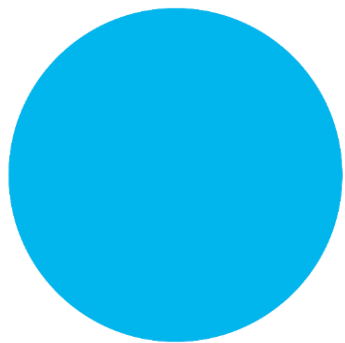


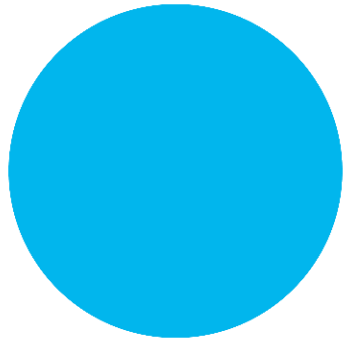
iXblue





**iXblue develops  
advanced technologies to  
match Customers' challenges in  
tough environments**

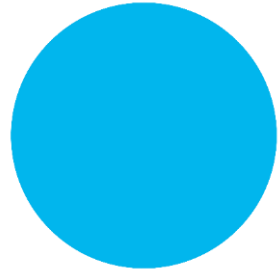




**iXblue develops  
advanced technologies to  
match Customers' challenges  
in tough environments**



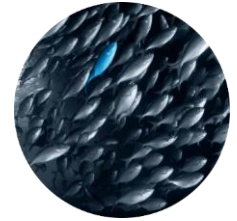
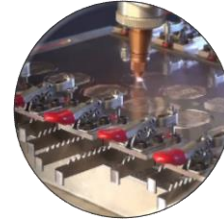
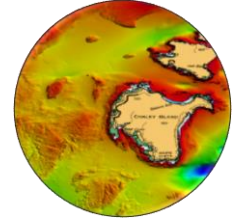
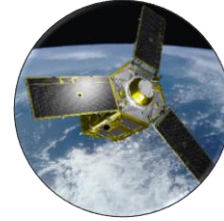
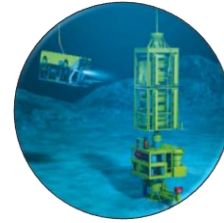




**All necessary know-how for any critical component or operation is developed in-house**

# Global Presence

## 24/7



## Global Markets

# iXblue

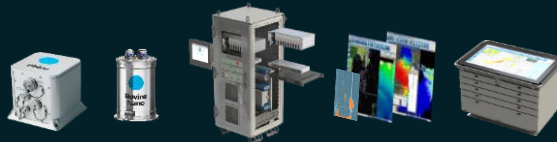
PHOTONIC SOLUTIONS



Specialty Fibers  
& Photonic  
Components

# iXblue

NAVIGATION SYSTEMS



Inertial Systems  
& Navigation Solutions

# iXblue

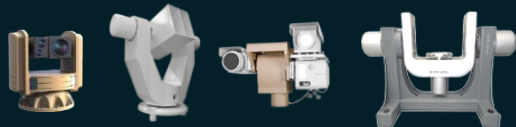
ACOUSTICS SYSTEMS



Acoustic Positioning  
& Sonar / Sounder solutions

# iXblue

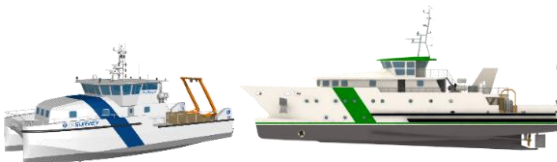
MOTION SYSTEMS



Multi-axis Tables, Simulators,  
Pan & Tilt & Positioners

# iXblue

DIVISION H2X



Composite  
Specialized ships

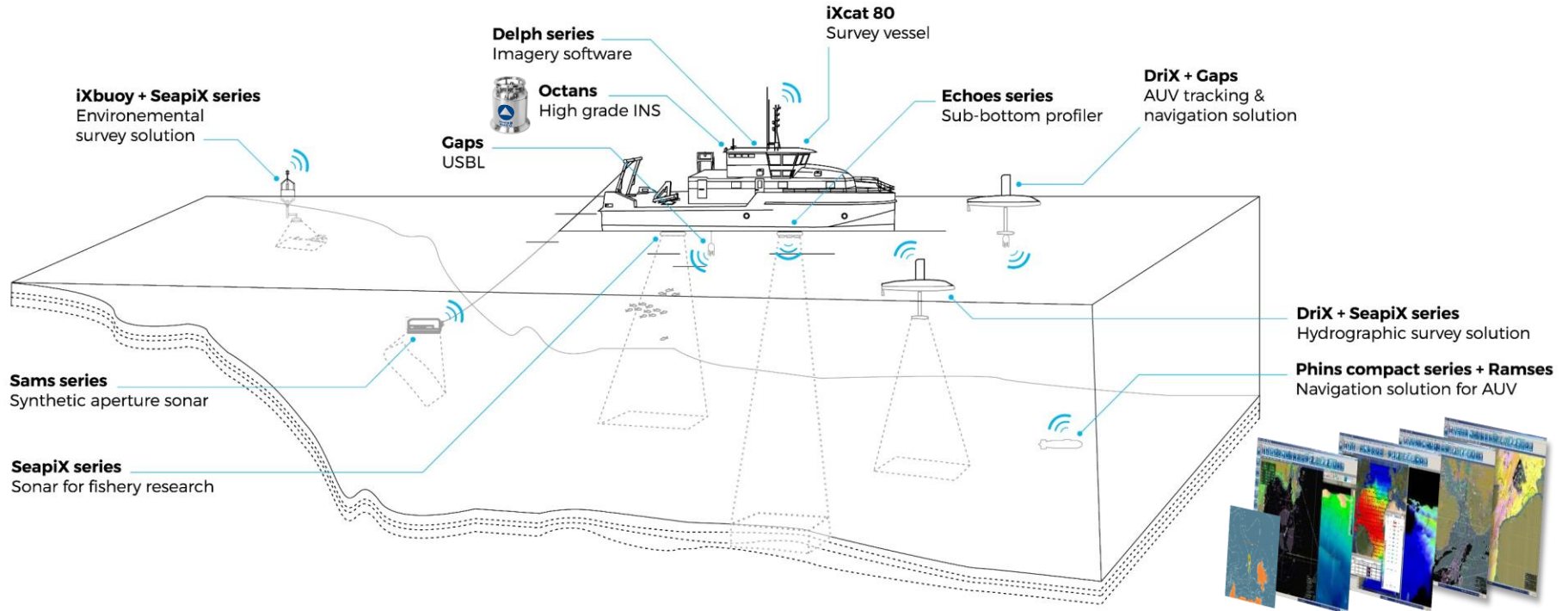
# iXblue

SEA OPERATION



A Survey  
Company

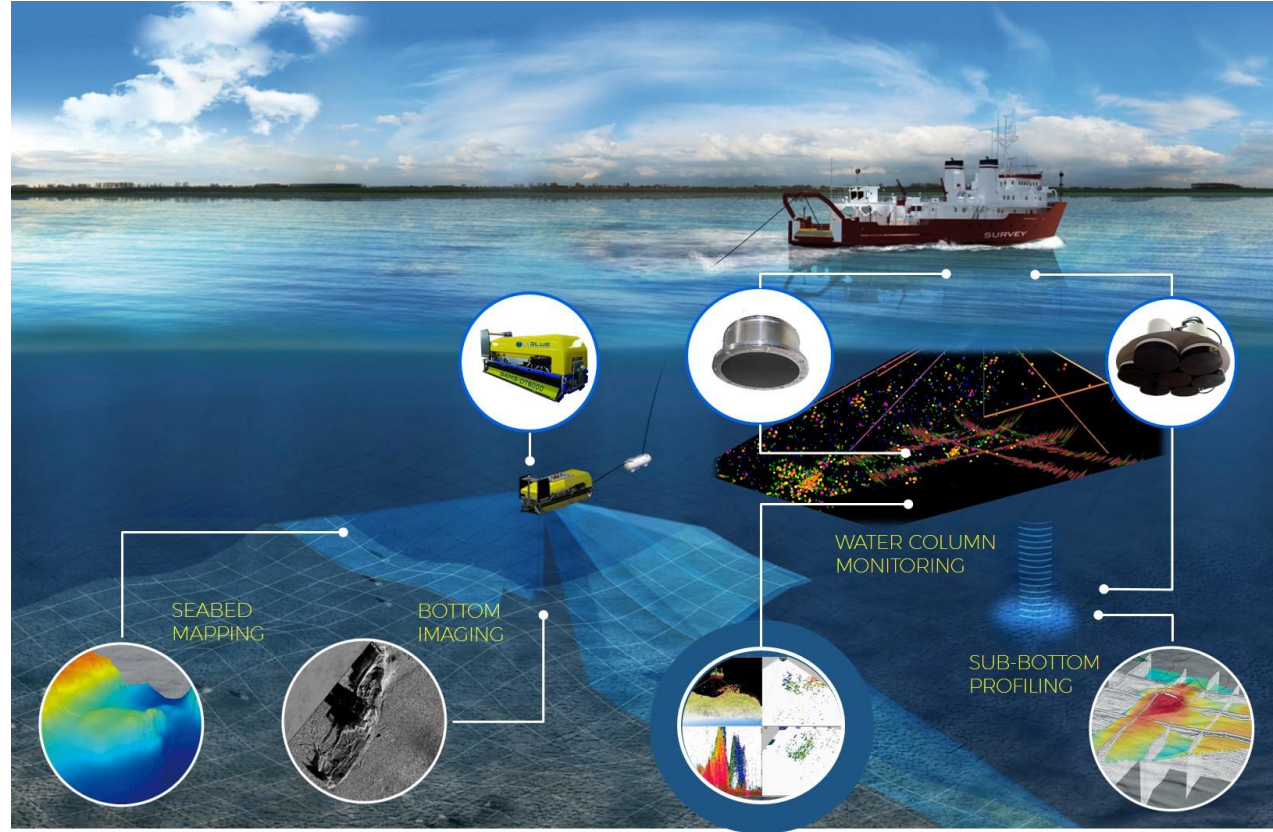
# Our strength : building on in-house Expertise





# Sonar System Division

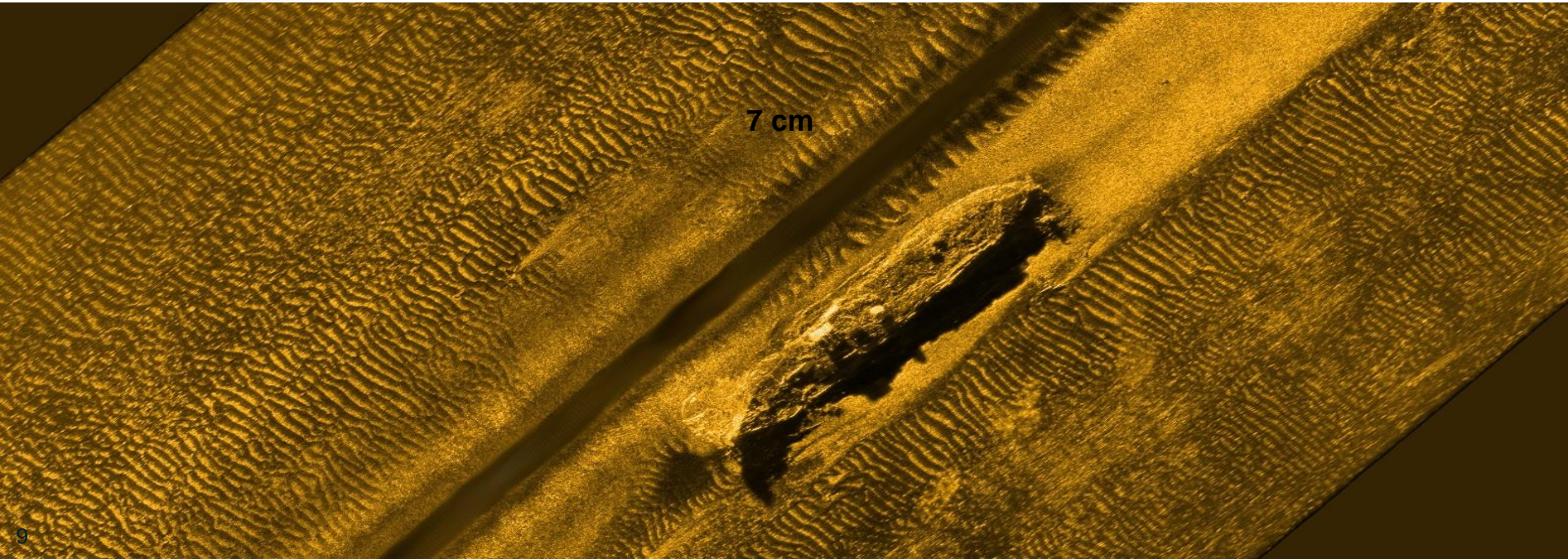
- More than 30 years of experience in acoustic solution design
- Ocean Imaging
  - o Water Column
  - o Seabed
  - o Sub-bottom
- Key technologies
  - o Transducers
  - o 3D MBES
  - o Inertial SAS
  - o Software image processing
- 1400 m<sup>2</sup> facilities @ La Ciotat shipyard including water tank (acoustic testing down 8kHz)





