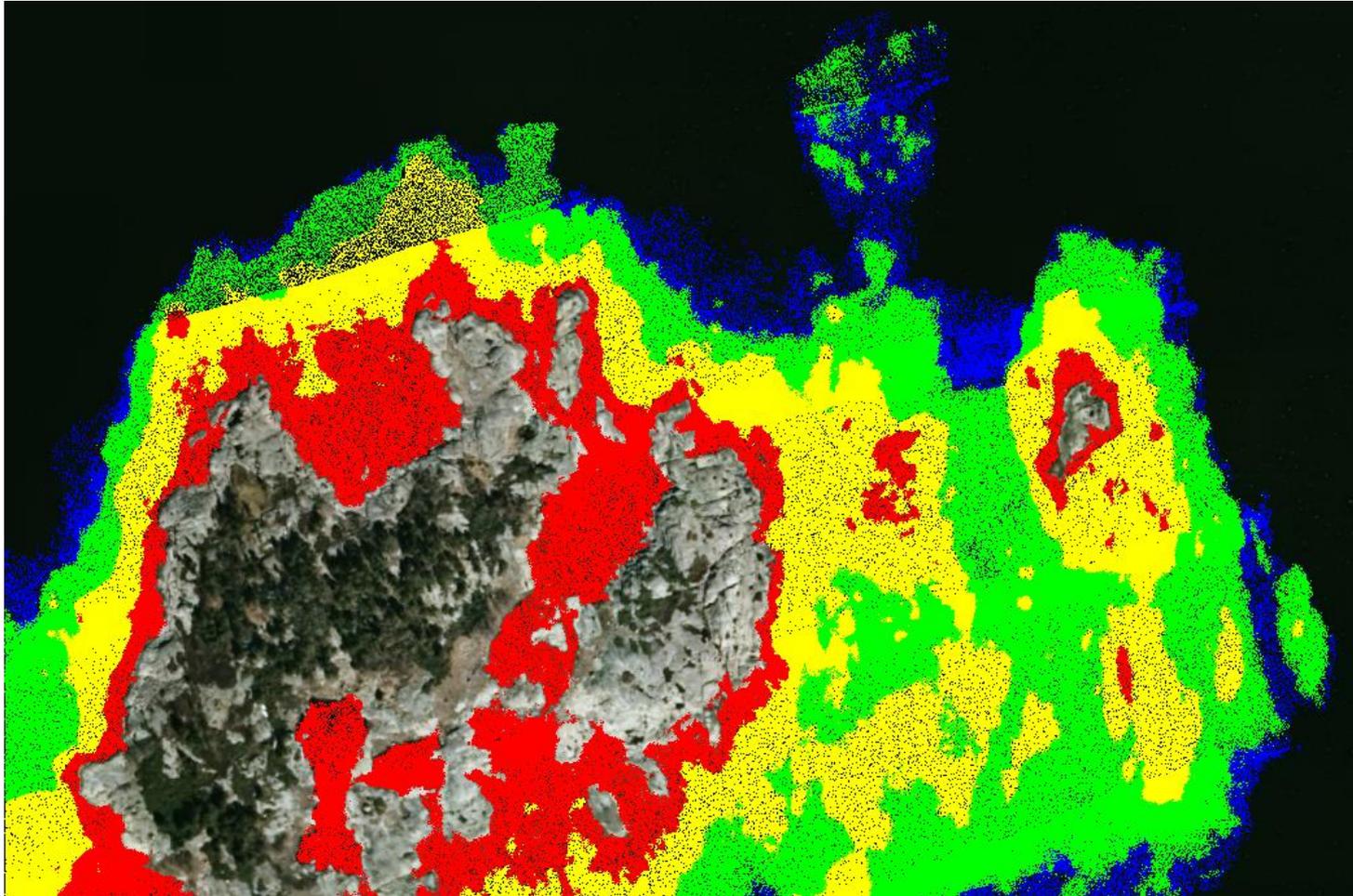
# Area Coverage

# LiDAR 4X 200% coverage

200m

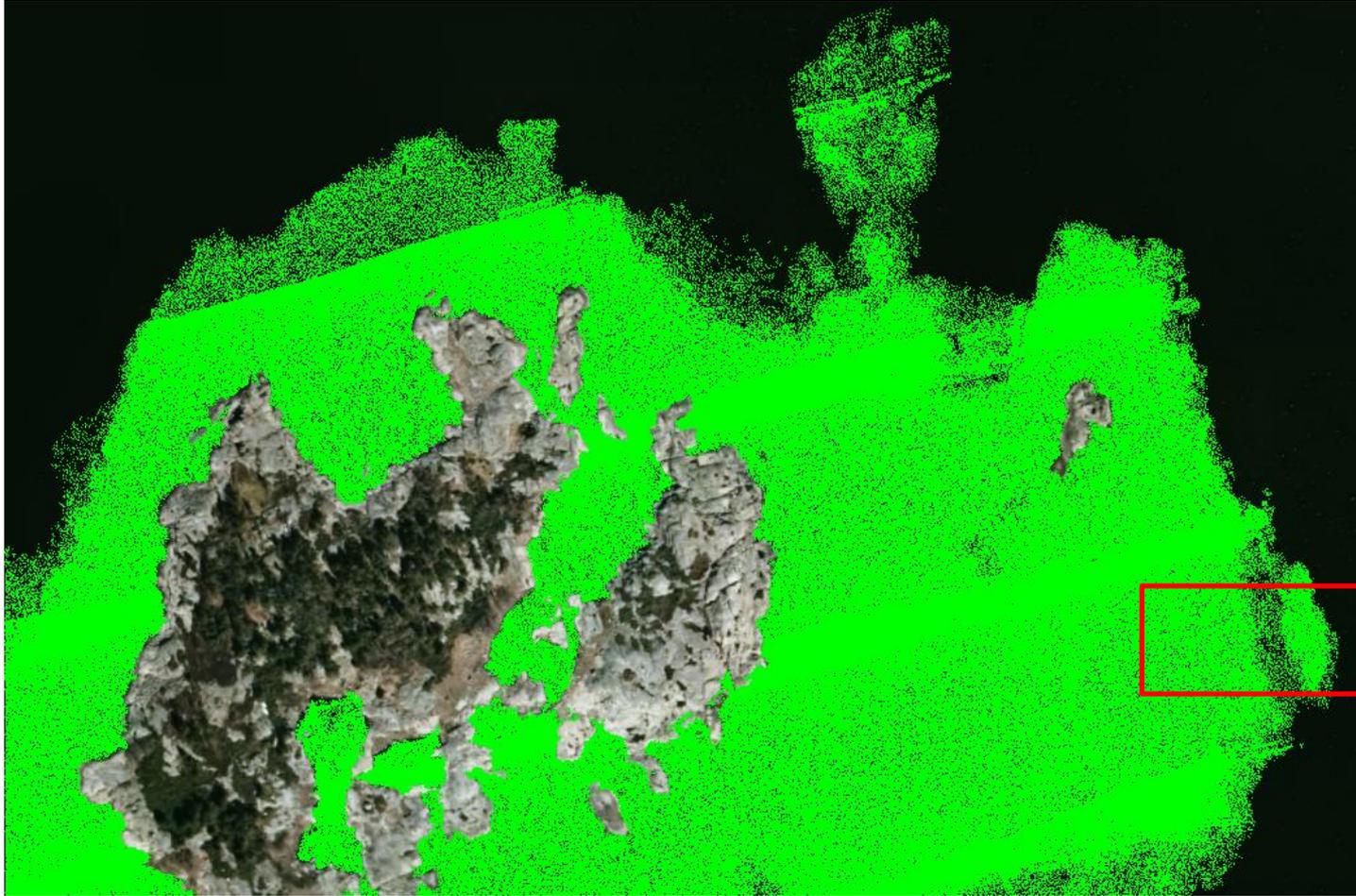


# LiDAR 4X 200% coverage



