

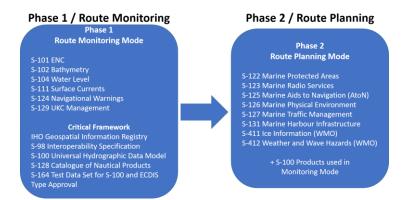
Eighth Meeting of the IHO Maritime Autonomous Surface Ships (MASS) Navigation Project Team (PT)

13th November 2024 – 1100 - 1300 (UTC)

Via

VTC (MS-Teams)

- 1. Welcome and Introductions.
- 2. Report from IHO Council and status of Project Team.
- 3. Revision of Terms of Reference and Work Plan for Project Team.
- 4. Review of Action Items from PT7:
 - a. ACTION-PT-7-1: To think and propose candidacy for role of Secretary All Members
 - b. ACTION-PT-7-2: To recruit new Member States in areas of MASS activity Chair
 - c. **ACTION-PT-7-3**: Recruit additional MASS industry experts, specifically from Japan and Norway **All Members**
 - d. **ACTION-PT-7-4**: With industry, develop use-cases and test-scenarios around the use of navigation data **All Members**
 - e. **ACTION-PT-7-5**: Continue to engage with IALA MASS Task Force **Chair & Member States**
 - f. ACTION-PT-7-6: Engage academia in research and data trials Chair & Member States
 - g. ACTION-PT-7-7: Make sample S-100 data sets available to MASS for trials CHS;NOAA;KHOA
 - h. **ACTION-PT-7-8**: Engage with IMO specifically on the MASS Code **Mark Casey**
 - i. **ACTION-PT-7-9**: Begin planning and engagement of MASS sea trials using S-100 sometime in 2025 **KHOA**
 - ACTION-PT-7-10: Begin planning to repeat Discovery and Analysis process for new MASS requirements sometime in 2025 - All Members
 - k. ACTION-PT-7-11: Set date and venue for next meeting post IHO Council Completed
 - I. **ACTION-PT-7-12**: Republic of Korea is proposing to hold the 1st meeting in person (with a potential virtual option) potentially in April 2025 **Vice-Chair; KHOA**
- 5. Review of Input Papers / Proposals and future Work Items from members.
 - a. **PT-8-Input-1**: Proposal on the Development of "Standards for Unmanned Survey Vessels" China MSA
 - b. *ENC for autonomous navigation ENG* A.Sabaidash, GEOPHONE GROUP INTERNATIONAL Oy
 - c. IHO S-100 Phase-2 Product Specs to support Route Planning



- 6. Any other Business
- 7. Date and format of Next Meeting