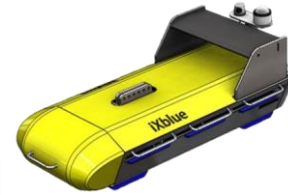
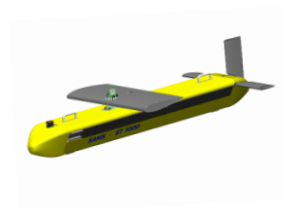
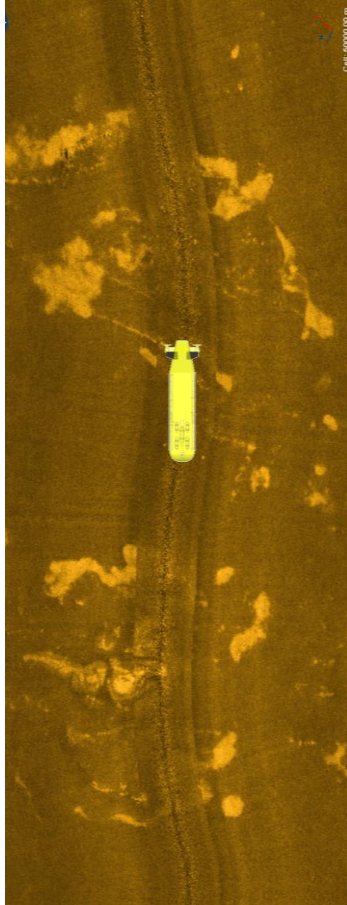


## SAMS Inertial SAS Mapping



# SAMS Product Range

SAMS-150-STD-1000 SAMS-100-LR-3000 SAMS-50-LR-6000



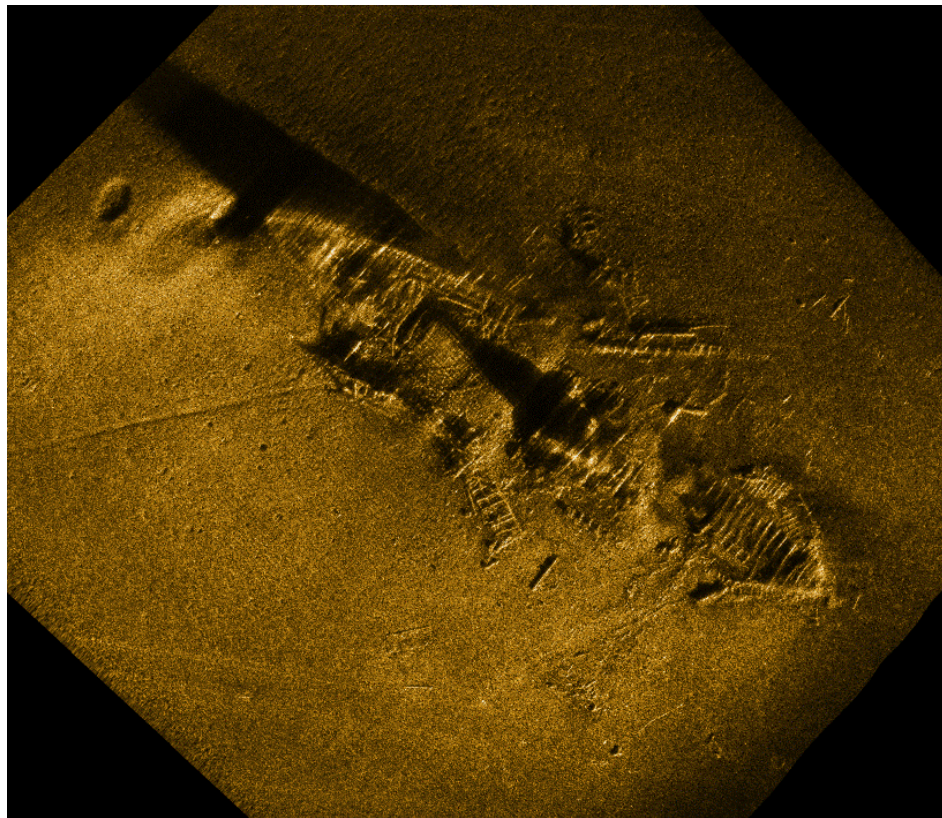
Reference	Length	Swath	Resolution	Operation Speed	Operation Depth	Full Swath Bathymetry
SAMS-150 Compact	1.2	500 m	7 cm	4	300	Yes by Default
SAMS-150 Standard	1.8	500 m	7 cm	7	1000 3000	Yes by Default
SAMS-150 High-Speed	2.4	500 m	7 cm	10	1000 3000	Yes by Default
SAMS-100	2.1	800 m	15 cm	6	1000 3000	Option
SAMS-50	3	1600 m	40 cm	3	6000	Option



# SAMS iXblue Inertial SAS

## Key Features

- Real-Time Georeferenced Sonar Mosaic
- Sub-metric Absolute Positioning
- Optimizing target detection (Non coherent integration) and classification (high-resolution – coherent integration)
- SAS Gain > 6 in Any Condition  
(x10 more tolerant to platform motion than standard SAS)
- Raw Data available for Post-Processing
- Industry standard processing and analysis software solution
- Multi-sensor platform

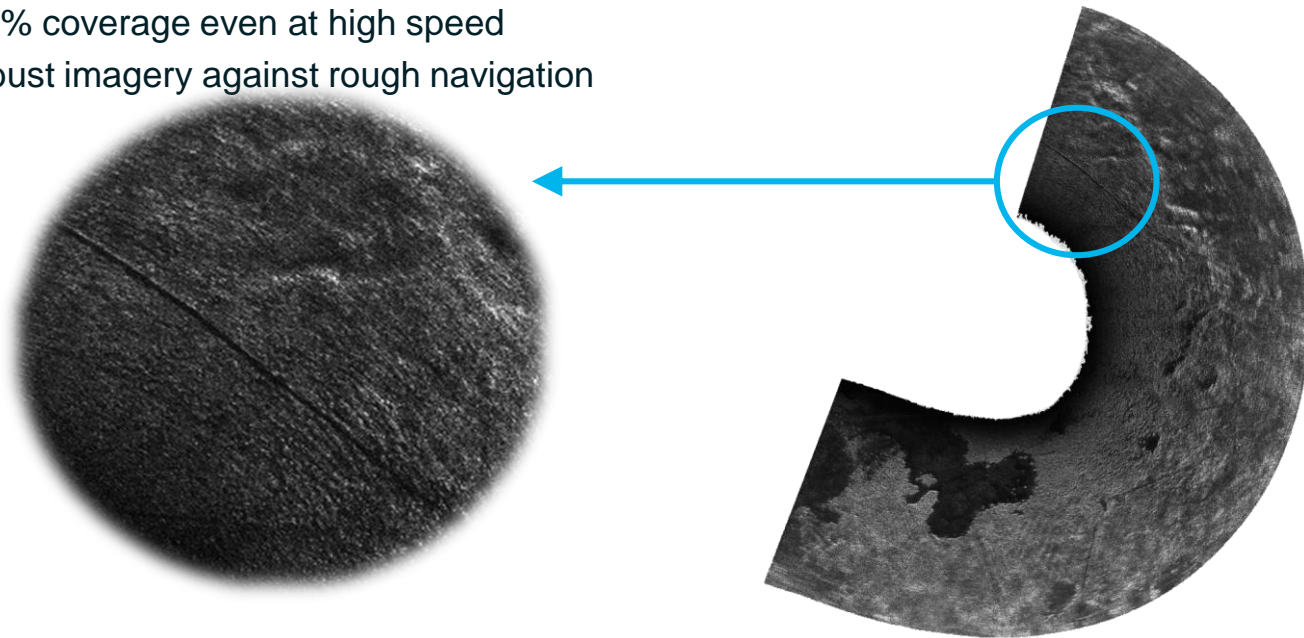


# SAMS – Performances & Results

Extreme case: Imaging in U-turn

## Wide Aperture Imaging

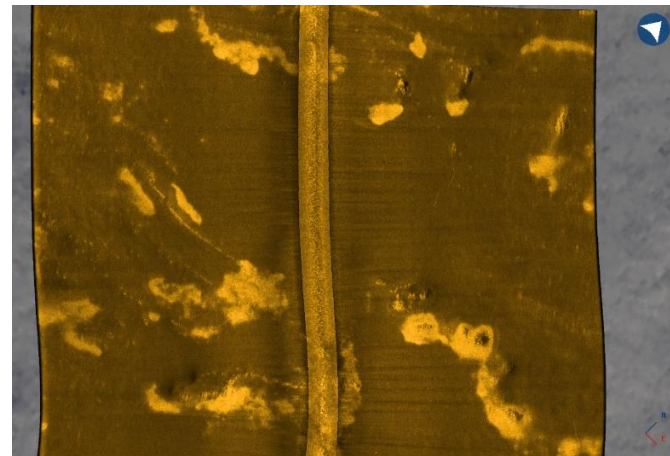
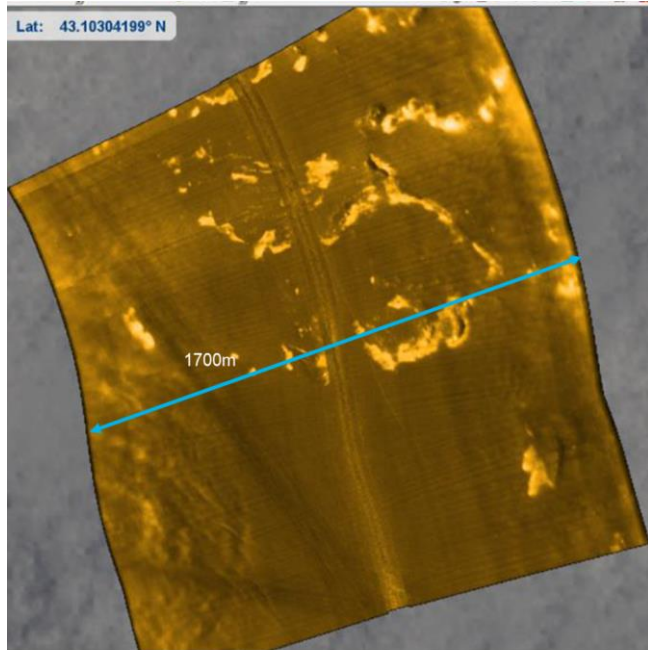
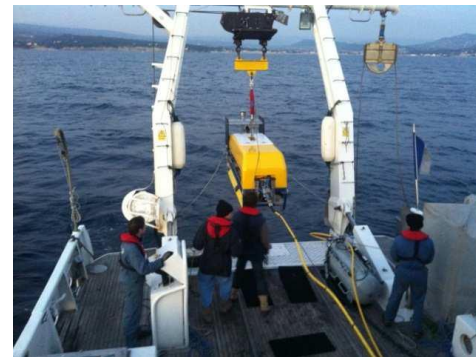
- Multiple sidescan beams are formed inside the wide emission aperture
- 100% coverage even at high speed
- Robust imagery against rough navigation