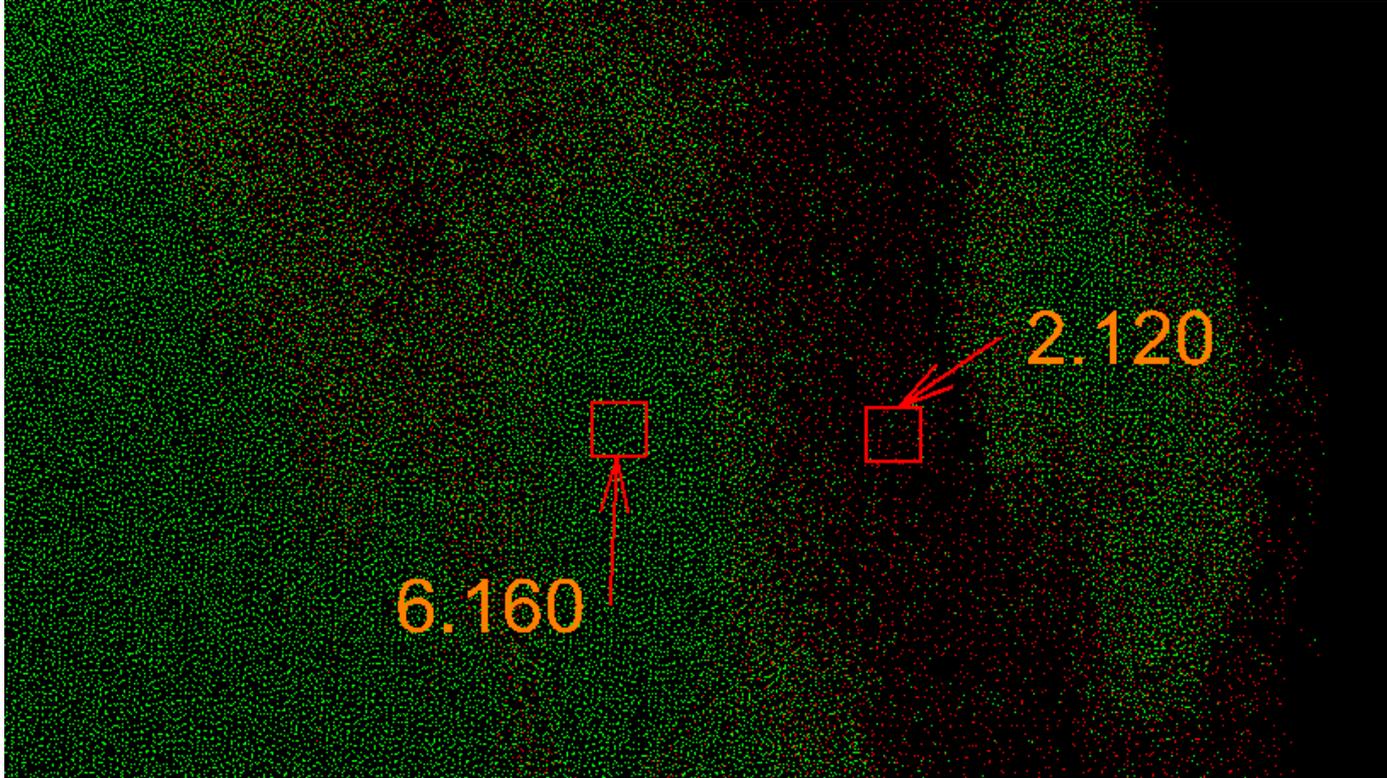
840m

# LiDAR 4X 200% coverage



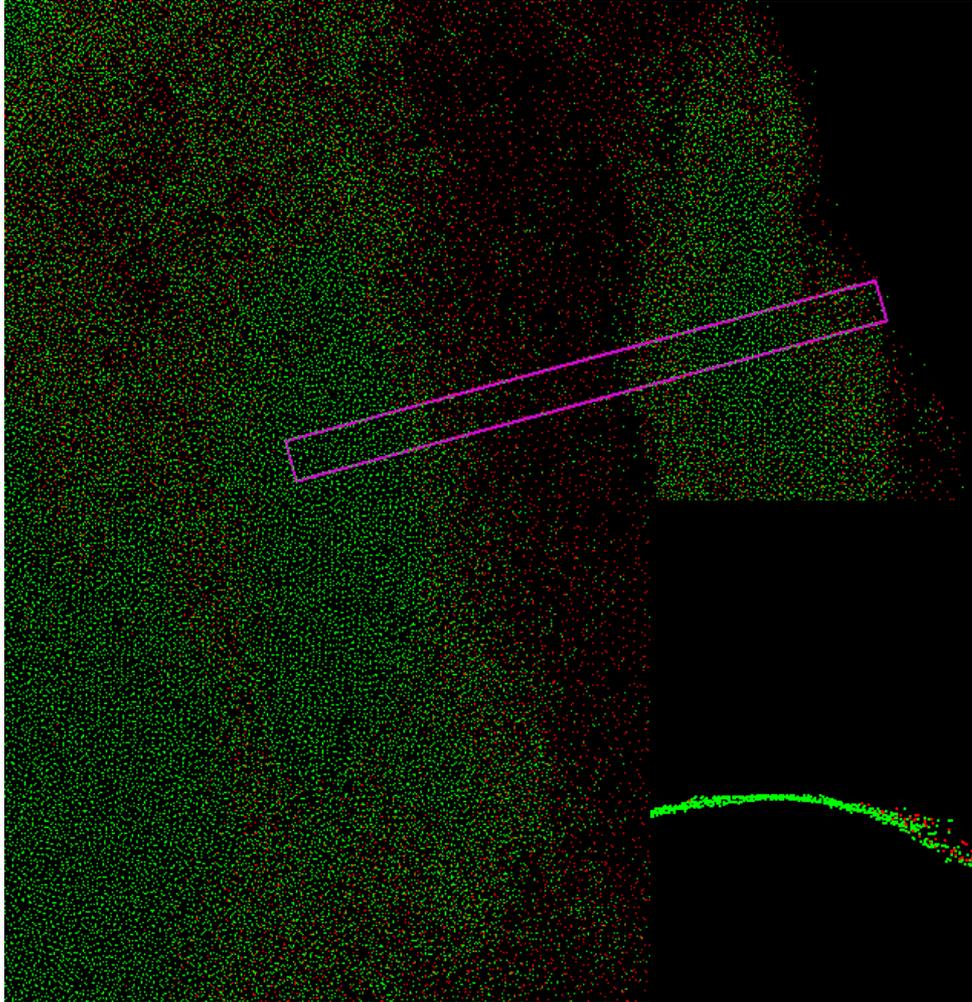
840m

# LiDAR 4X 200% coverage



Point