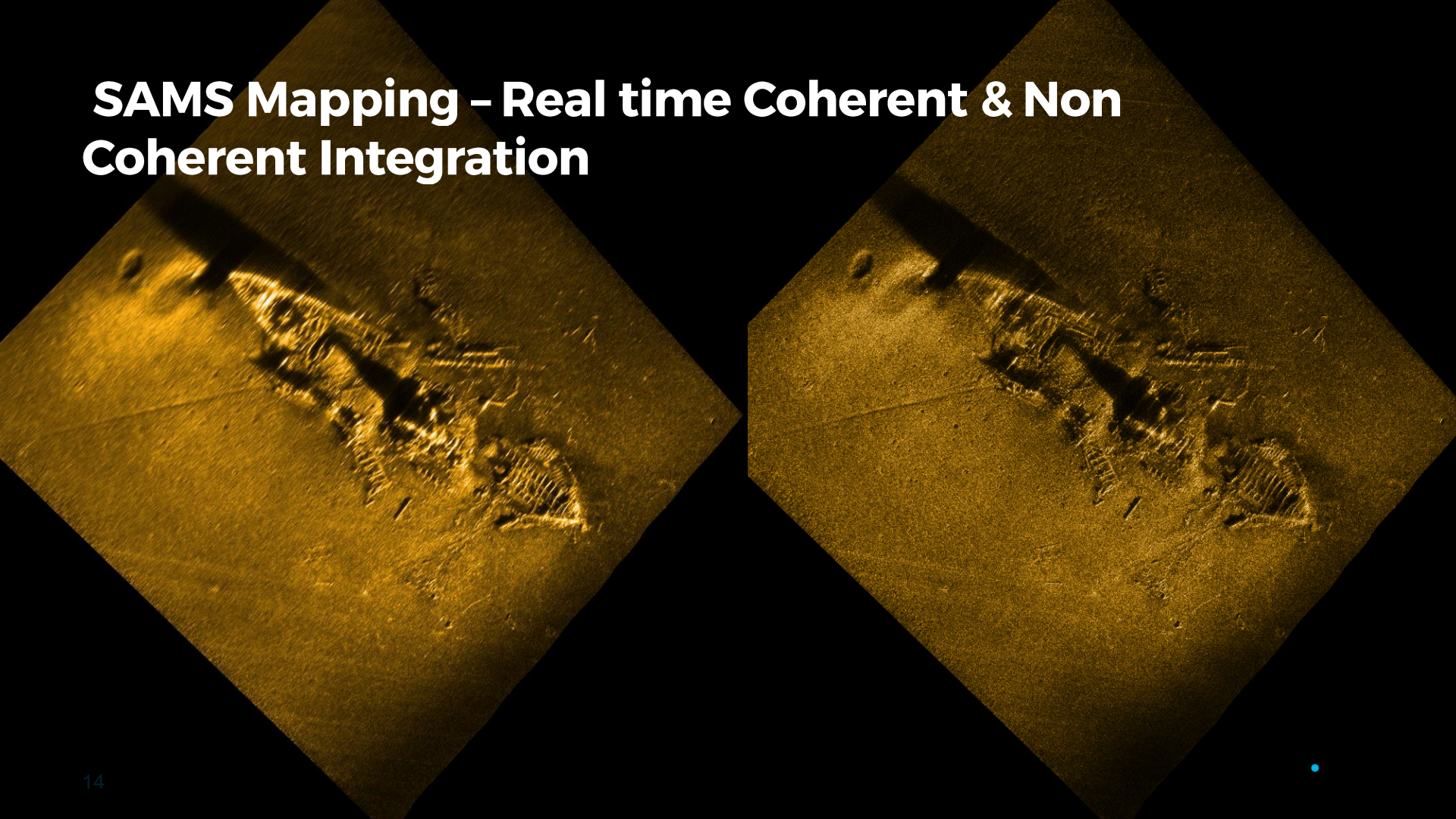


# iXblue Deep-Tow Inertia

SAMS-50-DT-6000



# SAMS Mapping – Real time Coherent & Non Coherent Integration



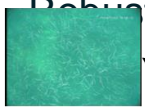




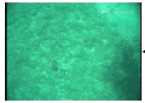
# Seabed Classification: a unique robust method

- Use of axial mode to measure the full backscattering energy in function of the grazing angle

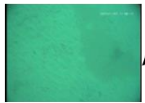
- Robust



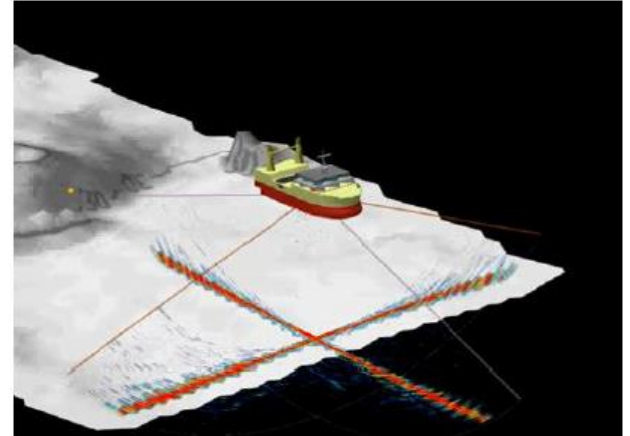
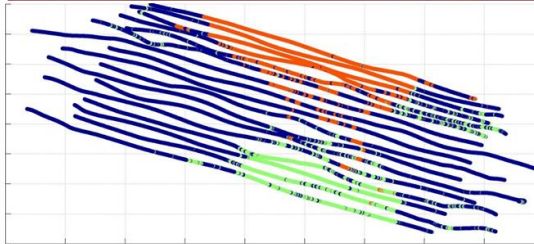
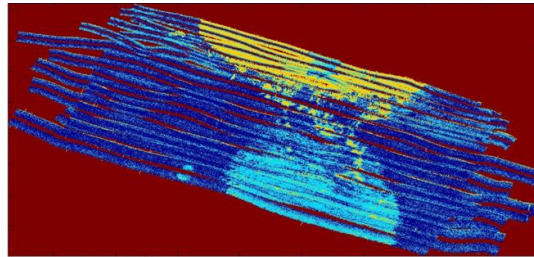
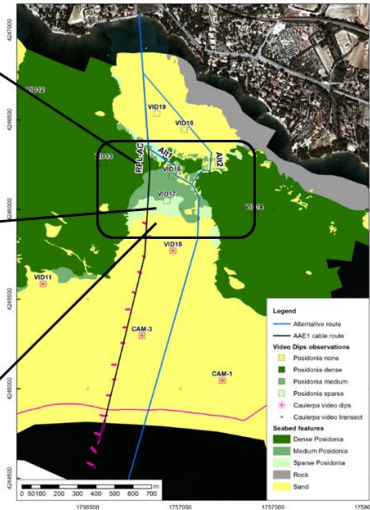
Dense Posidonia



Sparse Posidonia



Sand

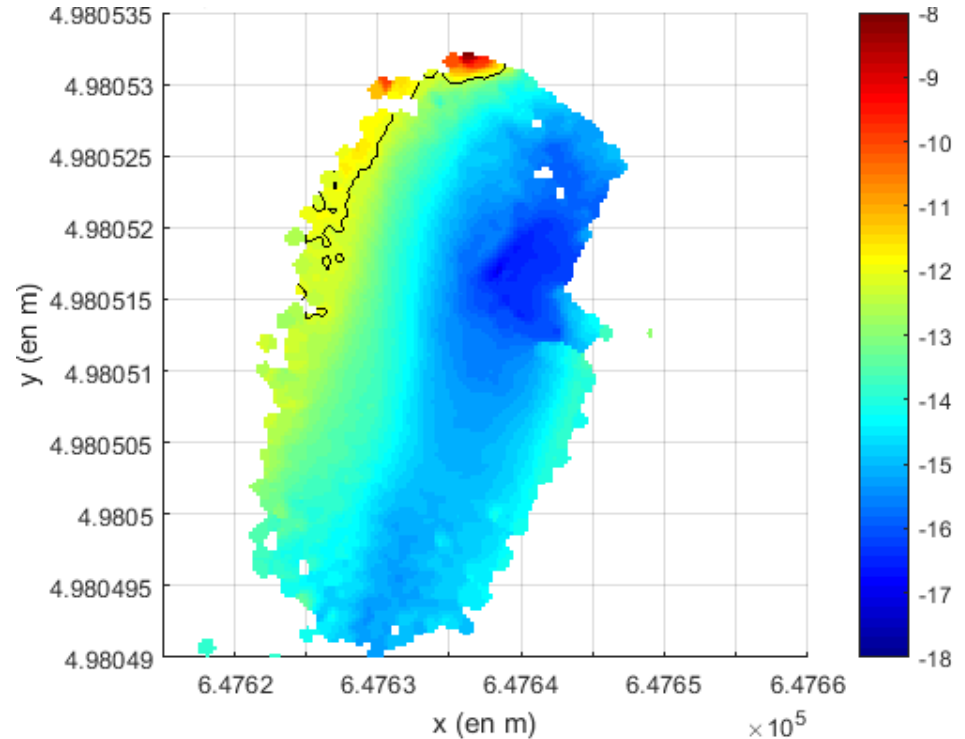




# Static Bathymetry : for dam and river

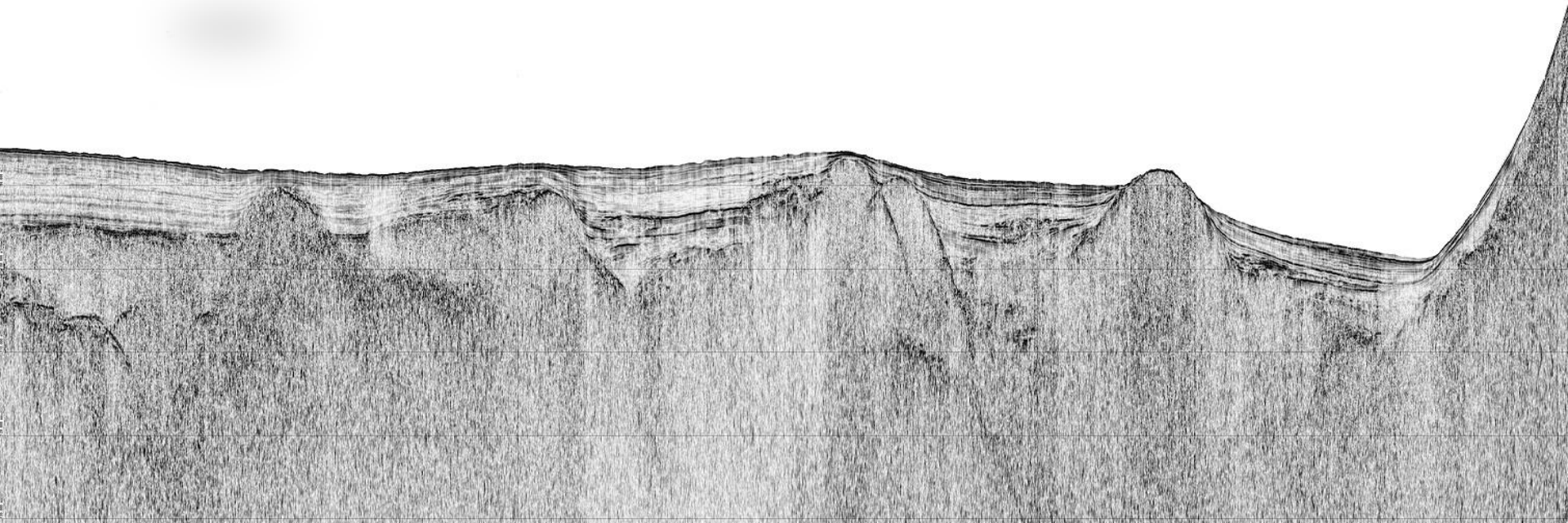


iXblue Sonar System Division



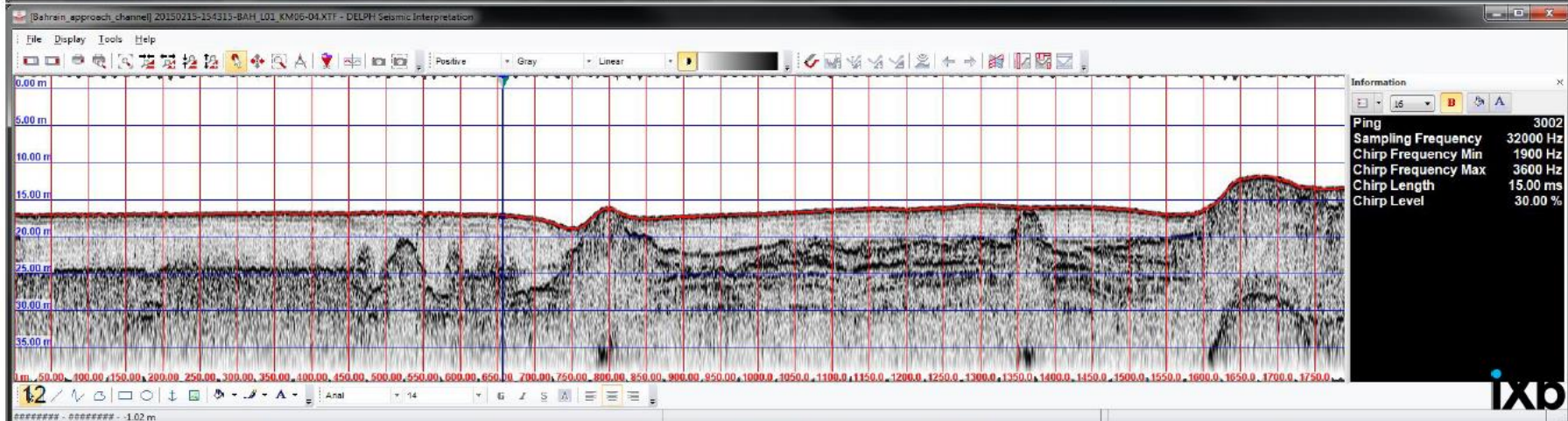
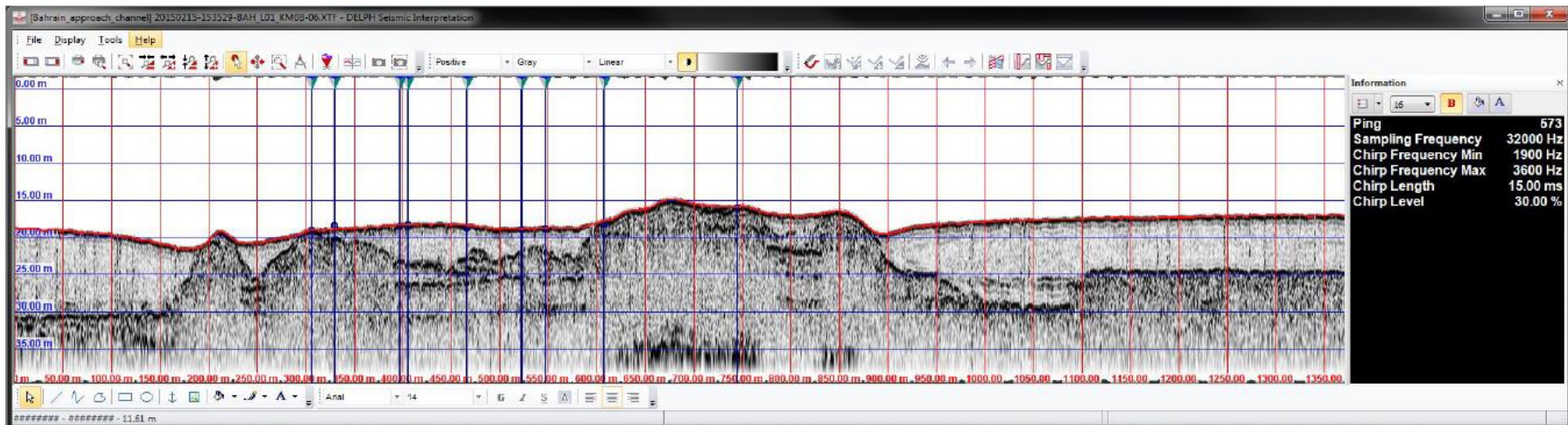