Density /m<sup>2</sup>  
Square size: 5x5m  
Color by Scanner  
Green: Shallow  
Red: Deep  
Depths 4.5m-9m

# LiDAR 4X 200% coverage



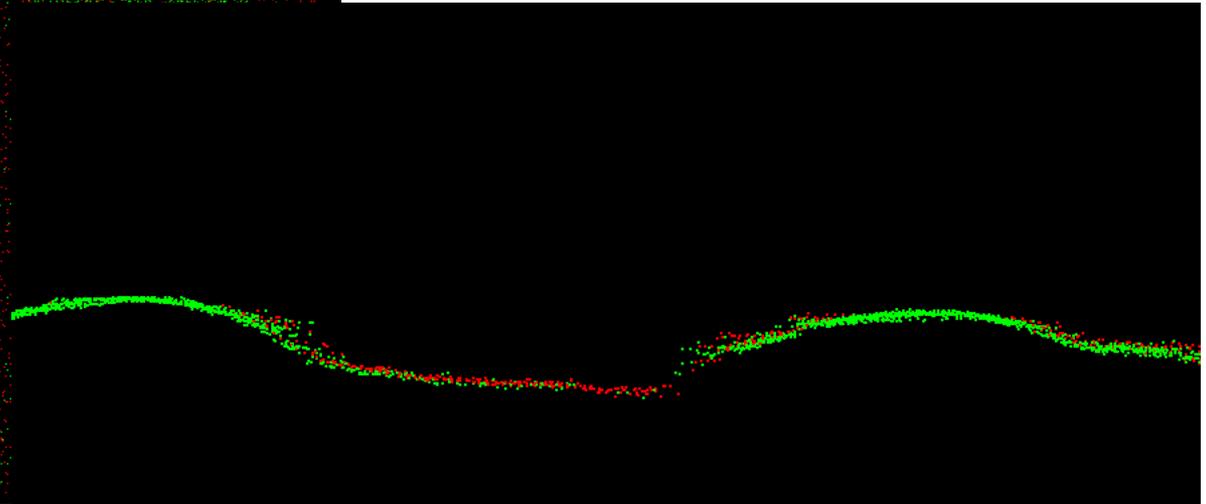
Color by Scanner

Green: Shallow Sensor

Red: Deep Sensor

Depths 4.5m-9m

Cross section depth 2m



**Thank you for your attention!**