## **ECHOES Sub-bottom Profilers**

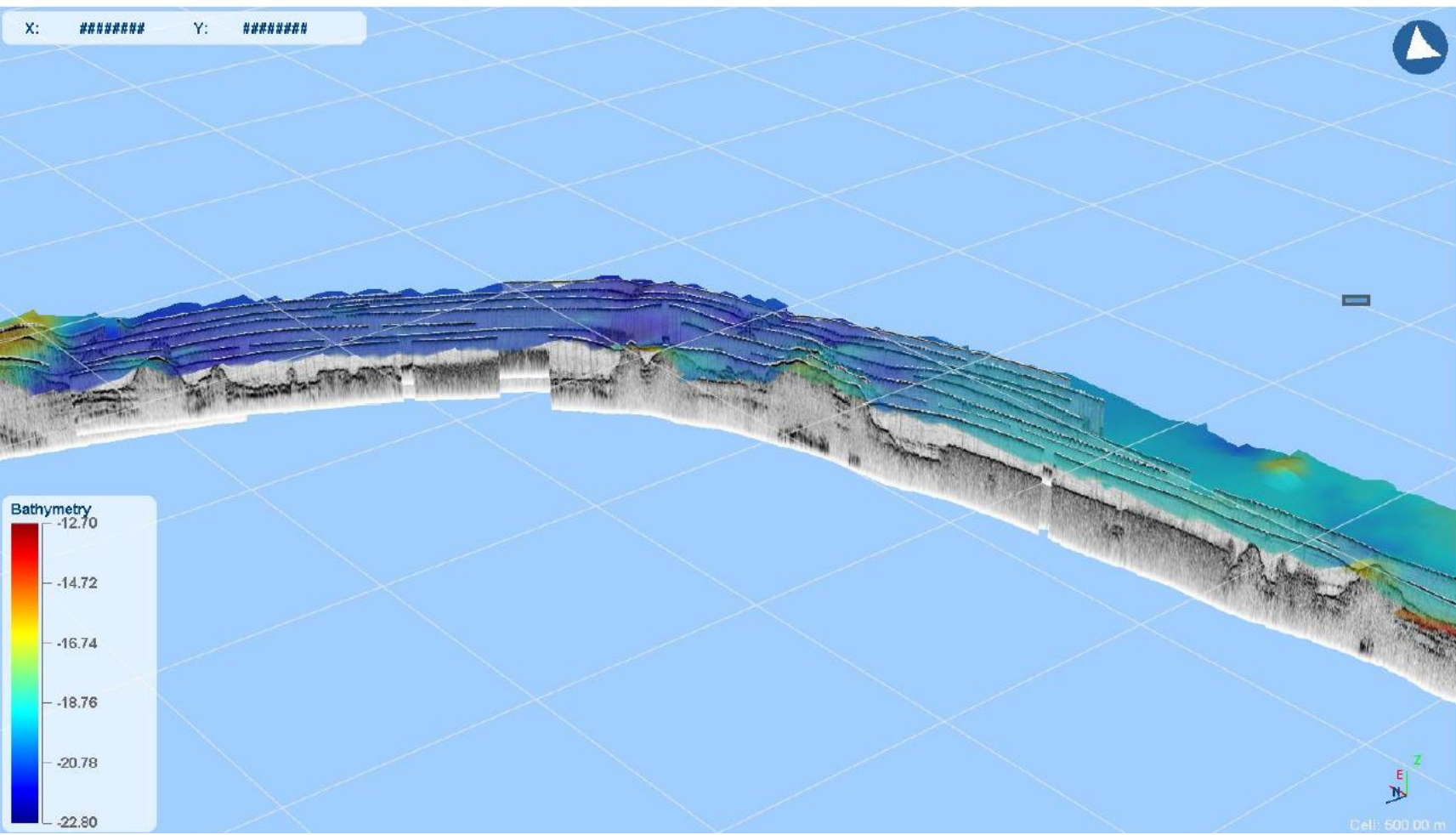




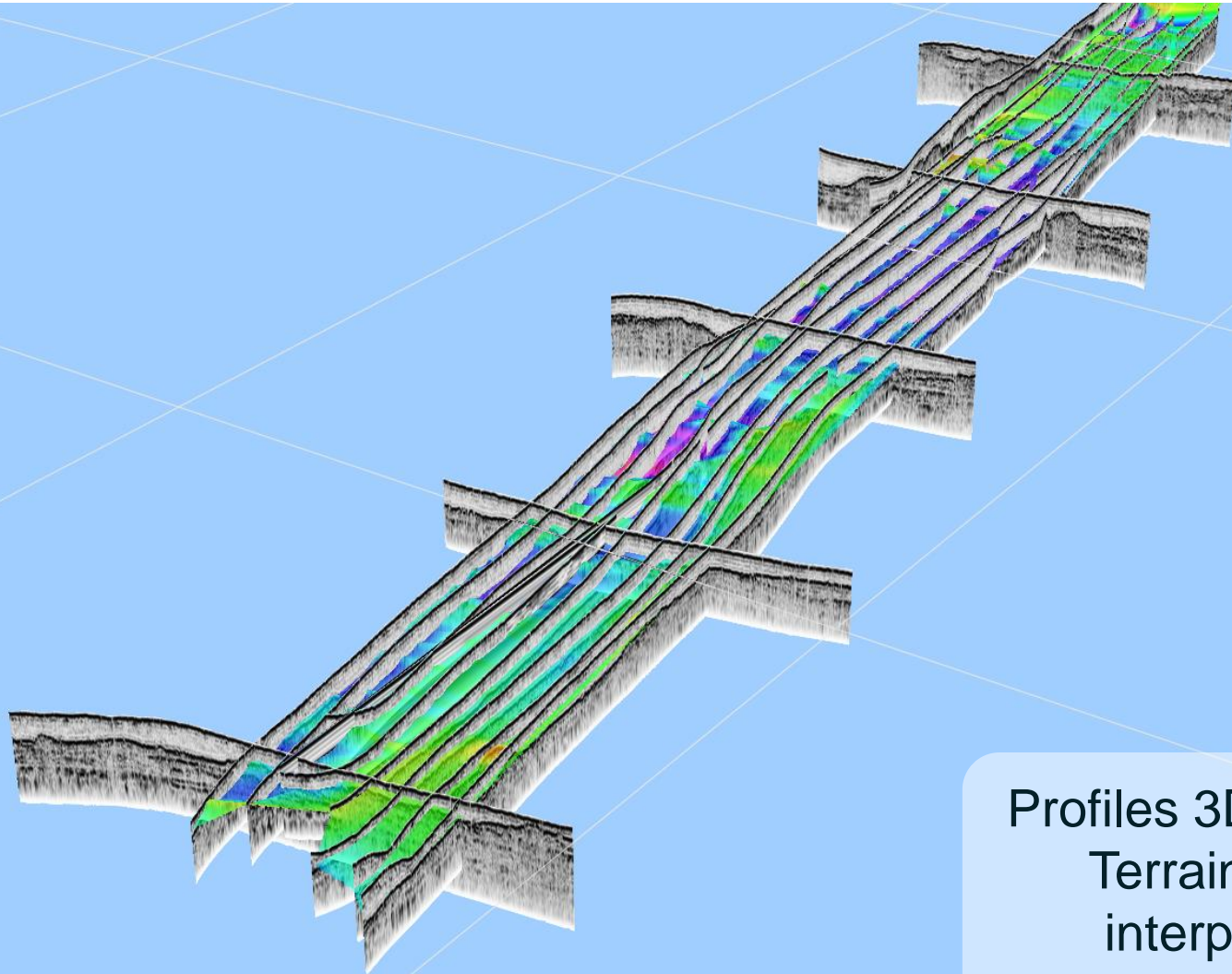
# Echoes 3500 T3 Dataset



# Echoes 3500 T3 Dataset

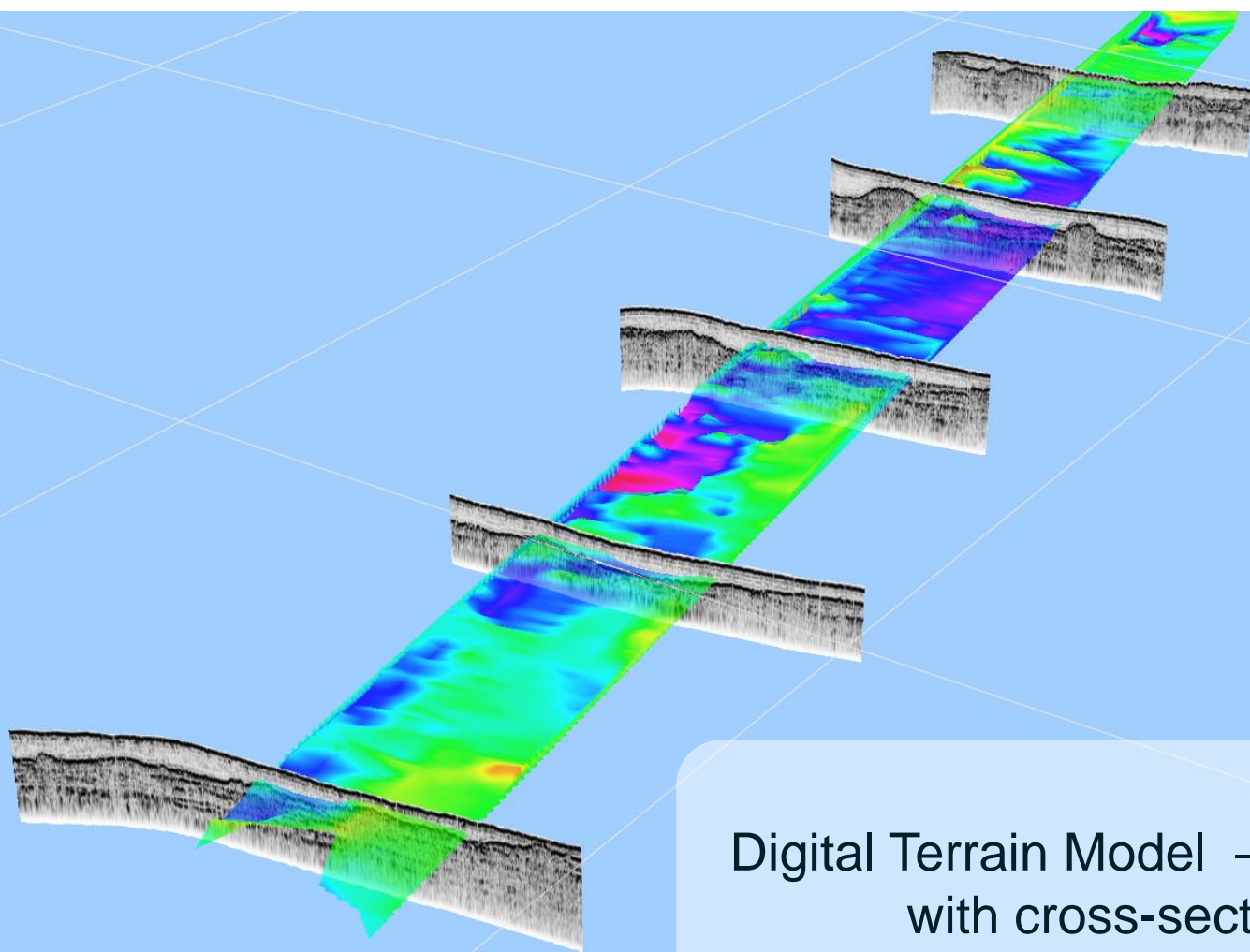






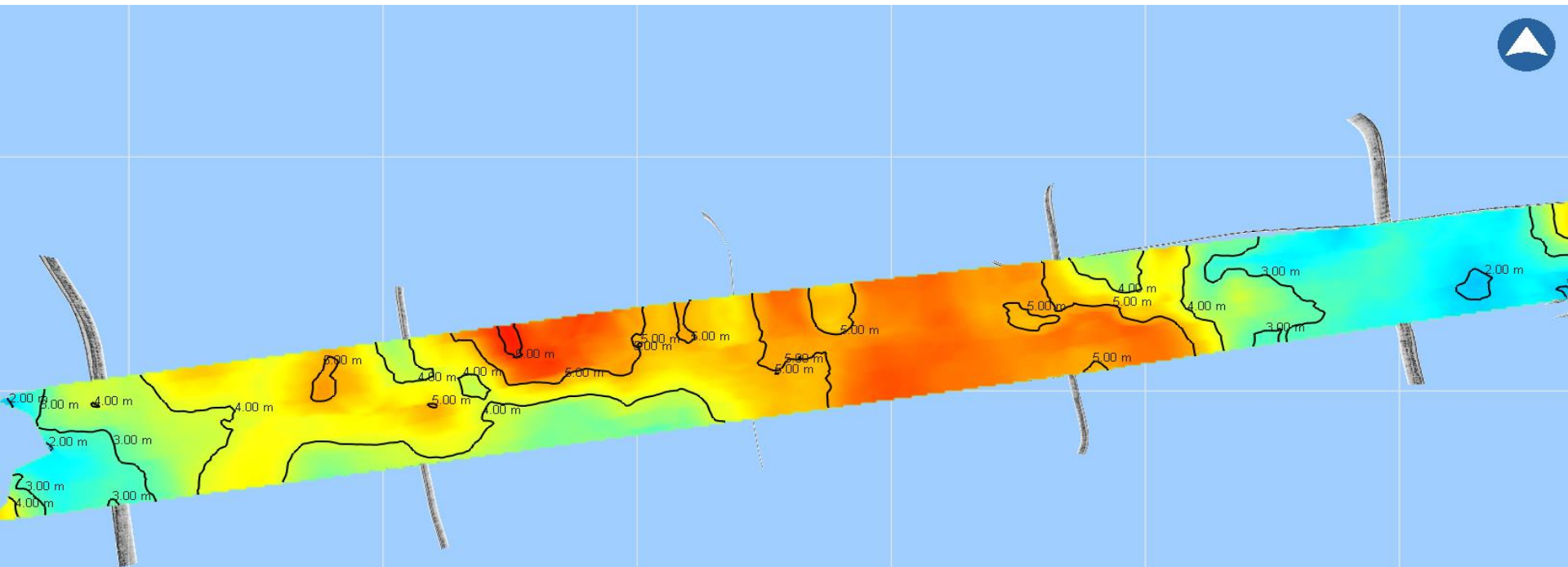
Profiles 3D display &  
Terrain Model  
interpolation

Cell: 1000.00 m

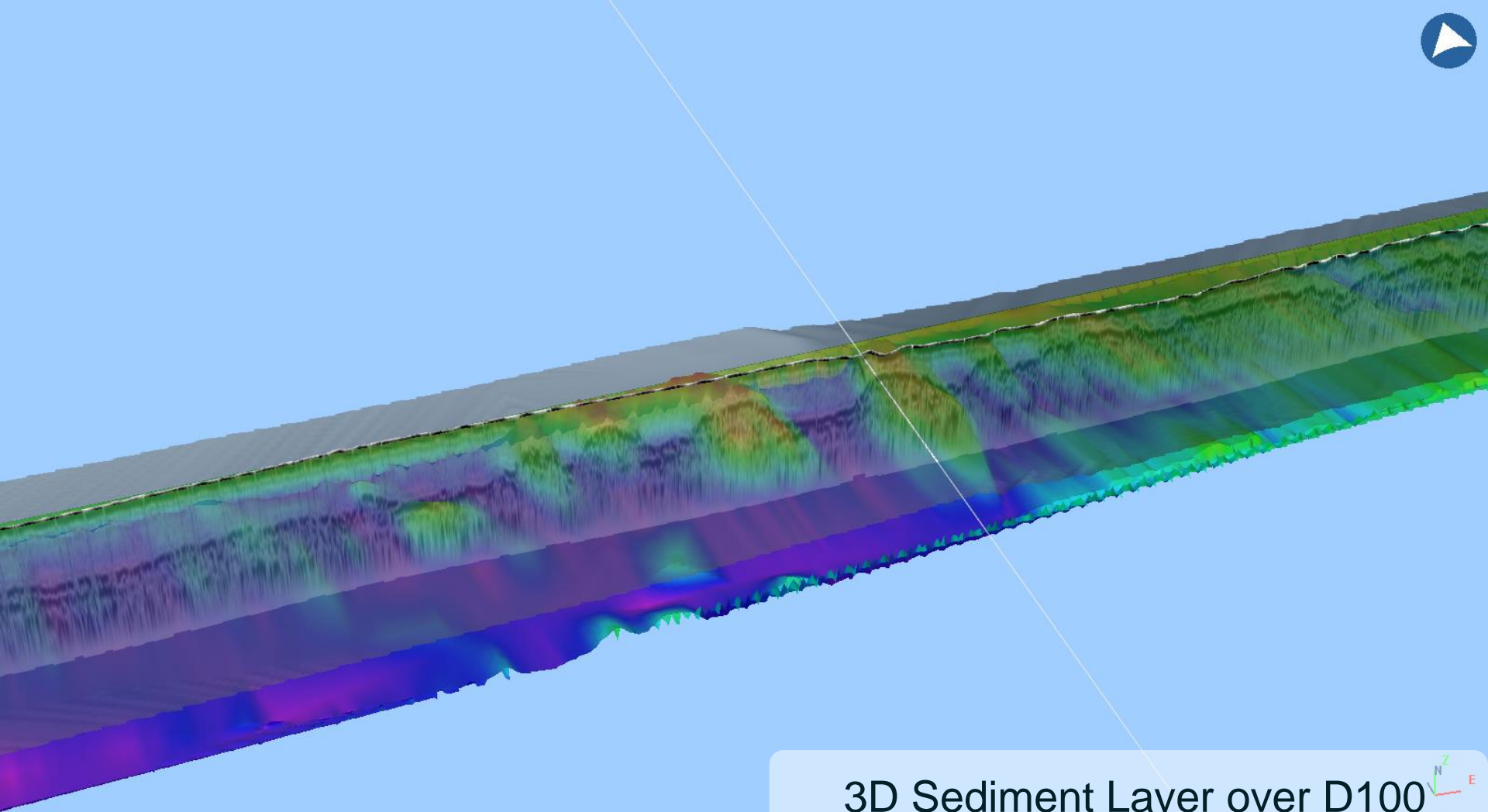


Digital Terrain Model – Unit D100  
with cross-sections





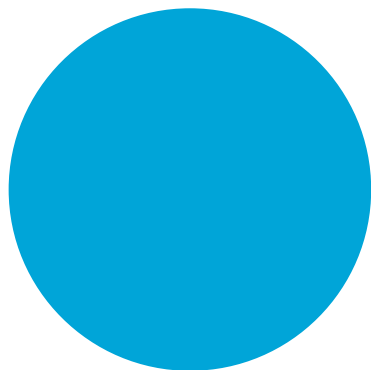
Isopach map – Thickness between seabed & unit  
D100



3D Sediment Layer over D100







**The rise of AUSV to perform  
high quality hydrographic  
survey.**

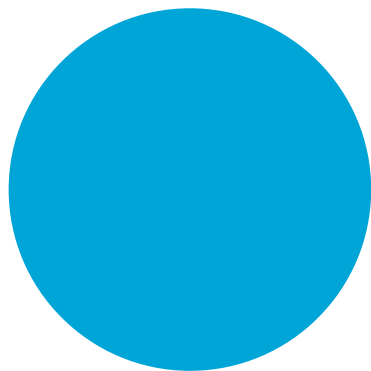
## **DRIX – Case Study**

**Author: David Vincentelli, iXblue**  
**[david.vincentelli@ixblue.com](mailto:david.vincentelli@ixblue.com)**  
**+33 647 330 120**

**ROPME, 19th of February 2019**

# TABLE OF CONTENT

1. What is the AUSV DriX
2. Theoretical expectation
3. Large scale deployment
4. Other applications



## **WHAT IS THE AUSV DriX ?**



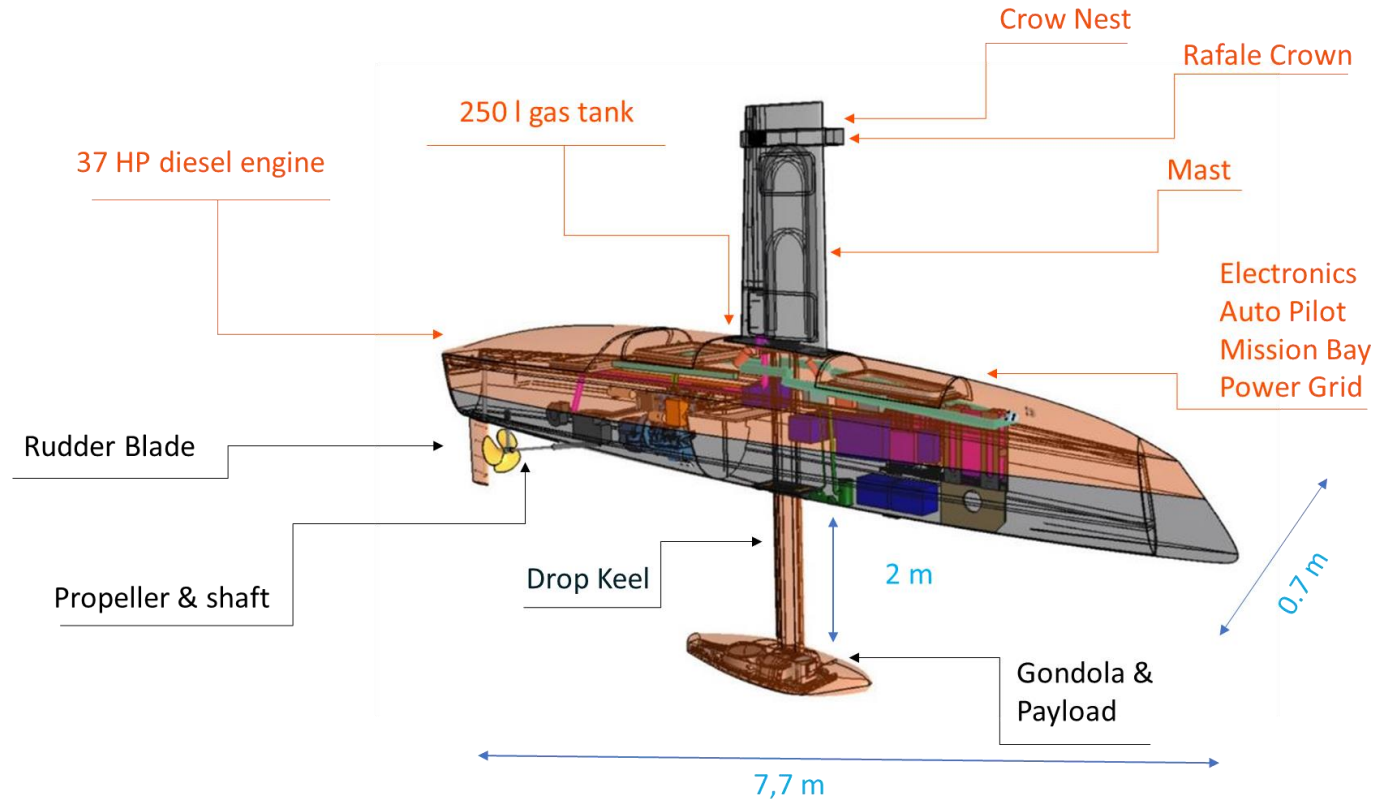
# DriX : AT SEA

DriX first test in the North Sea operated from a Mother Vessel



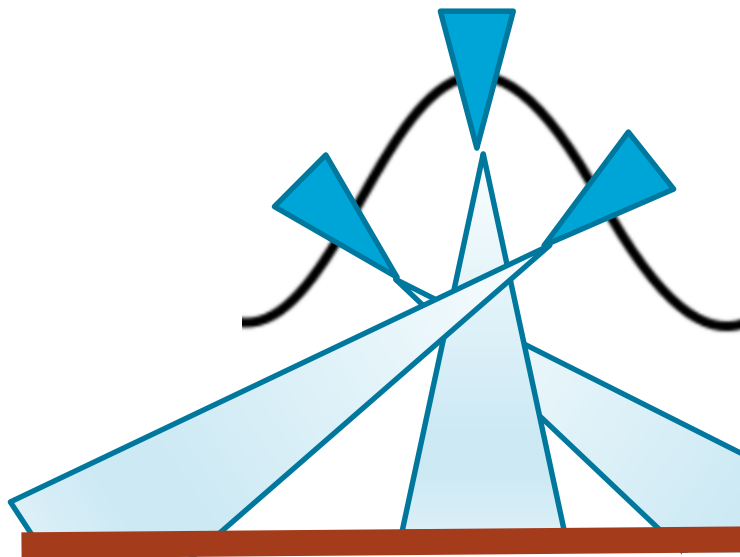
# DriX : THE INSIDE

A Naval Architecture breakthrough, reliable as a workhorse should

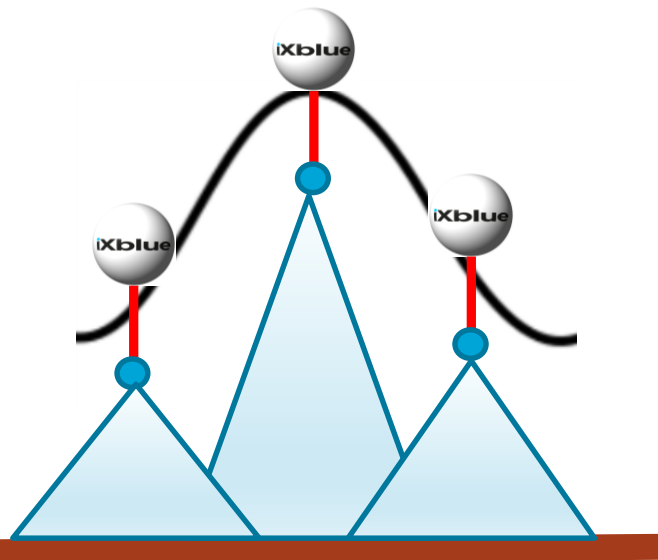


# A bit of naval architecture

DriX is a ping pong ball!



Traditional V-shape hull  
riding a wave



DriX riding a wave

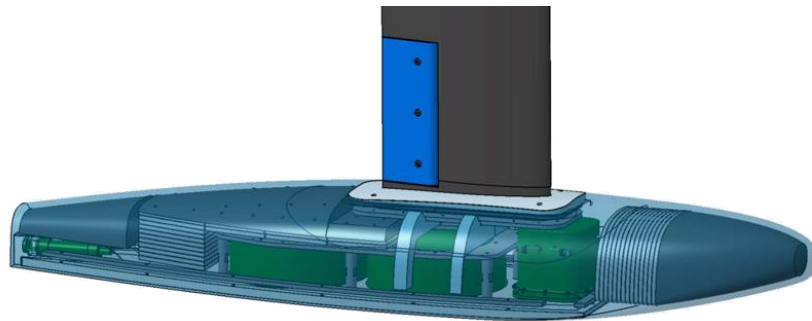
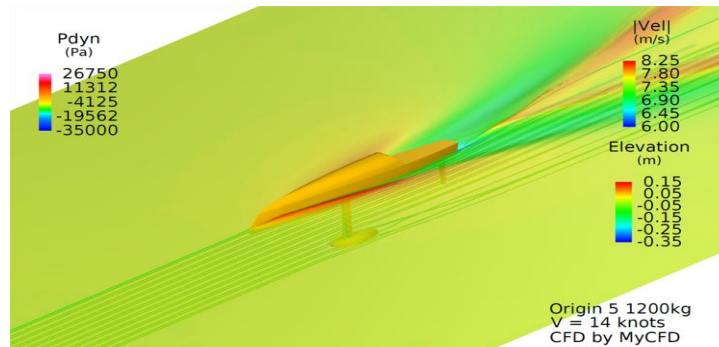


# DriX : AN UTMOST STABILITY FOR THE SENSORS

Video of DriX in strong winds (40kts)



# DriX : GONDOLA

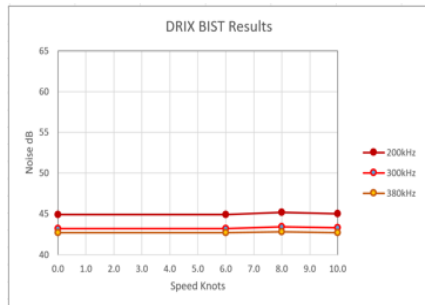


- Custom made to accomodate your equipment
- Makes the most of hydrodynamics
- Can be oustrehted to 3 m x 2 m

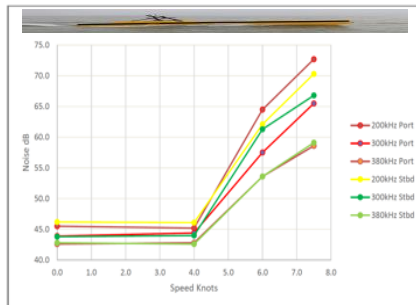
# GONDOLA MBES INTEGRATION

BIST TEST : Results of the observed noise level using a EM2040C MBES transducer

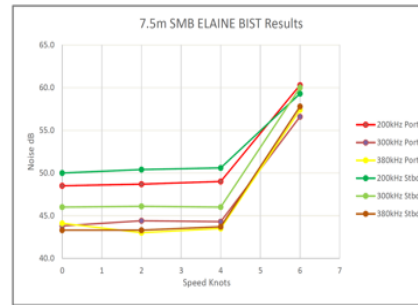
## DriX (Gondola in France)



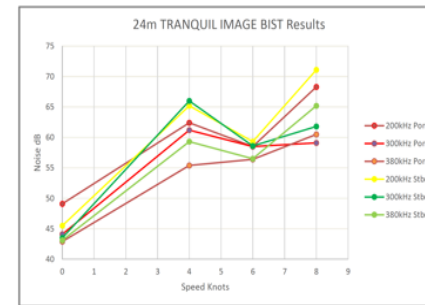
## Other AUSV Long endurance Length 5m (Hull mounted in France)



## Elaine (Gondola in NZ)



## Tranquil Image (Gondola in NZ)

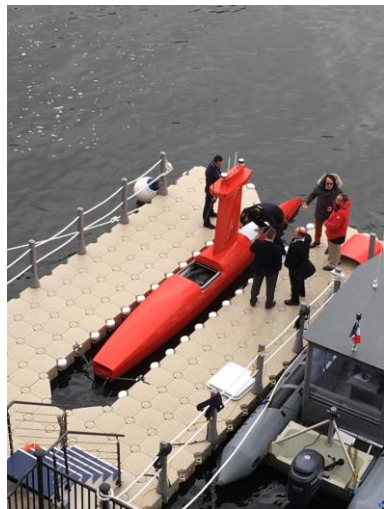




# EASY ACCESS FOR MAINTENANCE

## Access to DriX's main compartment:

unclip a Kevlar canopy, unbolt the hatch underneath - 4 quick bolts



## At Sea

its LARS is a comprehensive maintenance interface





2

## THEORICAL EXPECTATIONS

# FIRST CASE STUDY - La Ciotat (France)

Hydrographic IHO grade survey test in shallow waters [16m – 80m]



## Standard Hydro-grade set-up

- Real-time mission planner and acquisition: QPS Qinsy
- Motion Sensor: iXblue Phins C7
- GNSS: Trimble receiver
- MBES: Dual head EM-2040 in line
- Positioning post-pro: Grafnav

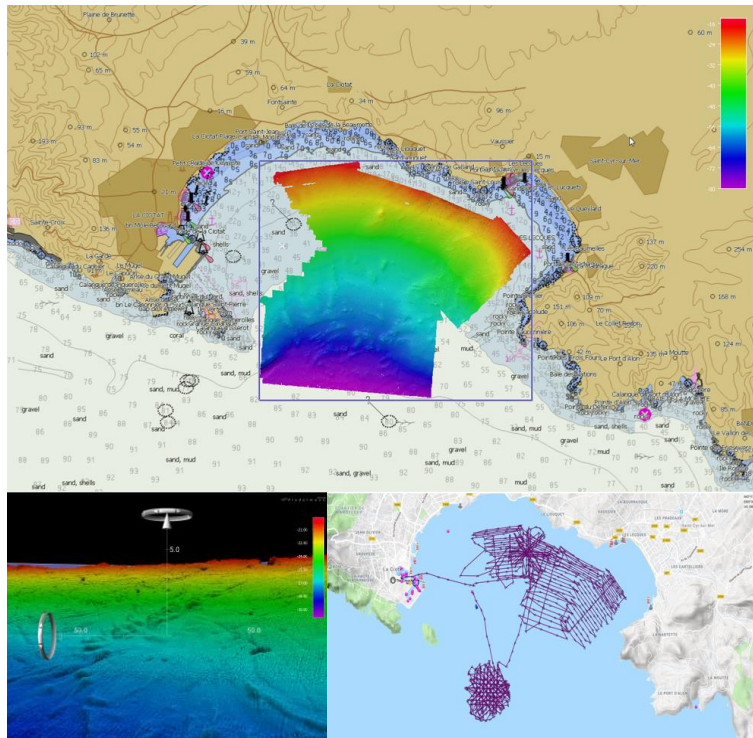
## The survey plan:

- 30 hours continuous acquisition
- Including calibration sites at various depth
- Survey speed tested: 4 to 12 kts
- Survey site water depth: 10 to 80m



# RESULTS

Test in shallow waters [16m – 80m]



- No survey downtime for crewchange
- Line Keeping : No rerun for steering issue
- Line Change : 1 min (incl. Motion stab)
- Average survey speed : 8 kts
- Qualified Special IHO Order up to: 10kts @ 30m

At survey speed

- Fuel consumption: < 2 L/h
- Weather contingency: BEAUFORT 4

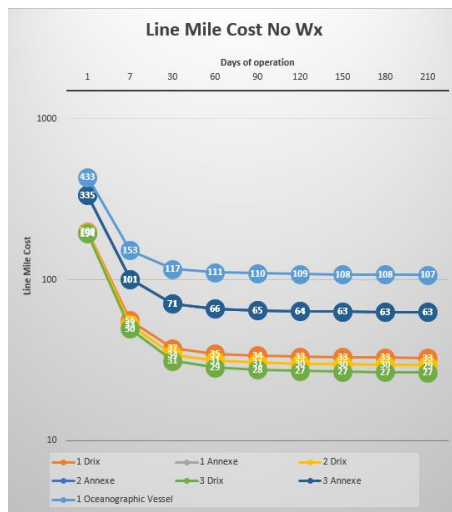
# PERSPECTIVES FOR THE HYDROGRAPHIC MARKET

Operational and maintenance cost comparison

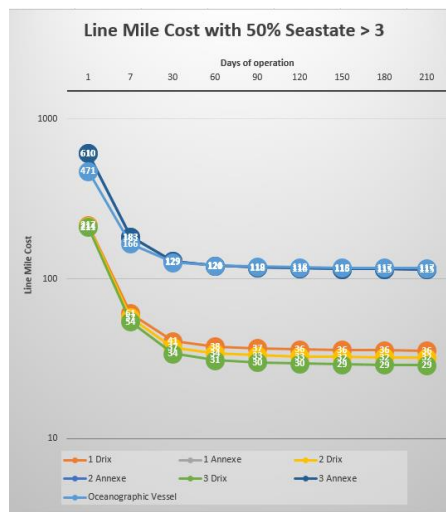
## Line mile cost comparison

### DriX versus oceanographic vessel & small boat

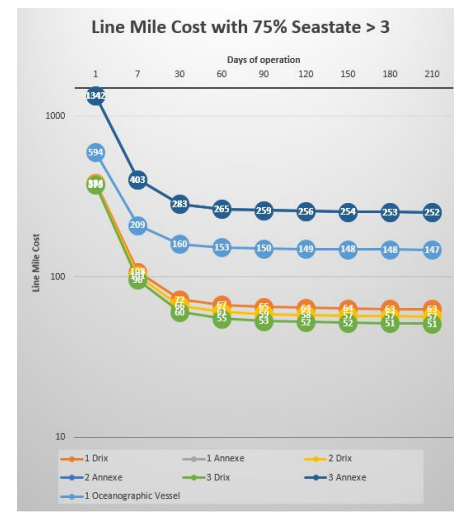
Sea state <3



50% of sea state >3



75% of sea state >3



# OPERATIONAL EFFICIENCY – Hydrographic survey work

## DriX Vs. Conventional Survey Platform



### VS a Survey Launch

- Up to 4 x faster / 5 x cheaper
  - Faster line change
  - Unparalleled line keeping & endurance
  - No crewchanges
  - Capacity to survey in marginal weather



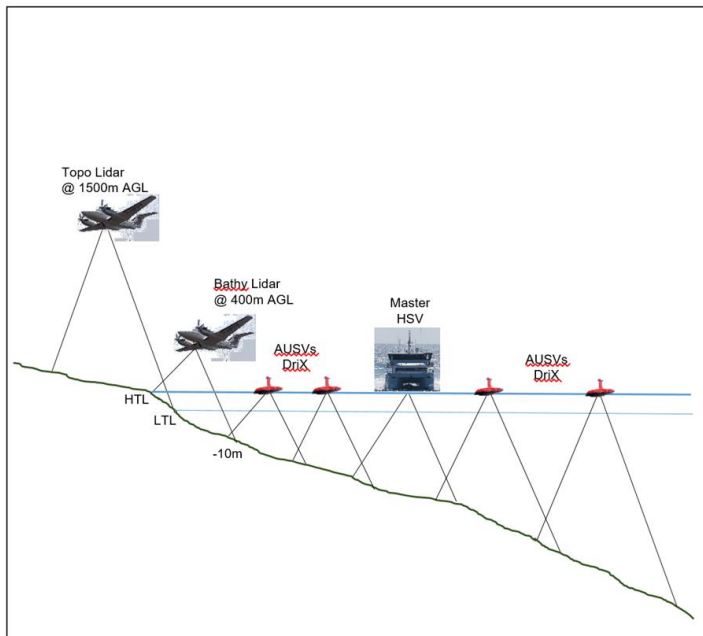
### VS an Oceanographic Vessel

- 1.3 x faster / 3 x cheaper
  - Unparalleled line change
  - Unparalleled line keeping
  - Low fuel consumption
  - little manning



# PERSPECTIVES FOR HYDROGRAPHIC MARKET

Integrate a multiplatform approach and adopt new survey strategy

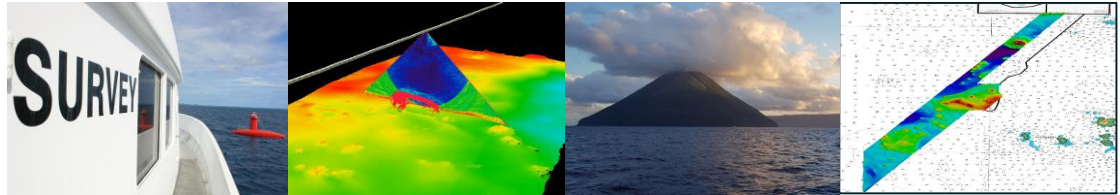


- **Gondola mounted sensor**
  - Reduced and compensated vibrations
  - Less weather limited
  - Outstanding data quality
- **Near Real-time data QC**
  - Real-time QC information transfer
  - Overlapping data acquisition from various source
- **New survey strategy**
  - Multiple sensor acquisition
  - Possible flexible scenario – scouting, shared tasks

# 3

## LARGE SCALE DEPLOYMENT

Field proven technology



# PROJECT CONTEXT

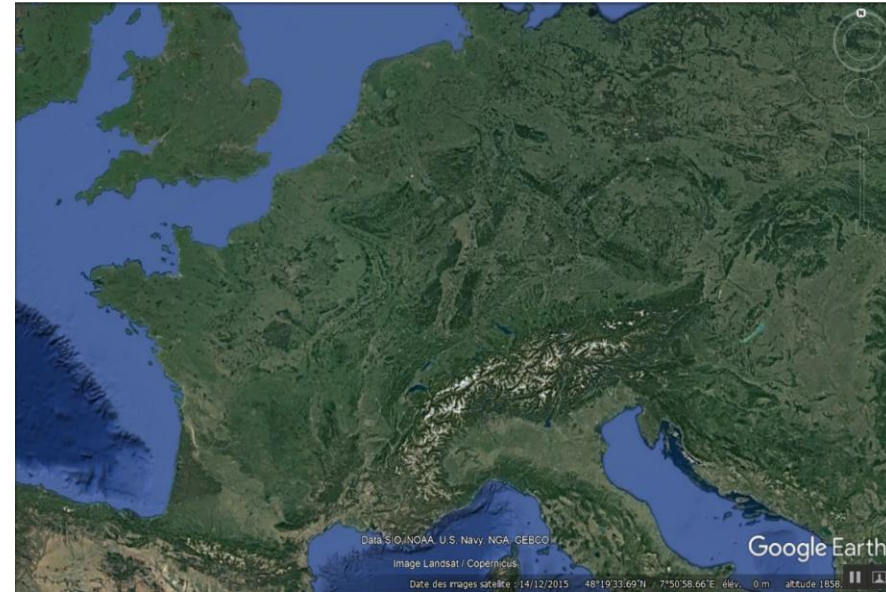
## Surveying the south pacific waters – Tonga Islands

- Project context

- Survey location : Kingdom of Tonga (archipelago of 170 islands)
- Client: LINZ (Land Information New Zealand)

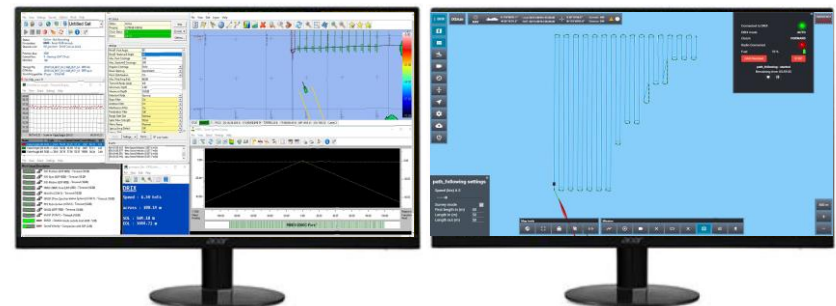
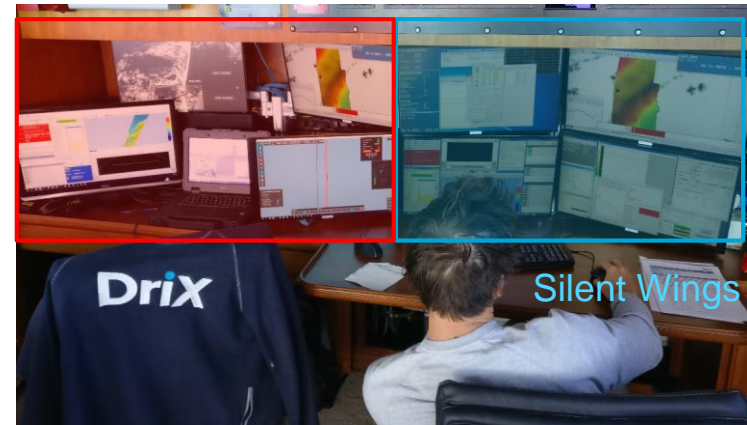
- Survey specifications

- Survey area oriented North/South, 200km long
  - Multiplatform approach:
    - Airborne LIDAR to cover areas 0 to 18m WD
    - Mother ship + AUSV to cover 694km<sup>2</sup>
- 7500 Line km



# CONDUCT OF SURVEY OPERATIONS

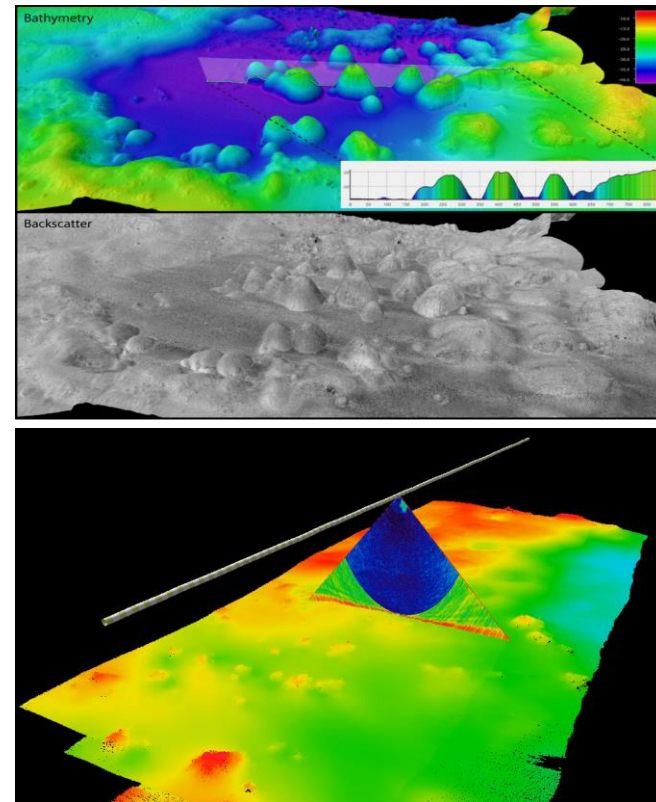
- Drix fitted on our support vessel without preliminary work
- 24/7 survey operations
- DRIX operating range from the Mother Vessel: up to 3,5km
- Drix surveyed with a max water height of 1,6m (sea state 4)
- Mother Vessel with a max water height of 2m (sea state 4/5)





# CONDUCT OF SURVEY OPERATION

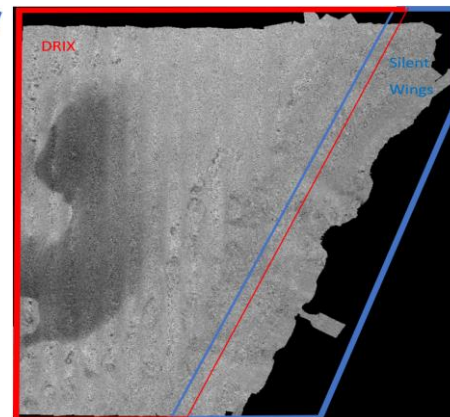
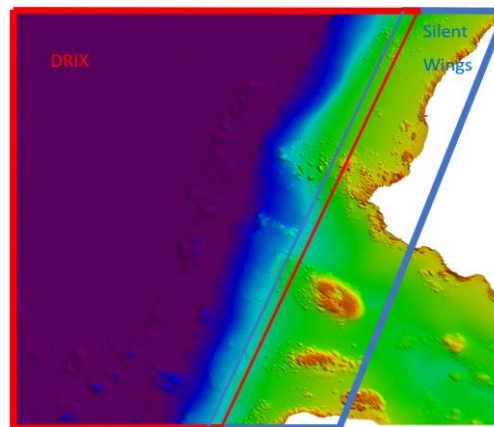
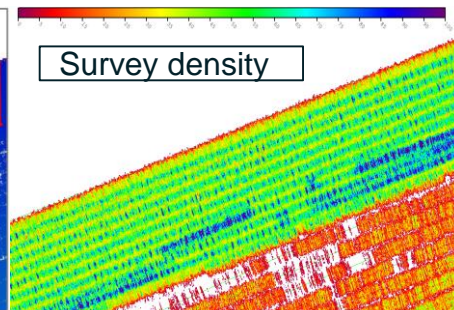
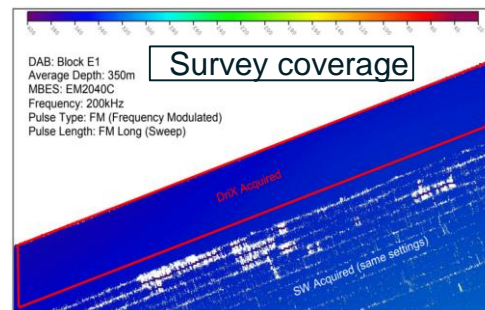
- Online
  - Acquisition of Mother Vessel survey Data
  - Sending missions / monitoring QC data of DRIX
  - Sound Velocity casts
  - Data backup of SW data
  - Download of DRIX's bathymetric data
- Post-processing of INS data using ixblue APPS software
  - Process of Drix and SW data (real time)
  - Export of smart heave solution
- Post-processing of bathymetric data in Caris
  - Merge and Process of Drix and SW data (real time)
  - Applying tide, squat and smart heave solution
- Post processing of backscatter and water column data
  - Processing of backscatter Drix and SW data in FMGT
  - Analysis of water column data in FM Midwater



# RESULTS

## On Data Quality

- Drix low noise level
  - Lost of seabed detection @ 320m for SW
  - 100% coverage @ 400m deep for DRIX
    - Improve bathymetric quality result
- Perfect complementarity between the two datasets
  - Average mean depth difference of 1.4cm on SW and Drix overlapping surfaces
  - Complete Merging of backscatter data



# RESULTS

## On Productivity

- Using DriX half of the time saved

- 33% survey duration
- 20% cost
- 34% carbon footprint

- Limitation on this project

- Impossibility to use DDS  
(DriX Deployment System)

Parameters	Drix	Silent Wings
Overall Line km	7450	
Line km	2360	5090
% of total line km	32	68
Effective survey time (Hours) *	166	358
Total use ** (days)	19	37
Average Survey Speed (knts)	7.6	7.6
Average transit speed	10	10
Autonomy @ average survey speed (days)	4-5	7
Fuel consumption @ survey speed (L/H)	2,4	~66

# 4

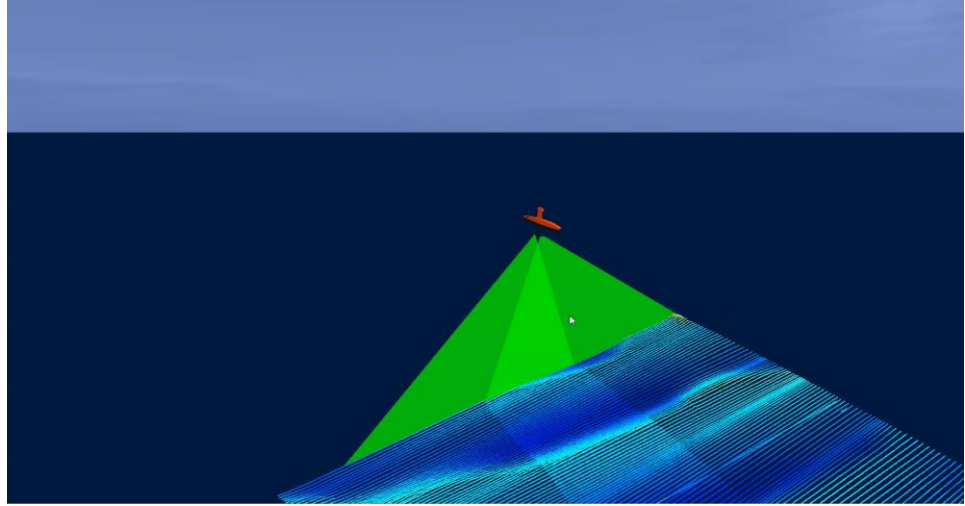
## Other applications

High opportunities and method optimization



# AUSVs - WORKING IN RESTRICTED AREAS

Scouring survey within a windfarm – Observed efficiency 3 to 4 times faster to conduct box survey

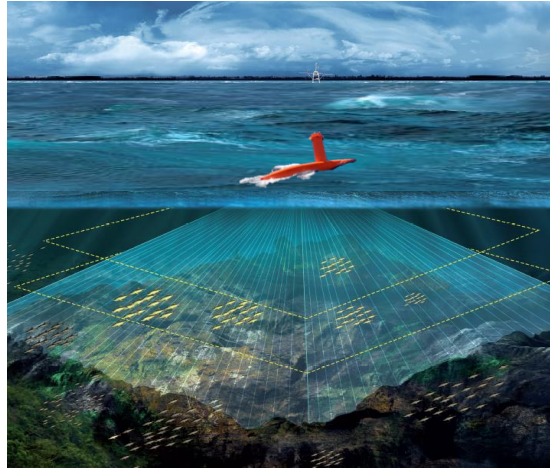


# UNDERWATER SURVEILLANCE AND MAPPING

**Day to day fairways  
surveillance**



**Support the fishing  
industry and marine  
environmental  
monitoring**



**Revealed the  
unaccessible**

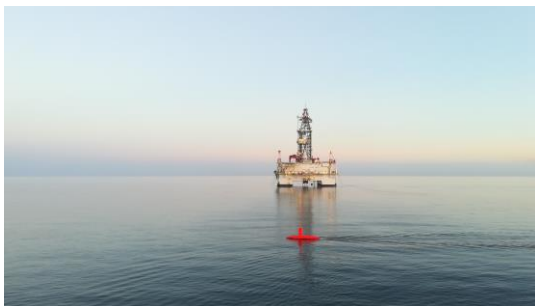


# METROLOGY – SUBSEA POSITIONING

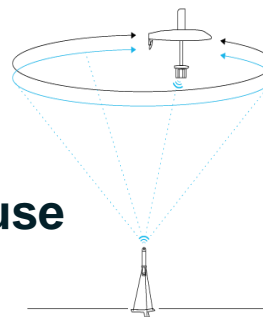
## BOX IN CALIBRATION

### Job description:

- Location : BAKU Azerbaidjan
- Calibration of 465m deep transponder
- Technique : Range only box-in
- Speed : 4knots and 8knots (dep. on circles)
- Box-IN radius : 300m and 500m

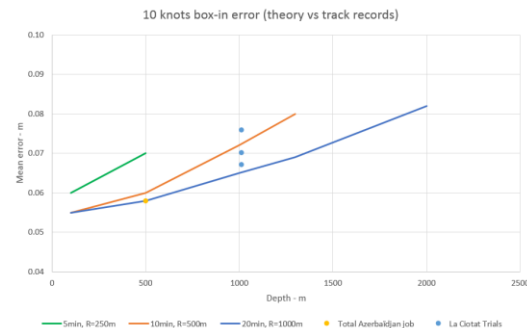


Easy to deploy, use



### RESULTS: Decimeter accuracy

- In 5min, up to 500m depth
- In 10min, up to 1300m
- In 20min, up to 2000m



# CONCLUSION USING DRIX TYPE AUSV



- Save time
- Increased data quality
- Provides Multi mission & transportable platform
- Improved safety of marine operations
- Buy, lease, service



**DriX**